

# **Palift** - DIVISION

# RAGNO XTJ 32 / C OPERATION AND MAINTENANCE MANUAL

RAGNO XTJ 32/C SERIAL NR. YEAR CE CERTIFICATION MANUAL N° CRAWLER VERSION PT 2712 2010 D 04 AA4121401 NM 119 A 09



#### TO THE OWNER

The platform you have bought has been designed and manufactured with a goal in mind: the quality

This machine complies with the safety standards in force; yet, this does not means that there is no risk of danger. Therefore, it is vital that you observe the safety regulations and follow some elementary precautions.

First of all, we strongly insist that you read this manual and observe all safety standards, as well use and maintenance instructions, in order to avoid work-related dangers

This manual is intended as a guide for platform use. Proper machine use and maintenance will ensure long-lasting product and satisfaction.

Before to entrust the platform to its operator, be sure that:

- 1. he has received proper safety and use training at our facility, or, alternatively, by a specialized and experienced person
- 2. he has read and understood the instructions of this manual

# In any case, the machine can be used only by a trained, 18 years old, operator authorized by employer

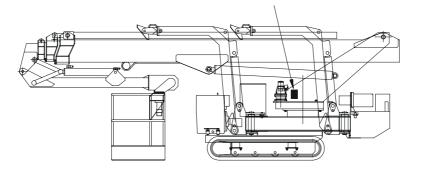
Always keep a copy of this manual on the platform - keep it complete and in good condition

Palazzani Industrie S.p.A. is at your disposal for any additional information and do not hesitate to get in touch should you require technical assistance or original spare parts, the only ones granting compatibility and quality

#### IDENTIFICATION OF THE PLATFORM

#### identification plate

When you ask for information, spare parts, or technical intervention, please always specify to Palazzani Industrie S.p.A. Model and Serial Number evidenced on the identification plate







THIS SYMBOL MEANS "SAFETY WARNING" AND HIGHLIGHTS IMPORTANT SAFETY INFORMATION

WHEN YOU SEE THIS SYMBOL, CAREFULLY READ THE MESSAGE THAT FOLLOWS AND PAY YOUR BEST ATTENTION SINCE THERE IS A DANGER OF SERIOUS PHYSICAL INJURY

THE IMPROPER USE OF THE PLATFORM, OR THE INOBSERVANCE OF THE SAFETY DIRECTIONS, COULD LEAD TO SERIOUS, EVEN FATAL, INJURY

BEFORE USING THE PLATFORM:

- 1. READ THIS MANUAL CAREFULLY
- 2. BE SURE THAT THE PLATFORM IS IN PERFECT ORDER, PARTICULARLY FOR SAFETY DEVICES
- 3. INQUIRE ABOUT SAFETY REGULATIONS REGARDING THE ACTIVITY SECTOR AND IN FORCE ON THE SITE

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RICAMBI(vedi Catalogo parti di ricambio)SCHEMA IDRAULICO(vedi Catalogo parti di ricambio)SCHEMA ELETTRICO(vedi Catalogo parti di ricambio)USO - MANUTENZIONE – RICAMBI MOTORE DIESEL(vedi apposito libro del<br/>Costruttore)



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#### **CHAP. 1 GENERAL CHARACTERISTICS**

#### **1.1 INTRODUCTION**

"Ragno" are aerial access platforms having the best facilities for internal positioning and working and for external applications, where entrance, slope or path are an impossible obstacle for more conventional machines.

One of the "Ragno" peculiarities is the stabilizing-legs' possibility to be rotated and articulated independently, which gives unprecedented versatility when setting up in confined spaces and on inclines.

"Ragno" have standard dual power: no-noise thermic power pack for robust external working and electric motor(s) for quiet and fume-free indoor operations. This platform is available in rubber-tracked crawler version particularly fit for irregular grounds, being capable of climbing steps or steep slopes.

The platform is not electrically isolated but it is being projected to operate outside.

#### **1.2 DESCRIPTION**

"Ragno" unit mainly consists of a frame with 4 articulated stabilizing legs, and supporting the turntable, slewing on a ball bearing ring.

Steel made multi-telescopic boom is hinged to the turntable and it supports the aerial cage, with an hydraulically articulating jib. All movements are actuated by hydraulic cylinders, or hydraulic motors

Unit is mounted on rubber tracks, completely integrated with the supporting frame.

Two power packs are mounted on the Ragno : el.motor 220V and no-noise diesel engine, all driving the platform movements alternatively and both source are able to the boom mouvements and travelling.

The machine has two control panel, one on the round, and one in the cage and are interlocked; it's possible to use only one.

The ground control panel allows the travelling and stabilizer positioning, and the boom mouvements generally used for the emergency operations.



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## 1.3 DIMENSIONS AND PERFORMANCES XTJ 32/C

Transfer position machine	
Min. height.	1985 mm
Length	6900 mm
Width (without cage)	1400 mm
Total weight	5940 kg
Max pressure on the ground of track	$0.85 \text{ kg/cm}^2$
Max. working height	32 m
Max. cage floor height	30 m
Max. outreach	15 m 16.5 m
Safe working load	200 kg 120 kg
Max. horizontal pull	400 N
Aerial cage dimensions (A x B)	1.95 x 0.7 x h 1.1 m
Tracks lenght	1990 m
Min.steering radius	4520 mm.
Max. selfpropelling speed	4.5 km/h
Max. superable slope	40 %
Max. lateral slope (with tracks)	15 %
Turntable slewing	360° (not continuous)
Cage rotation	$90^{\circ} + 90^{\circ}$
Hydr. system working pressure with diesel engine	240 bar
Hydr. system working pressure with el. motor	180 bar
Clearance	190 mm
Max. admitted wind speed	45 km/h
Max. admitted platform slope	2°

Technical data: - hydr. pressure and work speed with:

	Pressione	220 V	DIESEL
Stabilizing legs lowering	40 bar	75 sec.	20 sec.
Stabilizing legs raising	50 bar	30 sec.	15 sec.
Boom hoisting (completamente rientrati)	55 bar	90 sec.	70 sec.
Boom lowering (completamente rientrati)	140 bar	90 sec.	56 sec.
Boom hoisting (sfilati)	55 bar	160 sec.	160 sec.
Boom lowering (sfilati)	140 bar	123 sec.	123 sec.
Telescopic boom extension	100 bar	180 sec.	63 sec.
Telescopic boom re-entry	120 bar	87 sec.	46 sec.
Salita jib	150 bar	100 sec.	65 sec.
Discesa jib	170 bar	75 sec.	50 sec.
Jib opening	210 bar	10 sec.	10 sec.
Jib closing	210 bar	18 sec	18 sec.
Complete slewing (1 turn)	55 bar	160 sec.	160 sec.
Selfpropelling speed:			
10 m slow speed	50 bar	105 sec.	28 sec.
10 m fast speed	50 bar	60 sec.	8 sec.



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Time and pressare are intended with empty cage, worm oil and max joystick activation.

A 10% tolerance on this value is acceptable

Time and dimensions are indicative and Palazzani SpA may change the value for internal causes.

#### Main mechanic components:

Tracks:	MESSERSI' TIPO RTU 28F
Differential ratio:	1:41.9
Brakes:	automatic, with hydraulic releasing
Diesel engine:	HATZ 2L 41C
Cage levelling gears:	DINAMIC OIL RE242T2S-16,28-MD20
Turntable motoreducer:	DINAMIC OIL 111-NS-MD40

#### Main hydraulic components:

Diesel engine pump 220V el.motor pump Hand pump El. generator motor Turntable slewing motor Cage levelling motor Cage rotation motor Proportional electrodistributor Overcenter valve on cylinders Hoses Filter Oil: hydraulic system reducer gears groups	PLP 20.14/20.14D PLP 20.4D EP.25.W.B.TXA PLM 20.6.3S MLG 400 MLG 300 ATTUATORE MOVECO 180° PVG32 OIL CONTROL SAE 100 R2A 25 micron BP ENERGOL HLP HM 46 IP PONTIAX FZG85W/90
Grease	IP AUTO GREASE MP
Fuel	GASOIL
1 401	OT IOUTE

**ATTENTION!** for filling-up, it is recommended to use the above specified oil types exclusively - in case of oils with corresponding characteristics, it is advisable to make a complete change.



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#### Main electric components:

Electrical motor	3 kW 220 V a.c.
Generator	(optional) 5 kW 220 V a.c.
Batteries	n° 2 100 Ah
Battery charger	220 V ac - 24 V dc - 6 A
Radio control	Autec

Engine	diesel
Туре	Hatz 2L41C
Fuel	diesel
Rpm	3000 r/min.
Transmission	folle
Noise lowering solutions	original cover made
	by phonoabsorbing panel
Net power	14 kW a 3000 giri/min.

Phonometric tests (Directive CE 2002/44)

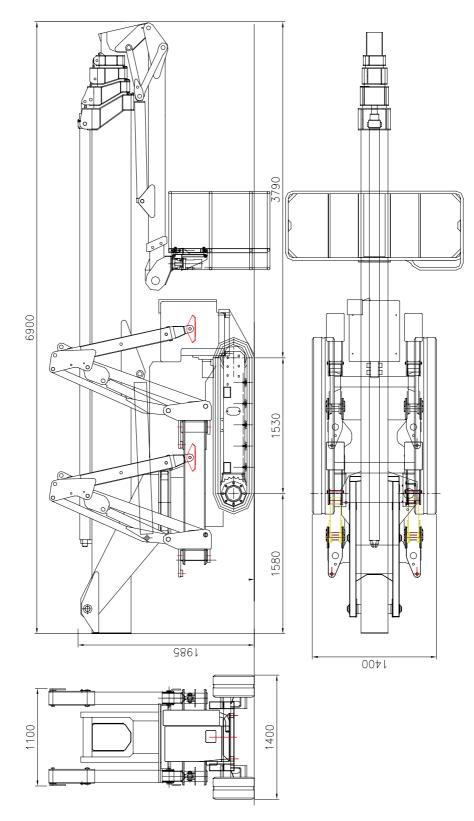
Acoustic pressure level (cage)	dB(A) 70.1
Acoustic pressure level (at ground during travelling)	dB(A) 78.9
Acoustic pressure level	dB(A) 96.5
Vibrations (Directive CE 2002/44)	$< 2.5 m/sac2 of \Lambda(2)$
Operator hand/arm	< 2,5  m/sec2 of A(8)
Operator body	< 1,25  m/sec2 of A(8)

Gas emissions (exhaust gas)

The engine power is less than 19 kW, therefore not subject to Directive CE97/68, however the Manufacturer complais from now with the above mentioned Directive, granting 3A forcasted on 2011.



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Max ground pressure of the track 0.85 kg/cm<sup>2</sup> Fig. 1.1 Main dimensions

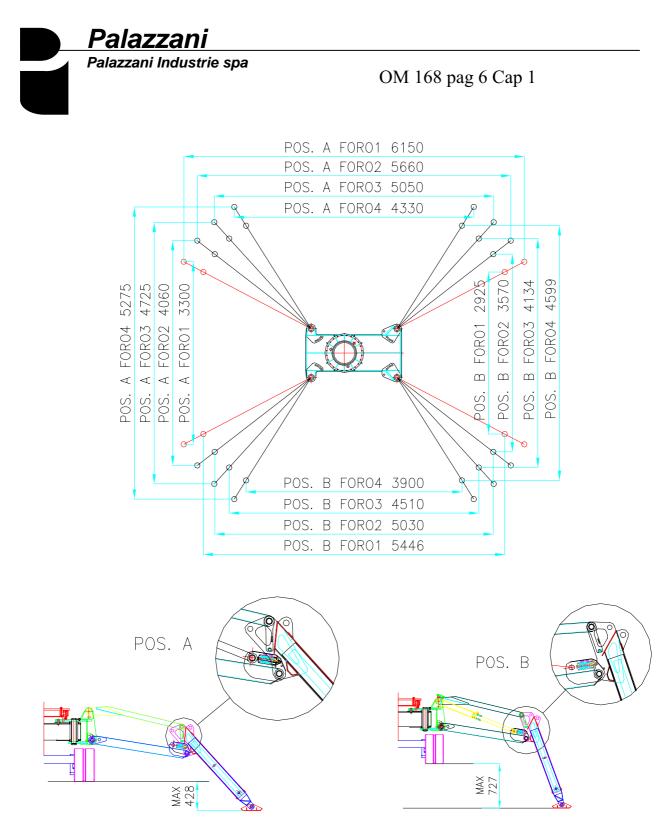


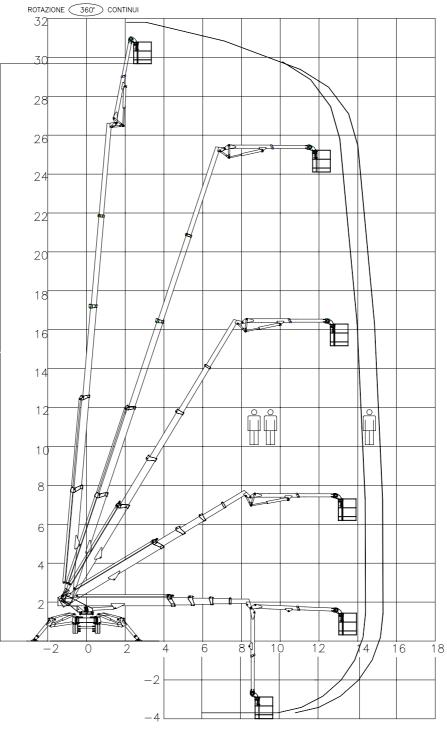
Fig. 1.2 – Stabilizer positions

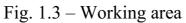
Max loading on a stabiliser KN 35



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#### 1.4. WORKING AREA





**Note!** This diagram show the max working area obtainable with the boom toward the diesel engine and the stabilizer at the hole n°1 and the position A of Fig. 1.2. In all the other configuration of the machine the working area my be reduced.



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#### 1.5 TRANSPORT

"Ragno" platform is authorized to road running only under particular conditions (see par.) and, therefore, it must be transported by lorry.

"Ragno" loading\unloading is possible in different ways: by using their stabilizinglegs, according to the directions of this manual (see chap. 3.1), hoisted by a crane, for loading\unloading or for work positioning. For this purpose, hooking eyebolts are placed on the top of stabilizing-legs.

According to lorry's characteristics, "Ragno" can be positioned on the bed with the boom over the driver's cab or towards the rear side.

It is possible to arrange a lorry for use of the "Ragno" as a normal truck-mounted platform: 4 eyebolts can be welded on the lorry bed and fastened to the "Ragno" supports by means of 20M turnbuckles.

In case of a normal lorry, it is better to fix front and rear wheels or tracks, to fix the boom with a textile chord around it and fixed on the winch sides of the lorry bed.

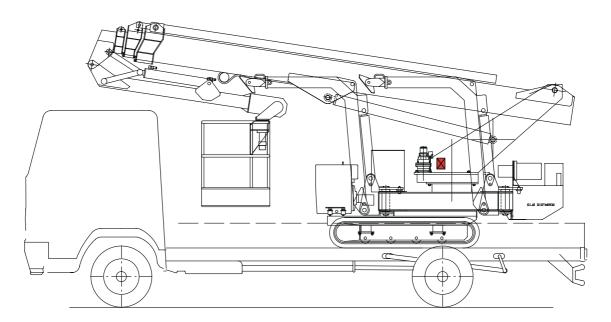


Fig. 1.4 Exemple of transport by lorry



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#### 1.6 MAIN GROUPS OF THE PLATFORM

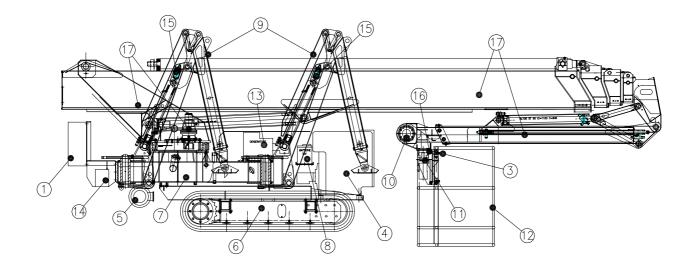


Fig. 1.5 Ragno with tracks

- 1) General control desk
- 2) Ground control panel
- 3) Cage control panel
- 4) Diesel engine
- 5) Electric motor
- 6) Track
- 7) Chassis frame
- 8) Batteries
- 9) Stabilizer

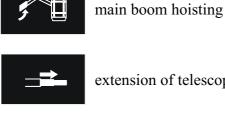
- 10) Cage levelling system
- 11) Cage rotation motor
- 12) Cage
- 13) Generator
- 14) Radio receiver (opzionale)
- 15) Load management system
- 16) Cage load limiting device
- 17) Turntable rotation device
- 18) Main telescopic boom and jib



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## **1.7 PICTOGRAMS LEGEND**

For a better understanding, we give you a brief description of the pictograms placed on the platform



extension of telescopic boom



turntable rotation (right)



Jib opening



telescopic booms re-entry

main boom lowering



turntable rotation (left)



jib closing



cage rotation (left)



cage rotation (right)



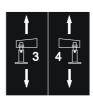
upward cage levelling



downward cage levelling



outriggers (legs) nr. 1/2 lowering and re-entering)



outriggers (legs) nr. 3/4 lowering and re-entering)



Red light signalling max. allowed outreach position

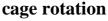


green light signalling the control panel activation



key switch selection control fonctions or panel outriggersboom-traslation





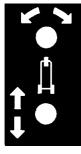


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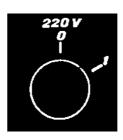
Fixing points for transport

steering



right left

forwards selfpropelling backwards



General electricity switch



hydraulic oil reservoir



fuel reservoir

selfpropelling

engine stop control

speed

slow



selfpropelling fast speed



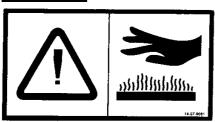
engine start control



hooking point for hoisting



jib extension



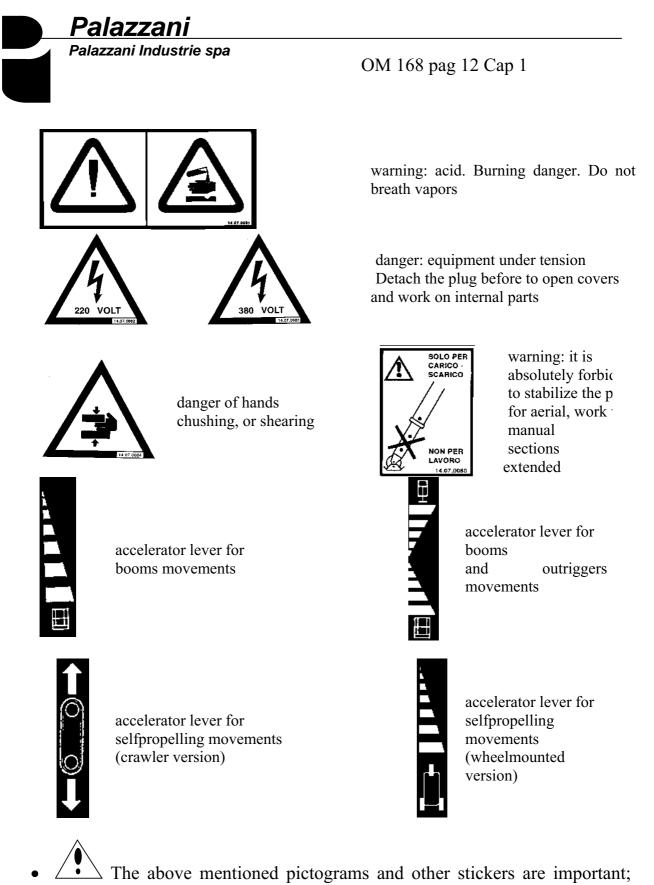


horn



jib re-entry

warning: diesel Engine and exhaust pipe scorch. Danger of burnes. Don't touch.



- even just a not-readable or missing one can cause serious consequences
  Every day be sure that all stickers are readable, clean them regularly and
- Every day be sure that all stickers are readable, clean them regularly and substitute them with new ones if necessary
- If an element of the machine which requires a sticker is substituted, put the new one after the substitution.



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# **CHAP. 2 SAFETY DIRECTIONS**

## 2.1 SCOPE

In accordance with European Standard "Machine Directive", this operational and maintenance manual :

- gives the operators all necessary information for a correct use of the platform
- points out hazards arising from an use not expressely foreseen by the manufacturer and, also, hazards existing even with a correct use of the platform.
- gives information about the safety devices mounted on the platform and directions for their check-up
- allows fast location of an eventual fault and gives directions for prompt intervention
- gives directions for recovery in emergency
- gives a calendar of routine maintenance interventions
- gives a list of reccomanded spare parts
- gives a list of the workshops authorized for interventions on the platform
- gives a check up schedule in the manufacturer or authorised sites

This manual must be read by the operators before using the platform and it must accompany the platform in case of a change of property

The safety instructions contained in this chapter refer to the most frequent risks only and are not to be considered exhaustive. The machine **can not** operate in particular situations sites: i.e. inflammable vapors, not unbreakable or toxic materials, free flames or pressure water, scarce light or high noise, etc.

It is recommendable to train operators with a short course by the Manufacturer so that than they can train the following new operators.

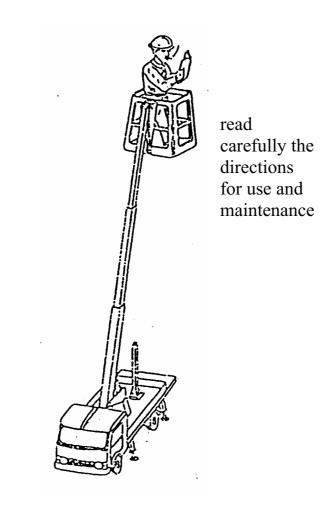
If the machine pass to another owner, this manual must be supplied to the new owner because it is part of the machine.



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## 2.2 SPECIAL DIRECTIONS

Although it is specifically designed for personnel hoisting and aerial work, platform can be used exclusively by trained operators, working in conformity with general safety standards and following specific instructions of this manual





During sloping transfer, keep the cage towards the slope by keeping away from scarps, landslide zones, deep holes and study the way considering the necessary steering radius. Use the transfer controls, away from the base machine, by using the belt. In cold temperatures, start the engine and let the oil warming for 5 min before the first manoeuvres which need slow speed.



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platform must be stabilised on compact ground - it is always recommended to place wooden boards under stabilising-legs, to increase the contact area and to reduce the specific pressure on the ground

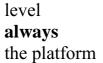
DANGER

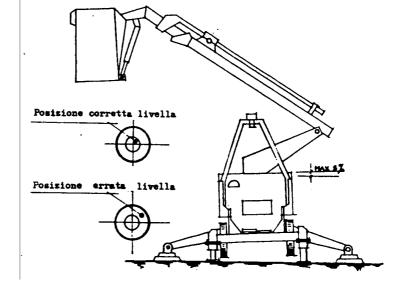
never go in or out the cage when it is in aerial position



Fig. 2.2

before completing the stabilising manoeuvre, check that the platform is perfectly levelled - 2° max. slope is admitted, as per fig. 2.3 (bubble must be positioned inside the external ring



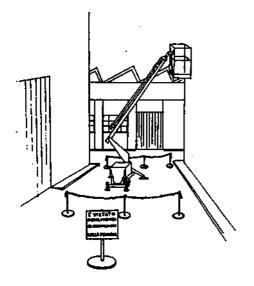




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 $\checkmark$  before approaching floors, verify if platform weight and legs pressure can be supported

working area must be signalled and delimited - unauthorised persons are not admitted on the platform working area



DANGER

projection on the ground of aerial working area must be signalled and delimited

Fig. 2.4

Before using the platform, verify the correct functioning of the safety decives.

Inform the technical responsible in case of noise, vibrations or anomalous machine behaviours.

never use the platform as an elevator



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aerial movements must be controlled by the operator on the cage exclusively control from the ground is admitted in emergency case, only. A trained person on ground, has to follow, in any case, the operation on the cage.

when working near overhead electric lines, it is necessary to operate with a particular caution, to avoid any accidental contact of the boom or of the cage.

#### <u>Here below the table of safety distances from electric as per D.Lgs</u> <u>81/2008</u>

Nominal tension	Minimal allowed
<u>Un</u>	<u>distance</u>
kV	m
≤ 1	3
10	3,5
15	3,5
132	5
220	7
380	7

This platfmor <u>is not</u> electrically isolated

## DANGER

avoid contacts with electric lines

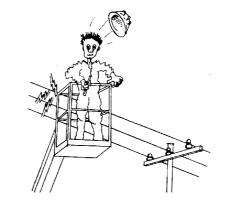


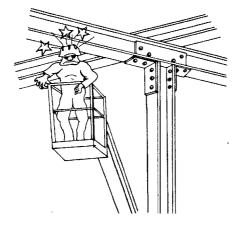
Fig. 2.5

Use the proportionality in the controls and doo not fulfill sudden manoeuvres or inversions.



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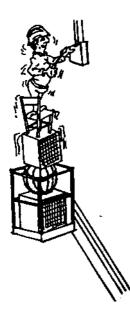
before operating aerial movements, verify eventual overhanging obstacles: balconies, branches, electric or telephonic lines, beams, etc.



DANGER use protecting helmet and safety belt



operators in aerial cage must always work with their feet on the cage floor use of footboards is not admitted no climbing on the railing and no leaning out It's also forbidden to lean out over the edge of the platform, but, , if necessary, do it only hooked to the safety belt and however staying with the feet on the floor



DA
NG
ER

footboards on the cage floor are not admitted

Fig. 2.7



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 $\checkmark$  no throwing materials or tools from the cage to the ground and vice versa - use of a wire is recommended

tools used by operators in the cage must be laid on the cage floor, or stowed in special pockets

DANGER

no horizontal pulling or pushing action

no tools throwing

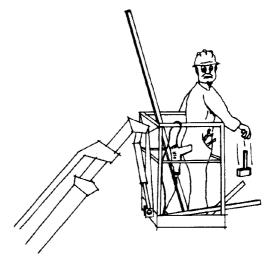


Fig. 2.8

4 don't place flags or large stripes on the aerial cage, increasing the surface exposed to the wind

#### DANGER

don't use the platform in case of wind speed over 12.5m/s (45 km.p.h.) In the following schedule it is indicated the "Beaufort scale" that gives indications about evaluation of the wind speed

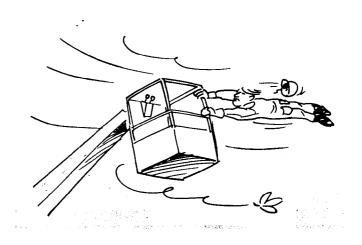


Fig. 2.9



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# Beaufort scale

Number of Beaufort	Wind speed (km/h)	Description	Earth conditions
0	0	Calm	Smoke vertically climbs
1	1-6	Drivel of wind	Wind movement visible from the smoke.
2	7-11	Light breeze	You feels the wind on the naked skin. The leaves rustle.
3	12-19	Tense breeze	Leaves and smaller branches in constant movement.
4	20-29	Moderate wind	Lifting of dust and paper. The branches have shaken.
5	30-39	Tense wind	The bushes oscillate with leaves. They forms small waves in the inland waters.
6	40-50	Fresch wind	Movement of big branches. Difficulty to use the umbrella.
7	51-62	Strong wind	Whole shaken trees. Difficulty to walk against wind.
8	63-75	Storm	Twigs torn by the trees. Generally it is impossible to walk against wind.
9	76-87	Strong storm	Light damages to the structures (fireplaces and tiles removed).
10	88-102	Storm	(Rare in dry land) Eradication of trees. Considerable structural damages.
11	103-117	Violent storm	Vast structural damages.
12	>117	Hurricane	Huge and wide damages to the structures.



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Avoid any contact against fixed, or mobile structures

never exceed the max admitted safe working load avoid to load material during work condition

DANGER use of the platform as a crane is forbidden



Fig. 2.10

Keep cleaned the cage of the platform by oily and slippery substances and from residual of preceding workmanships (bricks, jars, utensils).

Don't modify the electrohydraulic plant or the regulations to get higher performances to those suitable from the builder

Don't make maintenances with people on board and platform in movement.



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# CAP. 3° NORMAL USE CONDITIONS

# 3.1 LOAD AND UNLOAD ON TRUCK.

#### a) By crane

- take the tensors or the equipment fixing stripes off.
- hook the 4 eyebolts on the top of the stabilizing legs with proper loading ropes (min half weight each) (Fig. 3.1)
- lift the machine and go out with truck

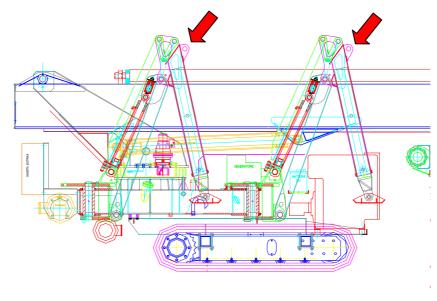


Fig. 3.1

b) Self-loading (if possible). See also the Chap. 3.24

- stop the lorry on level and rough ground
- rotate the stabilizing legs in the hole 2 (see Fig. 1.2)
- start the diesel engine.
- turn the selecting key of the ground control panel on the "stabiling-legs" symbol (part 6 of Fig. 3.2)
- extend the telescopic section of the stabilizar, lock it by means of the pins and lower the stabilizer on the ground.
- before lay the plates on the ground, put the proper rolling chariots (see Fig. 3.34).
- disengage the machine from the lorry and lowering the stabilizing-legs, hoist the platform from the lorry
- slowly, drive the lorry out of the platform
- lift the stabilisers as described in paragraph 3.12 with the belt control



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distant from the machine

 when the tracks are lowered on the ground, retract the telescope sections of the stabilizr.

**NB**: If the ground is solid and resistant (pressed earth, cement, asphalt) the operation is easy; on the contrary if the ground is yelding and irregular it is better to drive the charriots on wooden plates.

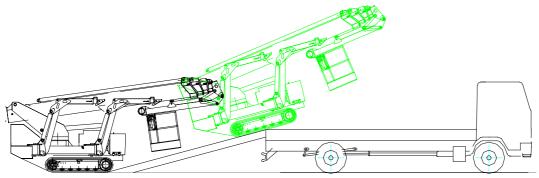
- for the loading, lift the stabilisers from the boom side before and than balancing them with the other two, and follow the procedure on the contrary.

- select now the controls key on "turntable" and transfer to the site with the stabilisers up (min 10/15 cm) for a better stability in case of strong asperities.

c) By using a ramp.

**ATTENTION!!** If you are using a ramp we recommend a max slope of 15° (about 25%) and to attack the ramp with the cage toward the climb. This is absolutly necessari for the stability of the machine.

To attack the ramp, lift up the cage just the necessary to avoid the ramp and not more, like showed in the following picture. (To lift up the cage, thus the main boom, see chap. 3.9)



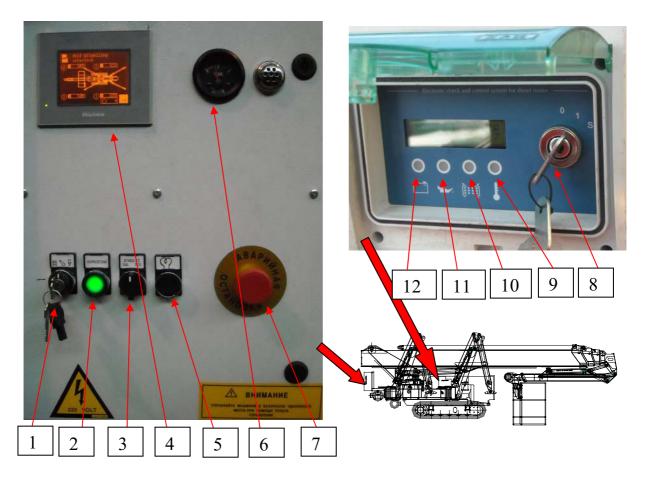
Warning! During the transport on the lorry, bee sure that the locking rotation pin is insert.





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# 3.2 MAIN CONTROL DESK





- 1) Switching controls key.
- 3) Lift up/lower stabilizer
- 5) Heating diesel engine glow plug
- 7) Emergency stop button
- 9) Overheating diesel engine
- 11) Low oil pressare diesel engine
- 2) Boom lifting up in travel condition
- 4) Programmable Logic Control (PLC)
- 6) Fuel level
- 8) General key
- 10) Air filter barred
- 12) Low tension generator of the diesel engin



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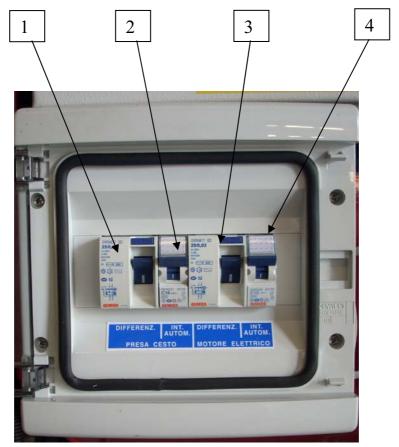


Fig. 3.3

- 1) Differential switch (cage plug)
- 2) Automatic magnetothermic switch (cage plug)
- 3) Differential switch (el. motor)
- 4) Automatic magnetothermic switch (el. motor)



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#### **BATTERY CHARGES**

The battery charges is fitted into the general electrical box.



1. Connect the machine net cable to a plug 230V -50 Hz.

2. After this operation the battery charger (in the electric box) light on automatically and the three leds light on contemporarely for few seconds (self-diagnosis)

3. Then the batteries recharging proces starts and the led shows the recharging status

4. Battery charges doesn't need any maintenance or intervention

A warning light with flashing leds is mounted to signal any eventual anomaly during the charge. Battery charger, is placed on the platform and it is

connected at its electric panel

During working with electric motor, the external electric plug feeds the motor and this device maintaining the batteries efficient.

Batteries are also re-charged by the alternator of the diesel engine.

# RISK OF BURN

When the electrolyte is freezed it can make the battery explodes if you try to charge it or to start the thermic motor with a secour battery.

To avoid to the electrolyte to freezes, maintain the battery always charged, disconnect always the negative pole (-) at firs and connect it always at last; never bridge the battery poles.

The electrolyte causes big burns, avoid the contact with skin, eyes, clothes. External: wash with water.

Internal: drink a big quantity of water or milk. Ask to a doctor.

Eyes: wash with water for 15 minutes and ask immediately to a doctor.



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#### **BATTERY CHARGES FOR RADIO-CONTROL**

The radio-control has two batteries; while using the radio-control, one of them



charging. In this way it's possible to have always a charged battery when necessary.

The battery charter is suitable inside the right cover of the machine (see the side pictures).

## 3.3 PLATFORM WORKING WITH DIESEL ENGINE

Platform is provided with 2 separate power; one of them is connected to the diesel engine installed on the same platform.

Used for the truck downloading and for long transfers to reach the working site. It can be used also for elevation working if the emissions gas are accepted (closed sites, noise prohibition, etc.)

Thanks to the diesel engine adequate power, platform movements can be driven at the best rated speed. (at least in respect to the motor at 220V)

Starting procedure:

- on main control desk (Fig. 3.2) rotate the key (item 8) on pos. 1 (oil and el. tension warning lights)
- rotate the key on position 2 to start diesel engine.
- let the engine run some minuts (almost 5 min. with a ridig temperature) before manoeuvring the platform
- due to the presence of a protecting timer, in case of engine stop, wait almost 20 sec. before re-starting
- il motore è regolato tra 2000 g/1 ed a tale regime resterà durante la fase di riposo; durante la traslazione del carro aumenterà il numero di giri automaticamente.



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- the engine is set between 1800 and 2000 rpm and remains on this level during the rest phase; during the slow travelling, but the rpm increase automatically in fast travelling.
- to stop it push the button "STOP" on one of the control panel or reset the main panel key; remember to unlock the "STOP" button rotating it slightly otherwise the engine does not start from any other control panel.
- it is possible to start engine also from control panel on cage\_by turning the key switch 2 of Fig. 3.7 if the stabilisers are on the ground and the controls selected on the above mentioned panel (key 1 in fig. 3.2 selected on cage symbol).
- it is possibile to start engine also from ground control panel, by the switch 12 of Fig. 3.6, but before it's necessary to activate it (see radio control manual).

# **WARNING**

Exhaust pipe is not protectet and burns also on the upper part of the diesel engine. During work with diesel engine in enclosed spaces, exhaust gas must be removed by means of an appropriate hose of a suitable material.

# **FIRE AND EXPLOSION RISKS**

- Fuel of the engine can cause fires and explosions
- Stop the engine before the refuelling
- No smoking during the refuelling
- All necessary protections must be activated in case of weldings, or free flames
- Clean the machine from oily materials and deposits or inflammable residual with non inflammable solvent.
- Also batteries can explode in presence of sparks or free flames: air the site and most of all do not put the battery in charge in these conditions.
- The exhaust gas can contain sparks, therefore air the working site if any vapours, gas or inflammable liquids are present.
- Eventual hydraulic oil or fuel leakage must be eliminated in phase of scheduled maintenance.

## 3.4 PLATFORM WORKING WITH ELECTRIC MOTORS

This energy source use is recommended when the machine works indoor or where the exhaust gas or noise are forbidden and when the energy saving is important.



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Where possible, it is recommended to branch always the platform to an electric source, in fact, el.motors can be used alternatively to diesel engine, for small aerial movements and, eventually, for recovery in emergency (i.e. diesel breakdown)

Starting procedure:

- on main control desk (Fig. 3.2) rotate the key (item 8) on pos. 1 (oil and el. tension warning lights)
- branch the electric plug (fig. 3.4) and socket (16A)
- verify that one of the "STOP" push-buttons is not pressed
- now, acting on one control lever, electric motor run
- it is also possible to stop electric motor, by acting on the same STOP pushbutton of the diesel engine, or by rotating key on OFF position
- electric motor re-starts, when the push-button is re-set by rotation and you act on one control lever



Fig. 3.4

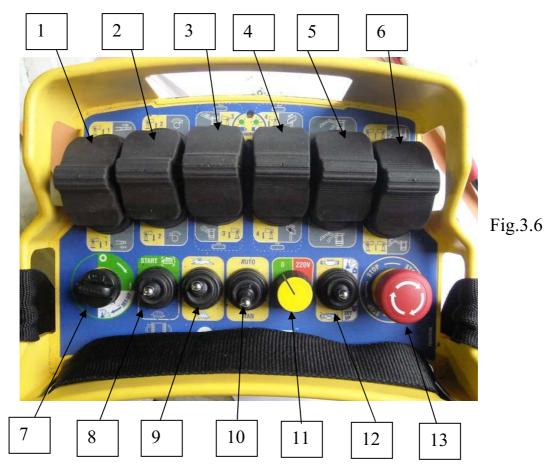
#### NOTE:

For the efficient functionning of magnetothermic differentials switch (life-savers) on the machine, the electricity plug mus be safely connected to the ground and be on a normal box; do not use flying cables sometimes existing on the working sites. During the machine displacement on the ground, keep the max attention to not crush the feeding cable with wheels or tracks and to the cable limit lenght.



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# 3.5 GROUND CONTROL PANEL



- 1. Stabilizer  $n^{\circ} 1$  telescope boom left track
- 2. Stabilizer n° 2 turntable rotation
- 3. Stabilizer n° 3 telescope jib
- 4. Stabilizer  $n^{\circ} 4$  cage rotation
- 5. Jib articulation
- 6. Stabilizer oil main boom right track
- 7. Radio-control switch on
- 8. Radio-conrol activation
- 9. Moving sped slow/fast
- 10. Automatic/manual stabilizing
- 11.Opzionale
- 12.Start/stop engine
- 13.Stop control



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## 3.6 CAGE CONTROL PANEL

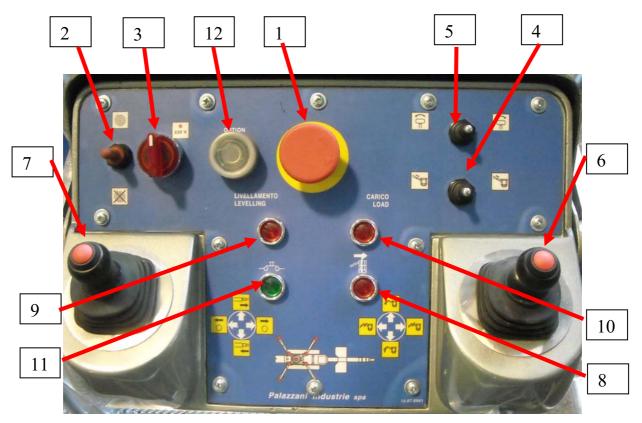


Fig. 3.7

- 1. Emergency stop button
- 2. Start/Stop engine
- 3. Activation current generator
- 4. Extend/retract jib
- 5. Cage rotation
- 6. Joystick activing main boom and jib
- 7. Joystick activing turntable roatation and telescopic boom
- 8. Led max outreach
- 9. Led cage not levelled
- 10.Led cage overload
- 11.Led control panel activate.
- 12.Cage anticollision deactivation



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## 3.7 PLATFORM STARTING PROCEDURE

Especially after a period of inactivity, before starting the engine it is recommended to check all the safety devices and controls.

Some of these controls can be fulfilled with the machine off, other controls after the stabilisers positioning. For the first ones:

- 1) verify the fuel level
- 2) verify the hydraulic oil level
- 3) verify the electrolyte level and batteries charge
- 4) verify the track condition
- 5) also check that STOP push-buttons are de-locked
- 6) check the booms extension chains integrity and tension (the chains must remain tense to the touch and not loosen during boom extension and retraction)

WARNING

Don't start the platform in case of any irregularity

#### 3.8 PLATFORM SELFPROPELLING

- start diesel engine from control panel (pos. 8 Fig. 3.2)
- select the controls selection key (pos. 1 Fig. 3.2) the turntable symbol (central position)
- detach the radio control from its support, use the shoulder belt and choose a remote, safe and panoramic control position, far from the platform

## WARNING

never drive the platform till you have reached a safe and panoramic remote control position.

- select "rabbit or snail" on the ground control panel with switch 9 in fig. 3.6
- softly act the two control levers 1 and 6 in fig. 3.6 to transfer forward or backward.

• it is possible to rotate the platform, acting on the levers in opposite sense

## WARNING

Use slow speed selection when driving on irregular grounds, slopes, restricted areas when sloping up or down, the cage side of the platform must always be in uphill position



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Stop the platform before inverting the drive sense

against overturging risks, it is recommended to drive with the stabilizing legs enlarged and lowered near the ground



Platform is not admitted to road circulation and, therefore, driving on an area opened to the traffic needs necessary protections and signals.

Many times an authority authorisation for the manufacturing site is necessary.

If not possible, follow the machine by the truck or by another vehicle with emergency lights on.

The operator must drive the machine on the sidewalk by paying attention to eventual obstacles or people present on the way.

The transfer on a public area must be short, made in favourable hours, and if necessary with the police approval.

#### 3.9 SPECIAL BOOM ACTIVATION

In case of a strong slope or loading ramps, the boom can be lifted at the necessary angle to avoid that the cage touches the ground without put stabilizers on the ground.

Act as following:

- the boom must be with extension completely retracted
- with the engine on, push the button part. 2 in fig. 3.2 and contemporarily, from the ground controls panel, lift the boom up (part.6 Fig. 3.6).
- when the operation is finished, repeat the operation on reverse to bring the boom back to horizontal position

Do not lift the cage floor more than 80 cm from the ground.

#### 3.10 STEERING

It is controlled varying the speed of the tracks, by means of the corresponding control lever.

Platform can be also be rotated, acting on the two levers 1 and 5 of Fig. 3.6 at the



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same time and in contrary sense. It is advised to make this manoeuvre at a low speed and on flat and regular ground, only

#### 3.11 AUTOMATIC BRAKE

No braking control is necessary, as the platform is provided with an automatic system consisting of mechanic negative brakes, with hydraulic release and overcentre valves, mounted on transmission hydraulic motors

Slow speed pre-selection 10 of Fig. 3.6 increases braking action and, therefore, it is recommended for driving and parking on a slope

### 3.12 LEVELLING THE MACHINE

Stabilizing legs can be individually rotated and articulated, according the owner needs.

Once detect the desire position it's indispensable to insert the pins in the appropriate holes (fig. 3.12).



Fig. 3.12

always verify that the floor capacity is adequate to the pressure of each outrigger (this value is signalled by a special label).

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Palazzani

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The stabilisers telescopic extensions can be retracted only for loading/downloading operation from the truck but they MUST be completely retracted during elevation booms working.

#### A different use can cause very dangerous injuries to operators and machine.

Now it is possible to level the machine as following:

- Turn the selecting key pos. 1 of Fig. 3.2 on "legs" symbol (right side)
- Check that the green light on the turntable will be switched on.
- You have two possibility to levelling the machine:
  - Automatic mode: switch on "Auto" the selector pos. 10 fig. 3.6. Activate

the joystick pos. 1 fig. 3.6 to give the direction of the movement, and at the same time push forward the joystick pos. 6 of the same picture, to give oil to the stabilizer. In this modality the machine levelling automatically and when the frame is in horizontal position, the system stop the stabilizer movements. **Note: check always** 



the correct level of the frame using the visual bubble on the frame.

- Manual mode: switch the pos. 10 fig. 3.6 on "Man". Activate the joystick from pos. 1 to 4 fig. 3.6 to give the direction movements for each stabilizer and at the same time push forward the joystick pos. 6 of the same pictures, to give oil to the stabilizer. In this modality it's possible to move separately every stabilizer.
- When the machine is leveled, the four light on the stabilizer (fig. 3.13) switch off. Attention! This do not ensure the correct levelling of the machine; before use the platform, check the correct levelling by means of the bubble on the frame.



Fig. 3.13

NOTE: When the machine is livelled, it's recommended (by means of the manual procedure) to give a short impulse, without movement of the frame, to the four



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stabilizer to ensure a correct pressure on the ground. In this way the performance of the machine will be at the top.

**Important!** Check the correct levelling of the machine by means of the bubbole on the frame (Fig. 3.14).

Use wooden plates to make the ground more solid (Fig. 3.15), which must be wide enought to avoid dumping and high no more than 20 cm.

It can be necessary to position the stabilisers on different height levels (i.e. on stairs, sidewalks, slopes, etc.) and this is easy because the stabilisers can lower independently (Fig. 3.16).



Fig. 3.14



Fig. 3.15



Fig. 3.16



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Remember that, in case of manual stabilization, it is easier and safer to adjust the levelling by lowering the stabilisers instead of lifting them. Always check that the plates are solidly positioned on the ground (it is

Always check that the plates are solidly positioned on the ground (it is dangerous to put them on gutters, near scarps, on soft or water grounds, etc.)

To retract the sabiliser, check that the green light on the turntable (Fig. 3.17) is lighted on. Select the key 1 in fig. 3.2 on stabilisers symbol, act the accelerator lever part 6 in fig 3.6 and the lever 1 to stabilisers lifting direction until the complete retraction. In alternative, act manually on every stabiliser in the following way: switch pos. 10 fig. 3.6 on "Man", act, preferably, two levers contemporarily (the two front or the two rear ones) and push the accelerator lever softly, until the complete retraction.



Fig. 3.17

#### NOTE:

In normal working conditions platform is to be hoisted  $10 \div 40$  cms. over flat ground

Do not excede 40 cm from the ground on flat ground.

Stabilization on steps gives no problem, it is only important to level the platform.

On a steep slope, where there is a risk of sliding, it is recommended to place some woods under the legs, in order to be within  $2^{\circ}$  (see spirit level) before levelling with legs

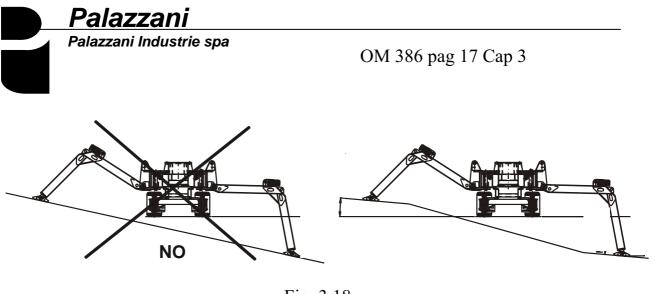


Fig. 3.18

The max slope between the two stabilisers plates laying floors indipendently from the scarp must not excede 5° to avoid chariot sliding due to the limited attrition resistance (Fig. 3.18).

#### 3.13 AERIAL WORK

#### Access to the platform

Access to the platform with retracted boom and cage near the ground. Materials also must be loaded this way.

Operators must not exit and access from the cage from high position.

Stay on the cage only for lifting and working in high position. During the transfer, operators must not stay on board.

It is possible but it is <u>very dangerous</u> to load material when the machine is placed and extended. Protections don't grant all risks from a possible overturn.

If the light and the overloading acoustic alarm activates, quickly download the exceeding load.

If the cage has to lift beyond an obstacle (river, difficult ground..) it is advisable to try before with a similar weight (i.e. 2 persons) and check if the boom reaches the wished position without stopping.

In this case it is always possible to safety lower the cage to the ground and lift again.

After positioning the stabilisers on the ground and leveling the chariot, the machine is ready for aerial work. Do the following: take the safety socket off (fig 3.19) used for transport and use the control panel in the cage.

From this position it is possible now to operatively move the boom. In fig. 3.7 all joystick manoeuvres are indicated.

It is possible to enable the aerial movement controls with the key also from a different position from the usual one (for maintenance, regulations, rentals with



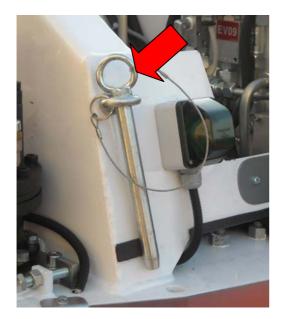
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operator, training courses, etc.).

After the cage access, before making any control, fix the safety belt (which must have a rope not more than 1 m lenght) to the proper rings (Fig. 3.20).

To control any movement, act on the corresponding lever, avoiding sudden and brusque manoeuvres.

First lift the first boom around  $45^{\circ}$  and than open the jib to get away from the boom; then you can proceed with turntable rotation and telescopic extensions.





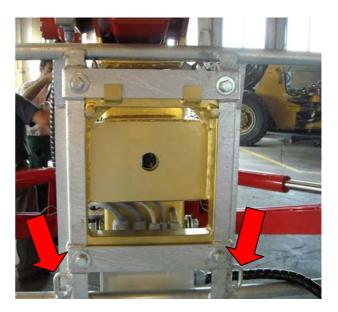


Fig. 3.20

 $\bigtriangleup$  Do not make abrupt manoeuvres or sudden inversions in movements to not counterblow the cage.

The more the telescopic are extended the lower must be the transfer.

To go back to rest position, retract the extension completely, close the jib, straighten the cage eventually rotated, put the chassis on axle rotating the turntable and lower with the first boom until the green light switch on (Fig. 3.17).

The above mentioned green light activates only when the booms are: completely retracted, on the longitudinal axle in respect to the chassis towards the diesel engine, lowered below a certain angle.

From this moment it is possible to lift the stabilisers selecting the stabilisers symbol with the key 1 Fig. 3.2 and proceeding as described in the paragraph 3.12.



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### 3.14 SAFETY DEVICES

Platform is provided with the following safety devices:

- automatic interlock between thermic and electric power sources
- automatic interlock between stabilizing legs and selfpropelling drive
- automatic interlock between stabilizing legs and boom
- load management system
- load limiting device (con preallarme)
- self-locking valves on hydraulic cylinders
- protection of the control levers
- rings for harness on aerial cage
- overpressure valves on hydraulic system
- booms extensions chains doubling
- automatic brake on turntable slewing
- automatic brake on transmission
- mobile panel for remote control
- emergengy stop push-buttons on all control stations
- el.sensors on the chains of the first boom section
- el. sensors on the pins of the legs supports
- cage levelling limiter (5°-10°)
- cage anticollision system



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### 3.15 LOAD MANAGEMENT SYSTEM

Platform is provided with an automatic moment limiting device, constantly monitoring the specific pressure of each stabilizing leg on the ground. When the pressure of one leg goes down to a minimum pre-set value, the red lamp mounted on this leg lights (fig.3.13) and, "limitator block" is displayed, at the same time, movements increasing working outreach are automatically excluded. This load/outreach limit situation is also signalled by a red light on the control panel. (Fig. 3.7 pos. 8)

Movements reducing outreach are always normally working and, therefore, operator can act on them to reduce the outreach.

Cage re-entering in safe position is signalled by leg and panel lamps switching off

Never switch off the start key of main control desk, when aerial cage is on the load/outreach limit situation, signalled by the red lamp on the control panel.

WARNING This particular load management system gives full protection, either with regards to all different legs positions and with different loads in the cage. It is tared by the manufacturer according to the platform's characteristics of stability.

Any intervention of modification and/or exclusion of this device is absolutely prohibited

No embarking persons, or materials in the cage, when it is in aerial position



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## 3.16 LOAD LIMITING DEVICE

The machine is equipped with and load limiting device in the cage. This device avoids the overcoming of mominal capacity. If this would happen it will cause the stop of all manoeuvres and the switching on of an acustic and luminous alarm on the cage (pos. 10 Fig. 3.7). To re-start all mouvements, take off the excess of load, wrongly loaded.

In case of accidental bump under a moulding or in branches, it is possible to activate the emergency operations to move tha machine like the instructions of chapter 5.

### 3.17 CAGE SELF-LEVELLING AND ROTATION

Aerial cage has two movements: rotation on horizontal position to grant the constant\_levelling with the proper ground\_and rotation right-left in respect to the vertical axle.

The first movement is automatically and consisting of an electronic pendulum acting on a proportional electro-distributor valve that opens the oil flow from main system to the hydraulic motor mounted on the boom top; the complete system is activated by acting on the boom or jib movement leveres, situated on both manoeuvre sites, and this excludes the sudden and unexpected movements of the cage.

The second movement is activated by switch on the control panel. (Fig. 3.7 pos. 5) For obtaining a complete rotation, keep the jib horizontal to avoid contacts between the cage and the boom; remember to return to the orthogonal position to the boom before lowering to rest.

The cage is equipped with an electronic device which activates with two main articulated booms lifting and lowering movements.

To maintain the cage horizontal, if there's no a defeat, act the lever during the jib manoeuvres softly; if the cage loses horizontal position more than  $5^{\circ}$  all boom movements stop so that the system has time to level the cage.



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N.B.: After 10° of inclination all movements stop and any by-pass is possible.

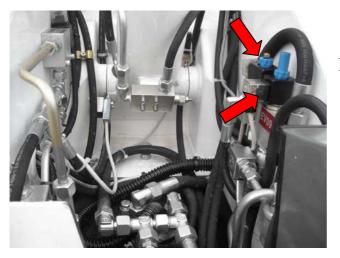


Fig. 3.24

If this happens:

- inside the turntable fig. take of the lead at the valve Fig. 3.24 marked with EV9 and and unscrew the blue cap.
- push and rotate the cursor.
- while pushing the button on the valve marked with EV10 act one manual lever of boom or jib lifting/lowering from one of the activated control panels until the cage returns vertical

In this way all service controls re-activate.

It is compulsory necessary to unlock the valve, put the cover, lead and write the cause for having taking off the lead on the manual **<u>before</u>** going back to work with the service controls.



#### 3.18 ELECTRONIC INCLINOMETER

Acoustic	Alarm
code	description
12 rings	Electro-mechanical bubbles in short circuit
11 rings	Permanent damage – repairable only by ISB S.r.l.
10 rings	Machine parameters not correct - send correct parameters
9 rings	Temperature over the allowed values
8 rings	Feeding tension over the allowed values
7 rings	Clockwise movement valve spool in court circuit or disconnected
2 rings	Platform inclination out of permitted limit

Note 1

The system generates a permanent alarm when an irreversible error can occur and the safety of the machine users could no more be assured. When this alarm activates, the machine is maintained in functioning condition only to allow the user on the cage to reach the ground. In these conditions, the light alarm displays 11 blinking, while 25 sec of acoustic alarm activates every 60 sec.

Note 2

The weight pre-alarm is indicated by a continuous acoustic alarm, interrupted by intervals of about 1 sec. This is for better hear the alarm

Fatal error

If the ecu system makes a permanent acoustic alarm (the light is permanent switched on), the system is no more working. The level and weight regulation will be permanently deactivated.



Fig. 3.26



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In the electronic card of Fig. 3.26 there's a green led (1) indicating the blinking (the same blinkings as the ringings), there are also some trimmer for the manual regulation of some parameters in case the programme device wouldn't be available.

See these trimmers and their function on Fig. 3.27

## TRIMMER USE

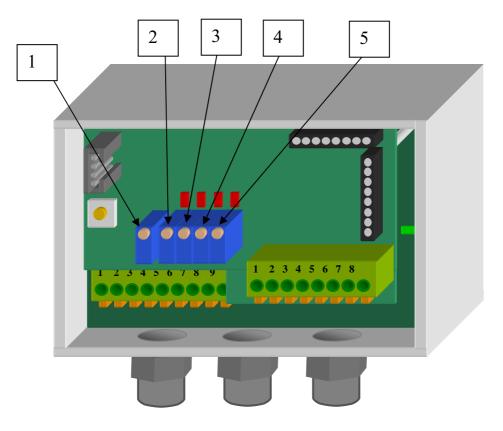


Fig. 3.27

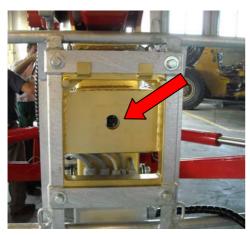
- 1 cage horizontality
- 2 clockwise current rotation
- 3 under clockwise current rotation
- 4 clockwise speed
- 5 under clockwise speed



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## 3.19 CAGE LOAD LIMITING

On the machine is fitted a sensor to evoid an overload of the cage (Fig.3.28).



If the weight in the cage is over the maximum admissible, all the movements of the machine are stepped and there i san acoustic and optical warning on the cage control panel. Before stop all the movements, there is a countinuous acoustic worning setted at the 80% of the maximum admissible load.

When the maximum load is reached there is an alternate acoustic worning.

Fig. 3.28



In the pictures 3.29 there is a short diagnostic of the load sensor.

- Error LED. Red color. If on, there is an anomaly in the sensor.
- Alarm LED. Red color. If on, there i san overload in the cage.
- Zero/Tara LED. Orange color. If on, the sensor works correctly and the measure is inside a tollerance +15kg -15kg.
- Power LED. Green color. If blinking, there is electrical power to the sensor.





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## 3.20 ELECTRIC CURRENT GENERATOR (OPTIONAL)

Platform is provided with an electric generator, hydraulically actuated by diesel engine exclusively, deliverying 1 kW-220V single phase el.curent to the aerial cage.

Electric generator is put in action from aerial cage panel (Fig. 3.7 pos. 3), when diesel engine runs, platform is stabilized and selecting key rotated on "cage" position.

Nevertheless, for economy reasons, it is advisable to actuate the el. generator only when it is strictly necessary.

Weekly check of the differential magnetothermic relay is recommended (life saver Fig. 3.3); drive the generator, push the test button and verify that el.current does not arrive at the plug on the cage.

In case of an electricity lost and differential intervention, make the electric system controlled by a skilled person.

Use exclusively tools and projectors in conformity with electric standards and in good conditions. (In alternative use the proper individual protection devices)



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3.21 INTERCOM (OPTIONAL)

It is possible to comunicate to the persons on the cage with the intercom.

SKYTALK is the industrial intercom water resistant for external use.



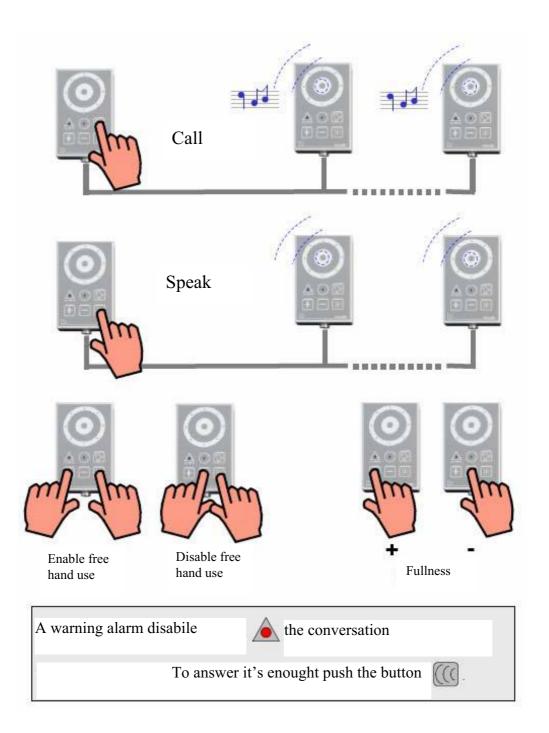
## INTERCOM FOR AEREAL WORK PLATFORMS

USE MANUAL





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## 3.22 CHECK-UP (FROM GROUND PANELS)

Especially after a period of inactivity, platform needs a check-up before working :

Check up list:

- when you turn the starting key of diesel engine, legs' flashing lights must be on (Fig. 3.13)
- these lights must be off when legs are lowered in pressure on the ground
- the green light on the turntable is on (Fig. 3.17)
- lift the boom until this green light on the turntable is switched off, descent until it switch on again, rotate the turntable slightly until the green light switches off.
- Hoist the boom till the green lamp of rest position is off and try to raise the legs (it must be impossible !!) If the stabilisers move do not use the machine and bring it to an authorised workshop or to the manufacturer)
- open the jib slightly and extend the boom until it stops when the red light on the manoeuvre panel and on one of the two stabilisers from the opposite boom position side (Fig. 3.13) switches on
- try now to lift the boom slightly and than lower it (if the red light is still on this manouvre must be possible)
- check that the red light on the manoeuvre panel remains on together with the green light near it
- check the correct working of : emergency stop push-buttons



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## 3.23 CHECK-UP (FROM CAGE PANEL)

Verify the correct working of all controls and warning lights of cage control panel and, also that aerial cage is correctly screwed on its support:

- test all above mentioned movements
- extend the telescopic until the red light switches on (fig. 3.7 pos. 8)
- start generator and also verify the light on the selector
- check the impossibility to make the rotation, boom descent and telescopic extentions manoeuvres, when the red light is ona (Fig. 3.7 pos. 8)
- verify the cage rotation
- verify the emergency STOP. Make a manoeuvre and push the stop button. On the contrary do not use the machine and contact an authorised workshop
- verify the start device
- Connect external line on one of electric plugs of the platform and verify that el. motor runs when STOP push button is released, also check that el.motor stop, when diesel engine start
- Check that the booms extension chains and their relative electric micro contacts on the first boom are integral
- Check if the load limiting device is functioning by loading (with the boom in horizontal position and the cage close to the ground) kg 240 or more and verifying the blinking red light, the acoustic alarm and the stopping of all movements of the booms.



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## **3.24 SPECIAL DIRECTIONS**

#### Transport

The machine has a modest transfer speed, therefore the transfering on working site must be done on truck.

The machine can be loaded with the boom above the cabin if the truck is not equipped with a crane, pallet holder or protection nets, or with the boom toward the back.

In this case put the indication of leaning loads from on the boom extremity.

Transport shoud be on a truck equipped for this purpose, because the platform is equipped with connections corresponding to the truck ones and this keep the fixing time shorter and the transport safer (Fig. 3.32)

Put tensers to these connections and fix them to the truck.



Fig. 3.32

#### Starting in rigid climate conditions

In favourable climate conditions act with a special procedure, most of all in first engine starting.

- start diesel engine and let it run almost 5'; in case of engine stop, wait almost 30 sec. before re-starting, due to the presence of a protecting timer
- after this time, accelerate at max selecting on "rabbit" and transfering for 1 minute

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- control first movements at a slow speed and let engine run, in order to have hydraulic oil at a right temperature
- leave the engine turning for the first 15 min even if the aerial work does not requires it
- till hydraulic oil has not reached a right temperature, irregular speed movements are possible

#### Driving on a slope

In case of slope grounds, first select the slow speed "snail" and observe the following:

- keep the booms extremities towards the slope
- when driving on a slope, it is recommended to pre-select slow speed and cage side of the platform must be always up-hill positioned
- when driving on irregular ground it is recommended to lower stabilizing legs near the ground (30 cms. approx.)
- it is also recommended to take the boom as low as possible
- platform must be driven from a safe side position (not before or behind)

#### Lights

For night working or in few lighted sites, use the electric socket on the cage to light a lamp max 60W a 220v c.a.

#### Lifted by crane

For loading the platform on a truck, it is possible to use a crane. In this case:

- be sure that the stabilisers are completely retracted
- use the fixing rings on he stabilisers to attach the machine to the crane with four independent ropes

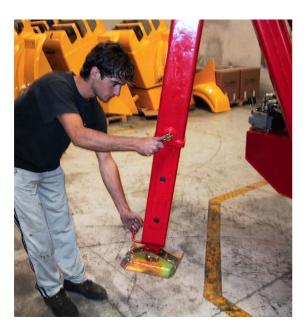
Use lifting equipment, i.e. ropes, with proper sections for lifting and check that the crane loading is proper with the total platform weight indicated in the turntable.



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#### Self-loading on truck (if possible)

The machine complete of original carriage can be loaded by itself on the truck with the following procedure:





- place the machine on a flat ground (if it's possible) and in any case in a not very difficult ground considering also the space for the truck
- put the outriggers supports in the position of central hole or in a sufficient position for the following truck passage.
- if the truck is very high, extract the manual extensions of the outriggers to second or third hole and put again the blocking pins (Fig. 3.33)

 $\checkmark$  These manual extensions of the outriggers must be used only for the loading on truck.

It is forbidden to move the boom while working with these extensions. <u>They</u> <u>mustn't</u> be used to enlarge the placement base nor to increase the working height of machines.



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- put the carriage with proper rolls under the plates (Fig. 3.34)
- lift completely the machine, moving alternatively the two front and rear stabilisers. Always lift the two front stabilisers first, and then to balance with the rear ones until the cylinders course is finished. (Fig. 3.35)



Fig. 3.34



Fig. 3.35

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During loading/unloading phase from the truck, you **must** mount the proper roll carriages on the extensions if they are extended. On the contrary you **must not** mount the roll carriages during normal placements for lifting working.

- move the truck as to place the load area under the machine
- retract the outriggers as to place the chassis on the supports and on the area itself
- fix the machine
- recover the carriages



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## **3.25 DIAGNOSTIC**

On the machine is fitted a touch screen interactive display located on the main electrical box (Fig. 3.36), and it's function is to monitoring the work cycle of the machine.

Additional the monitor has a diagnostic function.

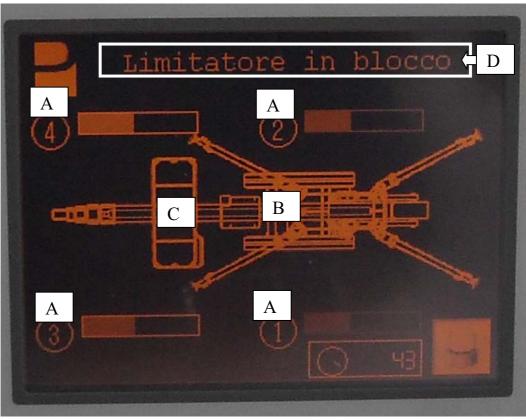


Fig. 3.36

Touching the area A it's possible to read the instantaneous value of the pressure on the pertinent stabilizer. The number is not indicative of a force or pressure, but it's only a value given from the sensor and it's range is between 1000 and 25000 (when the load is maximum).

Since on every stabilizer there are two sensor, for redundancy, touching the area A it's possible to read the channel "a" and the channel "b"; if the difference of the two value is over 1000, the machine stop because some sensor has a problem.

Touching the area B, it's possible to view the value of the sensors, channel "a" and "b", of the four stabilizer on the same page.

Touching the area C, it's possible to view the parameters setted by Palazzani for the control of the sensor. For details of this value, contact the service department of



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the Palazzani Industrie S.p.A.

In the area D it's possible to view the diagnostic messages; following a short description:

- Potentiometer 1a breakdown: it is displayed when the potentiometer exceede the min or max setted value. During booms working, it stops also movements which are controlled by the moment limitator. During transfer the movement is not stopped and only the message is displayed
- Potentiometer 2a breakdown: idem
- Potentiometer 3a breakdown: idem
- Potentiometer 4a breakdown: idem
- Potentiometer 1b breakdown: idem
- Potentiometer 2b breakdown: idem
- Potentiometer 3b breakdown: idem
- Potentiometer 4b breakdown: idem
- Selfpropelling interlock: it is displayed when the stabilizers are not layed on the ground and key selector is switched on "transfer" (and no allarm messages are displayed)
- Stabilizer interlock: it is displayed when at least one stabilizer touches the ground and the key selector is switched on transfer (the transfer is blocked)
- Uncorrect levelling of 2°: it is displayed if the machine is wrongly placed and it doesn't allow the booms movements. If the machine goes to an uncorrect levelling during working, only the message is displayed.
- Stabilizer pin not engaged: it is displayed during the positioning if a pin is not inserted. It blocks the stabilizers movement
- Articulation pin not engaged of 120°: it is displayed after the machine positioning if all stabilizers in working position are not open and it doesn't allow the booms movement
- Area manager temporarily blocking: it is displayed it is displayed during the normal blocking of the limitator (it turns on when the machine returns in the allowed area). The message remains displayed if an area transfer end of stroke is defeated
- Area manager permanently blocking: it is displayed if a limitator relay is blocked or if a potentiometer has not the alligned values (the locking limitator remains in fuction)
- Wide area: it is displayed after having placed teh stabilizers correctly and switched the key selector on boom position
- Medium area: it is displayed after wide area (and there are no allarm messages)
- Narrow area: it is displayed after medium area (and there are no allarm messages)



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## CAP. 3° NORMAL USE CONDITIONS

## 3.1 LOAD AND UNLOAD ON TRUCK.

a) By crane

- take the tensors or the equipment fixing stripes off.
- hook the 4 eyebolts on the top of the stabilizing legs with proper loading ropes (min half weight each) (Fig. 3.1)
- lift the machine and go out with truck

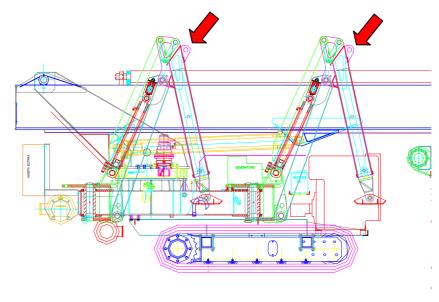


Fig. 3.1

b) Self-loading (if possible). See also the Chap. 3.24

- stop the lorry on level and rough ground
- rotate the stabilizing legs in the hole 2 (see Fig. 1.2)
- start the diesel engine.
- turn the selecting key of the ground control panel on the "stabiling-legs" symbol (part 6 of Fig. 3.2)
- extend the telescopic section of the stabilizar, lock it by means of the pins and lower the stabilizer on the ground.
- before lay the plates on the ground, put the proper rolling chariots (see Fig. 3.34).
- disengage the machine from the lorry and lowering the stabilizing-legs, hoist the platform from the lorry
- slowly, drive the lorry out of the platform
- lift the stabilisers as described in paragraph 3.12 with the belt control



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distant from the machine

 when the tracks are lowered on the ground, retract the telescope sections of the stabilizr.

**NB**: If the ground is solid and resistant (pressed earth, cement, asphalt) the operation is easy; on the contrary if the ground is yelding and irregular it is better to drive the charriots on wooden plates.

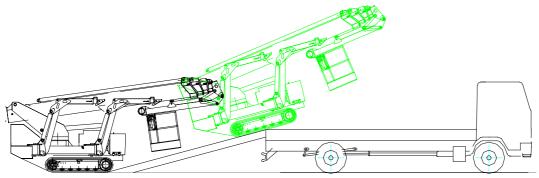
- for the loading, lift the stabilisers from the boom side before and than balancing them with the other two, and follow the procedure on the contrary.

- select now the controls key on "turntable" and transfer to the site with the stabilisers up (min 10/15 cm) for a better stability in case of strong asperities.

c) By using a ramp.

**ATTENTION!!** If you are using a ramp we recommend a max slope of 15° (about 25%) and to attack the ramp with the cage toward the climb. This is absolutly necessari for the stability of the machine.

To attack the ramp, lift up the cage just the necessary to avoid the ramp and not more, like showed in the following picture. (To lift up the cage, thus the main boom, see chap. 3.9)



Warning! During the transport on the lorry, bee sure that the locking rotation pin is insert.





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## 3.2 MAIN CONTROL DESK

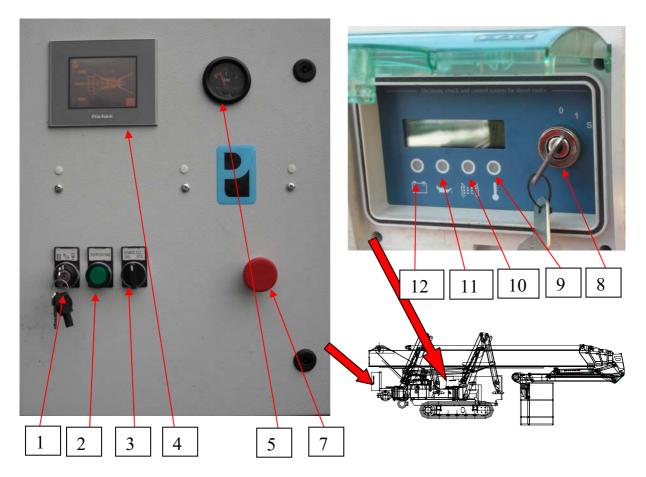


Fig. 3.2

13)
witching controls key.
15)
ift up/lower stabilizer
17)
uel level
19)
mergency stop button
21)
verheating diesel engine
23) Low oil pressare diesel engine

14)
oom lifting up in travel condition
16)
rogrammable Logic Control (PLC)
18)
---20)
eneral key
22) Air filter barred

24) Low tension generator of the diesel engin



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Fig. 3.3

- 5) Differential switch (cage plug)
- 6) Automatic magnetothermic switch (cage plug)
- 7) Differential switch (el. motor)
- 8) Automatic magnetothermic switch (el. motor)



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#### **BATTERY CHARGES**

The battery charges is fitted into the general electrical box.



5. Connect the machine net cable to a plug 230V -50 Hz.

6. After this operation the battery charger (in the electric box) light on automatically and the three leds light on contemporarely for few seconds (self-diagnosis)

7. Then the batteries recharging proces starts and the led shows the recharging status

8. Battery charges doesn't need any maintenance or intervention

A warning light with flashing leds is mounted to signal any eventual anomaly during the charge. Battery charger, is placed on the platform and it is

connected at its electric panel

During working with electric motor, the external electric plug feeds the motor and this device maintaining the batteries efficient.

Batteries are also re-charged by the alternator of the diesel engine.

# **RISK OF BURN**

When the electrolyte is freezed it can make the battery explodes if you try to charge it or to start the thermic motor with a secour battery.

To avoid to the electrolyte to freezes, maintain the battery always charged, disconnect always the negative pole (-) at firs and connect it always at last; never bridge the battery poles.

The electrolyte causes big burns, avoid the contact with skin, eyes, clothes.



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External: wash with water.

Internal: drink a big quantity of water or milk. Ask to a doctor. Eyes: wash with water for 15 minutes and ask immediately to a doctor.

#### **BATTERY CHARGES FOR RADIO-CONTROL**

The radio-control has two batteries; while using the radio-control, one of them



charging. In this way it's possible to have always a charged battery when necessary.

The battery charter is suitable inside the right cover of the machine (see the side pictures).

## 3.3 PLATFORM WORKING WITH DIESEL ENGINE

Platform is provided with 2 separate power; one of them is connected to the diesel engine installed on the same platform.

Used for the truck downloading and for long transfers to reach the working site. It can be used also for elevation working if the emissions gas are accepted (closed sites, noise prohibition, etc.)

Thanks to the diesel engine adequate power, platform movements can be driven at the best rated speed. (at least in respect to the motor at 220V)

Starting procedure:

- on main control desk (Fig. 3.2) rotate the key (item 8) on pos. 1 (oil and el. tension warning lights)
- rotate the key on position 2 to start diesel engine.
- let the engine run some minuts (almost 5 min. with a ridig temperature) before manoeuvring the platform
- due to the presence of a protecting timer, in case of engine stop, wait almost 20 sec. before re-starting



- il motore è regolato tra 2000 g/1 ed a tale regime resterà durante la fase di riposo; durante la traslazione del carro aumenterà il numero di giri automaticamente.
- the engine is set between 1800 and 2000 rpm and remains on this level during the rest phase; during the slow travelling, but the rpm increase automatically in fast travelling.
- to stop it push the button "STOP" on one of the control panel or reset the main panel key; remember to unlock the "STOP" button rotating it slightly otherwise the engine does not start from any other control panel.
- it is possible to start engine also from control panel on cage\_by turning the key switch 2 of Fig. 3.7 if the stabilisers are on the ground and the controls selected on the above mentioned panel (key 1 in fig. 3.2 selected on cage symbol).
- it is possibile to start engine also from ground control panel, by the switch 12 of Fig. 3.6, but before it's necessary to activate it (see radio control manual).



Exhaust pipe is not protectet and burns also on the upper part of the diesel engine. During work with diesel engine in enclosed spaces, exhaust gas must be removed by means of an appropriate hose of a suitable material.



# **FIRE AND EXPLOSION RISKS**

- Fuel of the engine can cause fires and explosions
- Stop the engine before the refuelling
- No smoking during the refuelling
- All necessary protections must be activated in case of weldings, or free flames
- Clean the machine from oily materials and deposits or inflammable residual with non inflammable solvent.
- Also batteries can explode in presence of sparks or free flames: air the site and most of all do not put the battery in charge in these conditions.
- The exhaust gas can contain sparks, therefore air the working site if any vapours, gas or inflammable liquids are present.
- Eventual hydraulic oil or fuel leakage must be eliminated in phase of scheduled maintenance.



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# 3.4 PLATFORM WORKING WITH ELECTRIC MOTORS

This energy source use is recommended when the machine works indoor or where the exhaust gas or noise are forbidden and when the energy saving is important. Where possible, it is recommended to branch always the platform to an electric source, in fact, el.motors can be used alternatively to diesel engine, for small aerial movements and, eventually, for recovery in emergency (i.e. diesel breakdown)

Starting procedure:

- on main control desk (Fig. 3.2) rotate the key (item 8) on pos. 1 (oil and el. tension warning lights)
- branch the electric plug (fig. 3.4) and socket (16A)
- verify that one of the "STOP" push-buttons is not pressed
- now, acting on one control lever, electric motor run
- it is also possible to stop electric motor, by acting on the same STOP pushbutton of the diesel engine, or by rotating key on OFF position
- electric motor re-starts, when the push-button is re-set by rotation and you act on one control lever



Fig. 3.4

#### NOTE:

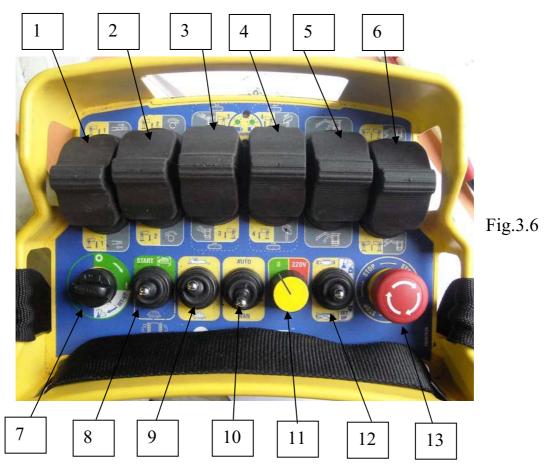
For the efficient functionning of magnetothermic differentials switch (life-savers) on the machine, the electricity plug mus be safely connected to the ground and be on a normal box; do not use flying cables sometimes existing on the working sites. During the machine displacement on the ground, keep the max attention to not



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crush the feeding cable with wheels or tracks and to the cable limit lenght.

# 3.5 GROUND CONTROL PANEL



- 14. Stabilizer n° 1 telescope boom left track
- 15. Stabilizer n° 2 turntable rotation
- 16. Stabilizer n° 3 telescope jib
- 17. Stabilizer nº 4 cage rotation
- 18. Jib articulation
- 19. Stabilizer oil main boom right track
- 20.Radio-control switch on
- 21.Radio-conrol activation
- 22. Moving sped slow/fast
- 23. Automatic/manual stabilizing
- 24.Opzionale
- 25.Start/stop engine
- 26.Stop control



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# 3.6 CAGE CONTROL PANEL

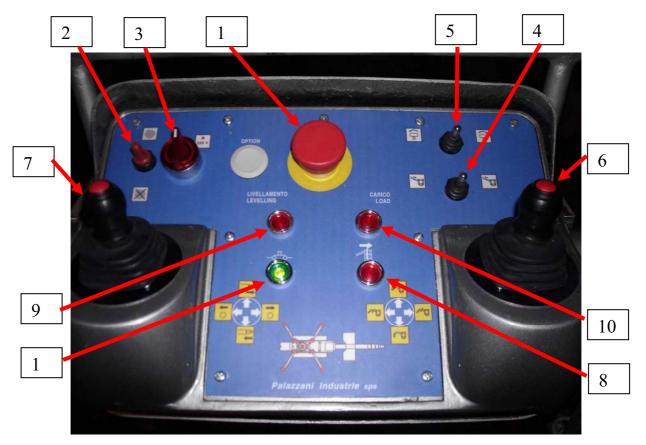


Fig. 3.7

- 13.Emergency stop button
- 14.Start/Stop engine
- 15. Activation current generator
- 16.Extend/retract jib
- 17.Cage rotation
- 18. Joystick activing main boom and jib
- 19. Joystick activing turntable roatation and telescopic boom
- 20.Led max outreach
- 21.Led cage not levelled
- 22.Led cage overload
- 23.Led control panel activate.

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# 3.7 PLATFORM STARTING PROCEDURE

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Especially after a period of inactivity, before starting the engine it is recommended to check all the safety devices and controls.

Some of these controls can be fulfilled with the machine off, other controls after the stabilisers positioning. For the first ones:

7) verify the fuel level	
8) verify the hydraulic oil level	
9) verify the electrolyte level and batteries charge	
10)	v
erify the track condition	
11)	a
lso check that STOP push-buttons are de-locked	
12)	c
heck the booms extension chains integrity and tension (the chains	
must remain tense to the touch and not loosen during boom extension	

WARNING

Don't start the platform in case of any irregularity

# 3.8 PLATFORM SELFPROPELLING

and retraction)

- start diesel engine from control panel (pos. 8 Fig. 3.2)
- select the controls selection key (pos. 1 Fig. 3.2) the turntable symbol (central position)
- detach the radio control from its support, use the shoulder belt and choose a remote, safe and panoramic control position, far from the platform



never drive the platform till you have reached a safe and panoramic remote control position.

- select "rabbit or snail" on the ground control panel with switch 9 in fig. 3.6
- softly act the two control levers 1 and 6 in fig. 3.6 to transfer forward or backward.

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it is possible to rotate the platform, acting on the levers in opposite sense

# WARNING

Use slow speed selection when driving on irregular grounds, slopes, restricted areas when sloping up or down, the cage side of the platform must always be in uphill position

Stop the platform before inverting the drive sense

against overturging risks, it is recommended to drive with the stabilizing legs enlarged and lowered near the ground

# WARNING

Platform is not admitted to road circulation and, therefore, driving on an area opened to the traffic needs necessary protections and signals.

Many times an authority authorisation for the manufacturing site is necessary.

If not possible, follow the machine by the truck or by another vehicle with emergency lights on.

The operator must drive the machine on the sidewalk by paying attention to eventual obstacles or people present on the way.

The transfer on a public area must be short, made in favourable hours, and if necessary with the police approval.

# 3.9 SPECIAL BOOM ACTIVATION

In case of a strong slope or loading ramps, the boom can be lifted at the necessary angle to avoid that the cage touches the ground without put stabilizers on the ground.

Act as following:

- the boom must be with extension completely retracted
- with the engine on, push the button part. 2 in fig. 3.2 and contemporarily, from the ground controls panel, lift the boom up (part.6 Fig. 3.6).
- when the operation is finished, repeat the operation on reverse to bring the boom back to horizontal position

 $\square$  Do not lift the cage floor more than 80 cm from the ground.



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## 3.10 STEERING

It is controlled varying the speed of the tracks, by means of the corresponding control lever.

Platform can be also be rotated, acting on the two levers 1 and 5 of Fig. 3.6 at the same time and in contrary sense. It is advised to make this manoeuvre at a low speed and on flat and regular ground, only

## 3.11 AUTOMATIC BRAKE

No braking control is necessary, as the platform is provided with an automatic system consisting of mechanic negative brakes, with hydraulic release and overcentre valves, mounted on transmission hydraulic motors

Slow speed pre-selection 10 of Fig. 3.6 increases braking action and, therefore, it is recommended for driving and parking on a slope

# 3.12 LEVELLING THE MACHINE

Stabilizing legs can be individually rotated and articulated, according the owner needs.

Once detect the desire position it's indispensable to insert the pins in the appropriate holes (fig. 3.12).



Fig. 3.12

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always verify that the floor capacity is adequate to the pressure of each outrigger (this value is signalled by a special label).

The stabilisers telescopic extensions can be retracted only for loading/downloading operation from the truck but they MUST be completely retracted during elevation booms working.

# A different use can cause very dangerous injuries to operators and machine.

Now it is possible to level the machine as following:

- Turn the selecting key pos. 1 of Fig. 3.2 on "legs" symbol (right side)
- Check that the green light on the turntable will be switched on.
- You have two possibility to levelling the machine:
  - Automatic mode: switch on "Auto" the selector pos. 10 fig. 3.6. Activate

the joystick pos. 1 fig. 3.6 to give the direction of the movement, and at the same time push forward the joystick pos. 6 of the same picture, to give oil to the stabilizer. In this modality the machine levelling automatically and when the frame is in horizontal position, the system stop the stabilizer movements. **Note: check always** 



the correct level of the frame using the visual bubble on the frame.

- Manual mode: switch the pos. 10 fig. 3.6 on "Man". Activate the joystick from pos. 1 to 4 fig. 3.6 to give the direction movements for each stabilizer and at the same time push forward the joystick pos. 6 of the same pictures, to give oil to the stabilizer. In this modality it's possible to move separately every stabilizer.
- When the machine is leveled, the four light on the stabilizer (fig. 3.13) switch off. Attention! This do not ensure the correct levelling of the

machine; before use the platform, check the correct

levelling by means of the bubble on the frame.



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Fig. 3.13

NOTE: When the machine is livelled, it's recommended (by means of the manual procedure) to give a short impulse, without movement of the frame, to the four stabilizer to ensure a correct pressure on the ground. In this way the performance of the machine will be at the top.

**Important!** Check the correct levelling of the machine by means of the bubbole on the frame (Fig. 3.14).

Use wooden plates to make the ground more solid (Fig. 3.15), which must be wide enought to avoid dumping and high no more than 20 cm.

It can be necessary to position the stabilisers on different height levels (i.e. on stairs, sidewalks, slopes, etc.) and this is easy because the stabilisers can lower independently (Fig. 3.16).

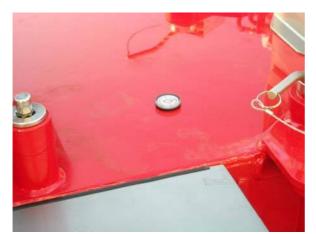
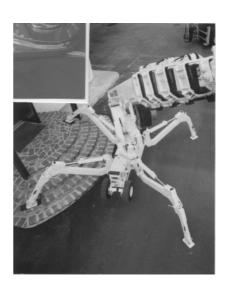


Fig. 3.14







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Fig. 3.15

Fig. 3.16

Remember that, in case of manual stabilization, it is easier and safer to adjust the levelling by lowering the stabilisers instead of lifting them. Always check that the plates are solidly positioned on the ground (it is dangerous to put them on gutters, near scarps, on soft or water grounds, etc.)

To retract the sabiliser, check that the green light on the turntable (Fig. 3.17) is lighted on. Select the key 1 in fig. 3.2 on stabilisers symbol, act the accelerator lever part 6 in fig 3.6 and the lever 1 to stabilisers lifting direction until the complete retraction. In alternative, act manually on every stabiliser in the following way: switch pos. 10 fig. 3.6 on "Man", act, preferably, two levers contemporarily (the two front or the two rear ones) and push the accelerator lever softly, until the complete retraction.



Fig. 3.17

# NOTE:

In normal working conditions platform is to be hoisted  $10 \div 40$  cms. over flat ground

Do not excede 40 cm from the ground on flat ground.

Stabilization on steps gives no problem, it is only important to level the platform.

On a steep slope, where there is a risk of sliding, it is recommended to place some woods under the legs, in order to be within  $2^{\circ}$  (see spirit level) before levelling



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with legs

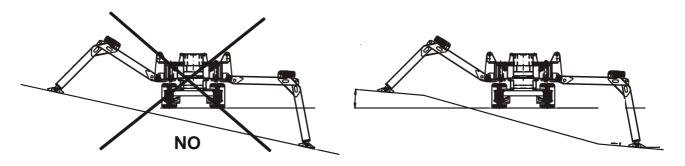


Fig. 3.18

The max slope between the two stabilisers plates laying floors indipendently from the scarp must not excede  $5^{\circ}$  to avoid chariot sliding due to the limited attrition resistance (Fig. 3.18).

#### 3.13 AERIAL WORK

#### Access to the platform

Access to the platform with retracted boom and cage near the ground. Materials also must be loaded this way.

Operators must not exit and access from the cage from high position.

Stay on the cage only for lifting and working in high position. During the transfer, operators must not stay on board.

It is possible but it is <u>very dangerous</u> to load material when the machine is placed and extended. Protections don't grant all risks from a possible overturn.

If the light and the overloading acoustic alarm activates, quickly download the exceeding load.

If the cage has to lift beyond an obstacle (river, difficult ground..) it is advisable to try before with a similar weight (i.e. 2 persons) and check if the boom reaches the wished position without stopping.

In this case it is always possible to safety lower the cage to the ground and lift again.

After positioning the stabilisers on the ground and leveling the chariot, the machine is ready for aerial work. Do the following: take the safety socket off (fig 3.19) used for transport and use the control panel in the cage.

From this position it is possible now to operatively move the boom. In fig. 3.7 all



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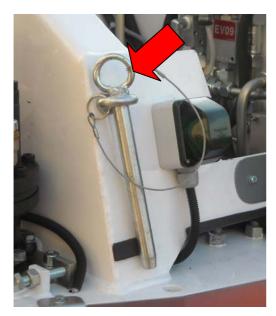
joystick manoeuvres are indicated.

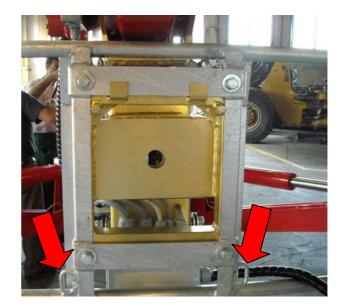
It is possible to enable the aerial movement controls with the key also from a different position from the usual one (for maintenance, regulations, rentals with operator, training courses, etc.).

After the cage access, before making any control, fix the safety belt (which must have a rope not more than 1 m lenght) to the proper rings (Fig. 3.20).

To control any movement, act on the corresponding lever, avoiding sudden and brusque manoeuvres.

First lift the first boom around 45° and than open the jib to get away from the boom; then you can procede with turntable rotation and telescopic extensions.









 $\bigtriangleup$  Do not make abrupt manoeuvres or sudden inversions in movements to not counterblow the cage.

The more the telescopic are extended the lower must be the transfer.

To go back to rest position, retract the extension completely, close the jib, straighten the cage eventually rotated, put the chassis on axle rotating the turntable and lower with the first boom until the green light switch on (Fig. 3.17).

The above mentioned green light activates only when the booms are: completely retracted, on the longitudinal axle in respect to the chassis towards the

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diesel engine, lowered below a certain angle.

From this moment it is possible to lift the stabilisers selecting the stabilisers symbol with the key 1 Fig. 3.2 and proceeding as described in the paragraph 3.12.

# 3.14 SAFETY DEVICES

Platform is provided with the following safety devices:

- automatic interlock between thermic and electric power sources
- automatic interlock between stabilizing legs and selfpropelling drive
- automatic interlock between stabilizing legs and boom
- load management system
- load limiting device (con preallarme)
- self-locking valves on hydraulic cylinders
- protection of the control levers
- rings for harness on aerial cage
- overpressure valves on hydraulic system
- booms extensions chains doubling
- automatic brake on turntable slewing
- automatic brake on transmission
- mobile panel for remote control
- emergengy stop push-buttons on all control stations
- el.sensors on the chains of the first boom section
- el. sensors on the pins of the legs supports
- cage levelling limiter (5°-10°)



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# 3.15 LOAD MANAGEMENT SYSTEM

Platform is provided with an automatic moment limiting device, constantly monitoring the specific pressure of each stabilizing leg on the ground. When the pressure of one leg goes down to a minimum pre-set value, the red lamp mounted on this leg lights (fig.3.13) and, "limitator block" is displayed, at the same time, movements increasing working outreach are automatically excluded. This load/outreach limit situation is also signalled by a red light on the control panel. (Fig. 3.7 pos. 8)

Movements reducing outreach are always normally working and, therefore, operator can act on them to reduce the outreach.

Cage re-entering in safe position is signalled by leg and panel lamps switching off

Never switch off the start key of main control desk, when aerial cage is on the load/outreach limit situation, signalled by the red lamp on the control panel.

WARNING This particular load management system gives full protection, either with regards to all different legs positions and with different loads in the cage. It is tared by the manufacturer according to the platform's characteristics of stability.

Any intervention of modification and/or exclusion of this device is absolutely prohibited

No embarking persons, or materials in the cage, when it is in aerial position



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The machine is equipped with and load limiting device in the cage.

This device avoids the overcoming of mominal capacity. If this would happen it will cause the stop of all manoeuvres and the switching on of an acustic and luminous alarm on the cage (pos. 10 Fig. 3.7).

To re-start all mouvements, take off the excess of load, wrongly loaded.

 $\Delta$  In case of accidental bump under a moulding or in branches, it is possible to activate the emergency operations to move tha machine like the instructions of chapter 5.

# **3.17 CAGE SELF-LEVELLING AND ROTATION**

Aerial cage has two movements: rotation on horizontal position to grant the constant levelling with the proper ground and rotation right-left in respect to the vertical axle.

The first movement is automatically and consisting of an electronic pendulum acting on a proportional electro-distributor valve that opens the oil flow from main system to the hydraulic motor mounted on the boom top; the complete system is activated by acting on the boom or jib movement leveres, situated on both manoeuvre sites, and this excludes the sudden and unexpected movements of the cage.

The second movement is activated by switch on the control panel. (Fig. 3.7 pos. 5) For obtaining a complete rotation, keep the jib horizontal to avoid contacts between the cage and the boom; remember to return to the orthogonal position to the boom before lowering to rest.

The cage is equipped with an electronic device which activates with two main articulated booms lifting and lowering movements.

To maintain the cage horizontal, if there's no a defeat, act the lever during the jib manoeuvres softly; if the cage loses horizontal position more than 5° all boom movements stop so that the system has time to level the cage.



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N.B.: After 10° of inclination all movements stop and any by-pass is possible.

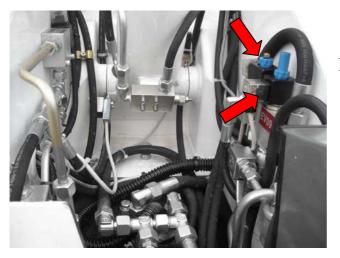


Fig. 3.24

If this happens:

- inside the turntable fig. take of the lead at the valve Fig. 3.24 marked with EV9 and and unscrew the blue cap.
- push and rotate the cursor.
- while pushing the button on the valve marked with EV10 act one manual lever of boom or jib lifting/lowering from one of the activated control panels until the cage returns vertical

In this way all service controls re-activate.

It is compulsory necessary to unlock the valve, put the cover, lead and write the cause for having taking off the lead on the manual **before** going back to work with the service controls.



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# 3.18 ELECTRONIC INCLINOMETER

Acoustic	Alarm
code	description
12 rings	Electro-mechanical bubbles in short circuit
11 rings	Permanent damage – repairable only by ISB S.r.l.
10 rings	Machine parameters not correct - send correct parameters
9 rings	Temperature over the allowed values
8 rings	Feeding tension over the allowed values
7 rings	Clockwise movement valve spool in court circuit or disconnected
2 rings	Platform inclination out of permitted limit

Note 1

The system generates a permanent alarm when an irreversible error can occur and the safety of the machine users could no more be assured. When this alarm activates, the machine is maintained in functioning condition only to allow the user on the cage to reach the ground. In these conditions, the light alarm displays 11 blinking, while 25 sec of acoustic alarm activates every 60 sec.

Note 2

The weight pre-alarm is indicated by a continuous acoustic alarm, interrupted by intervals of about 1 sec. This is for better hear the alarm

Fatal error

If the ecu system makes a permanent acoustic alarm (the light is permanent switched on), the system is no more working. The level and weight regulation will be permanently deactivated.



Fig. 3.26



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In the electronic card of Fig. 3.26 there's a green led (1) indicating the blinking (the same blinkings as the ringings), there are also some trimmer for the manual regulation of some parameters in case the programme device wouldn't be available.

See these trimmers and their function on Fig. 3.27

# TRIMMER USE

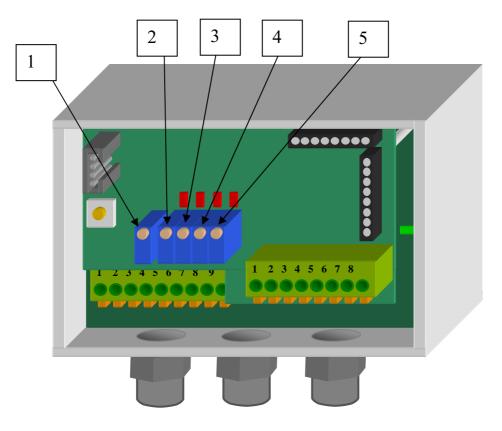


Fig. 3.27

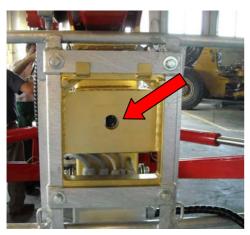
- 6 cage horizontality
- 7 clockwise current rotation
- 8 under clockwise current rotation
- 9 clockwise speed
- 10 under clockwise speed



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# 3.19 CAGE LOAD LIMITING

On the machine is fitted a sensor to evoid an overload of the cage (Fig.3.28).



If the weight in the cage is over the maximum admissible, all the movements of the machine are stepped and there i san acoustic and optical warning on the cage control panel. Before stop all the movements, there is a countinuous acoustic worning setted at the 80% of the maximum admissible load.

When the maximum load is reached there is an alternate acoustic worning.

Fig. 3.28



In the pictures 3.29 there is a short diagnostic of the load sensor.

- Error LED. Red color. If on, there is an anomaly in the sensor.
- Alarm LED. Red color. If on, there i san overload in the cage.
- Zero/Tara LED. Orange color. If on, the sensor works correctly and the measure is inside a tollerance +15kg -15kg.
- Power LED. Green color. If blinking, there is electrical power to the sensor.





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# 3.20 ELECTRIC CURRENT GENERATOR (OPTIONAL)

Platform is provided with an electric generator, hydraulically actuated by diesel engine exclusively, deliverying 1 kW-220V single phase el.curent to the aerial cage.

Electric generator is put in action from aerial cage panel (Fig. 3.7 pos. 3), when diesel engine runs, platform is stabilized and selecting key rotated on "cage" position.

Nevertheless, for economy reasons, it is advisable to actuate the el. generator only when it is strictly necessary.

Weekly check of the differential magnetothermic relay is recommended (life saver Fig. 3.3); drive the generator, push the test button and verify that el.current does not arrive at the plug on the cage.

In case of an electricity lost and differential intervention, make the electric system controlled by a skilled person.

Use exclusively tools and projectors in conformity with electric standards and in good conditions. (In alternative use the proper individual protection devices)



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3.21 INTERCOM (OPTIONAL)

It is possible to comunicate to the persons on the cage with the intercom.

SKYTALK is the industrial intercom water resistant for external use.



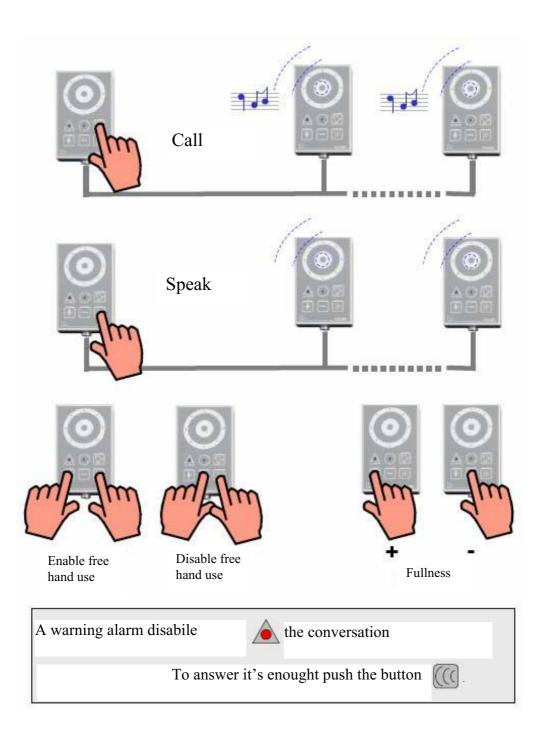
# INTERCOM FOR AEREAL WORK PLATFORMS

USE MANUAL





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# 3.22 CHECK-UP (FROM GROUND PANELS)

Especially after a period of inactivity, platform needs a check-up before working :

Check up list:

- when you turn the starting key of diesel engine, legs' flashing lights must be on (Fig. 3.13)
- these lights must be off when legs are lowered in pressure on the ground
- the green light on the turntable is on (Fig. 3.17)
- lift the boom until this green light on the turntable is switched off, descent until it switch on again, rotate the turntable slightly until the green light switches off.
- Hoist the boom till the green lamp of rest position is off and try to raise the legs (it must be impossible !!) If the stabilisers move do not use the machine and bring it to an authorised workshop or to the manufacturer)
- open the jib slightly and extend the boom until it stops when the red light on the manoeuvre panel and on one of the two stabilisers from the opposite boom position side (Fig. 3.13) switches on
- try now to lift the boom slightly and than lower it (if the red light is still on this manouvre must be possible)
- check that the red light on the manoeuvre panel remains on together with the green light near it
- check the correct working of : emergency stop push-buttons



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# 3.23 CHECK-UP (FROM CAGE PANEL)

Verify the correct working of all controls and warning lights of cage control panel and, also that aerial cage is correctly screwed on its support:

- test all above mentioned movements
- extend the telescopic until the red light switches on (fig. 3.7 pos. 8)
- start generator and also verify the light on the selector
- check the impossibility to make the rotation, boom descent and telescopic extentions manoeuvres, when the red light is ona (Fig. 3.7 pos. 8)
- verify the cage rotation
- verify the emergency STOP. Make a manoeuvre and push the stop button. On the contrary do not use the machine and contact an authorised workshop
- verify the start device
- Connect external line on one of electric plugs of the platform and verify that el. motor runs when STOP push button is released, also check that el.motor stop, when diesel engine start
- Check that the booms extension chains and their relative electric micro contacts on the first boom are integral
- Check if the load limiting device is functioning by loading (with the boom in horizontal position and the cage close to the ground) kg 240 or more and verifying the blinking red light, the acoustic alarm and the stopping of all movements of the booms.



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# **3.24 SPECIAL DIRECTIONS**

## Transport

The machine has a modest transfer speed, therefore the transfering on working site must be done on truck.

The machine can be loaded with the boom above the cabin if the truck is not equipped with a crane, pallet holder or protection nets, or with the boom toward the back.

In this case put the indication of leaning loads from on the boom extremity.

Transport shoud be on a truck equipped for this purpose, because the platform is equipped with connections corresponding to the truck ones and this keep the fixing time shorter and the transport safer (Fig. 3.32)

Put tensers to these connections and fix them to the truck.



Fig. 3.32

#### Starting in rigid climate conditions

In favourable climate conditions act with a special procedure, most of all in first engine starting.

- start diesel engine and let it run almost 5'; in case of engine stop, wait almost 30 sec. before re-starting, due to the presence of a protecting timer
- after this time, accelerate at max selecting on "rabbit" and transfering for 1 minute

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- control first movements at a slow speed and let engine run, in order to have hydraulic oil at a right temperature
- leave the engine turning for the first 15 min even if the aerial work does not requires it
- till hydraulic oil has not reached a right temperature, irregular speed movements are possible

## Driving on a slope

In case of slope grounds, first select the slow speed "snail" and observe the following:

- keep the booms extremities towards the slope
- when driving on a slope, it is recommended to pre-select slow speed and cage side of the platform must be always up-hill positioned
- when driving on irregular ground it is recommended to lower stabilizing legs near the ground (30 cms. approx.)
- it is also recommended to take the boom as low as possible
- platform must be driven from a safe side position (not before or behind)

#### <u>Lights</u>

For night working or in few lighted sites, use the electric socket on the cage to light a lamp max 60W a 220v c.a.

#### Lifted by crane

For loading the platform on a truck, it is possible to use a crane. In this case:

- be sure that the stabilisers are completely retracted
- use the fixing rings on he stabilisers to attach the machine to the crane with four independent ropes

Use lifting equipment, i.e. ropes, with proper sections for lifting and check that the crane loading is proper with the total platform weight indicated in the turntable.



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# Self-loading on truck (if possible)

The machine complete of original carriage can be loaded by itself on the truck with the following procedure:





- place the machine on a flat ground (if it's possible) and in any case in a not very difficult ground considering also the space for the truck
- put the outriggers supports in the position of central hole or in a sufficient position for the following truck passage.
- if the truck is very high, extract the manual extensions of the outriggers to second or third hole and put again the blocking pins (Fig. 3.33)

 $\checkmark$  These manual extensions of the outriggers must be used only for the loading on truck.

It is forbidden to move the boom while working with these extensions. <u>They</u> <u>mustn't</u> be used to enlarge the placement base nor to increase the working height of machines.



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- put the carriage with proper rolls under the plates (Fig. 3.34)
- lift completely the machine, moving alternatively the two front and rear stabilisers. Always lift the two front stabilisers first, and then to balance with the rear ones until the cylinders course is finished. (Fig. 3.35)



Fig. 3.34



Fig. 3.35

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During loading/unloading phase from the truck, you **must** mount the proper roll carriages on the extensions if they are extended. On the contrary you **must not** mount the roll carriages during normal placements for lifting working.

- move the truck as to place the load area under the machine
- retract the outriggers as to place the chassis on the supports and on the area itself
- fix the machine
- recover the carriages



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# 3.25 DIAGNOSTIC

On the machine is fitted a touch screen interactive display located on the main electrical box (Fig. 3.36), and it's function is to monitoring the work cycle of the machine.

Additional the monitor has a diagnostic function.

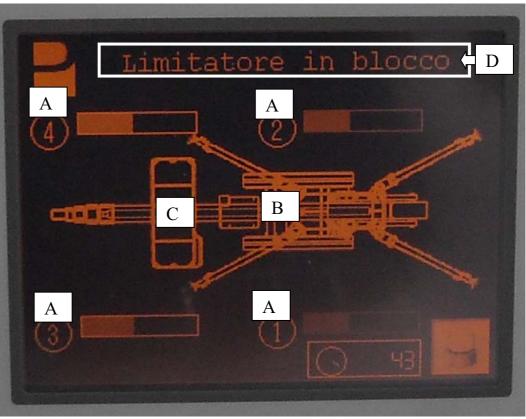


Fig. 3.36

Touching the area A it's possible to read the instantaneous value of the pressure on the pertinent stabilizer. The number is not indicative of a force or pressure, but it's only a value given from the sensor and it's range is between 1000 and 25000 (when the load is maximum).

Since on every stabilizer there are two sensor, for redundancy, touching the area A it's possible to read the channel "a" and the channel "b"; if the difference of the two value is over 1000, the machine stop because some sensor has a problem.

Touching the area B, it's possible to view the value of the sensors, channel "a" and "b", of the four stabilizer on the same page.

Touching the area C, it's possible to view the parameters setted by Palazzani for the control of the sensor. For details of this value, contact the service department of



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the Palazzani Industrie S.p.A.

In the area D it's possible to view the diagnostic messages; following a short description:

- Potentiometer 1a breakdown: it is displayed when the potentiometer exceede the min or max setted value. During booms working, it stops also movements which are controlled by the moment limitator. During transfer the movement is not stopped and only the message is displayed
- Potentiometer 2a breakdown: idem
- Potentiometer 3a breakdown: idem
- Potentiometer 4a breakdown: idem
- Potentiometer 1b breakdown: idem
- Potentiometer 2b breakdown: idem
- Potentiometer 3b breakdown: idem
- Potentiometer 4b breakdown: idem
- Selfpropelling interlock: it is displayed when the stabilizers are not layed on the ground and key selector is switched on "transfer" (and no allarm messages are displayed)
- Stabilizer interlock: it is displayed when at least one stabilizer touches the ground and the key selector is switched on transfer (the transfer is blocked)
- Uncorrect levelling of 2°: it is displayed if the machine is wrongly placed and it doesn't allow the booms movements. If the machine goes to an uncorrect levelling during working, only the message is displayed.
- Stabilizer pin not engaged: it is displayed during the positioning if a pin is not inserted. It blocks the stabilizers movement
- Articulation pin not engaged of 120°: it is displayed after the machine positioning if all stabilizers in working position are not open and it doesn't allow the booms movement
- Area manager temporarily blocking: it is displayed it is displayed during the normal blocking of the limitator (it turns on when the machine returns in the allowed area). The message remains displayed if an area transfer end of stroke is defeated
- Area manager permanently blocking: it is displayed if a limitator relay is blocked or if a potentiometer has not the alligned values (the locking limitator remains in fuction)
- Wide area: it is displayed after having placed teh stabilizers correctly and switched the key selector on boom position
- Medium area: it is displayed after wide area (and there are no allarm messages)
- Narrow area: it is displayed after medium area (and there are no allarm messages)



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# CHAP. 4 ANOMALOUS WORK CONDITIONS

# 4.1 IMPROPER USE

- If not explicitly indicated by the customer, it is forbidden to use the platform as a crane, with or without the aerial cage
- The strains induced to the frame due to the weigh lifting may cause serious damage to the parts and affect the arms stability itself or the chains endurance.
- It is forbidden to drive the platform, if the boom is not lowered on its rest position. The machine stability may be seriously affected.
- The same is for the arm maneuvers without placing the stabilizers.
- Any modification of the speed of the movements is forbidden
- It is forbidden to mount on the aerial cage, or along the boom any superstructure increasing the resistence to the wind
- In case of using the equipment this way, place the machine with the square base and let the extensions re-enter for at least 1 mt. each.
- It is forbidden to extend the telescopic section of the legs, for the stabilization of the platform (it can be extended exclusively for loading/unloading operations)
- It is forbidden to stabilize the platform on the holes indicated for the rest position of the legs (rest hole).
- The contact area may result too small and the machine stability to overturning may not be guaranteed.
- The machine, during this forbidden operation, does not allow arms maneuvers, also when the placement is done.

# 4.2 ANOMALOUS CONDITIONS

- Outcoming the area automatic limits is severely forbidden.
- Manual intervention on the hydraulic controls (by-passing the safety devices) is allowed exclusively for an intervention in emergency <u>it is</u> <u>forbidden</u> to follow this procedure for an increase of the performances of the platform
- In case of a failure in the electric plant, the emergency operations will allow every maneuver (see the chapter about the emergency operations).platform must be directly controlled by the operator on the aerial cage – operation from the ground is admitted only for particular situations and for emergency interventions (maintenance interventions, machine resetting, staff education, short use with an assistant previously authorized by the boss, when persons



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not prepared are present in the cage).

# **4.3 CRITICAL CONDITIONS**

- When the expanding of the tracks is provided, always maneuver with extended tracks and shrink them when maneuvering on plain terrain only, for trepassing narrow passages.
- lower the outriggers near the ground, when the the platform is driven on irregular ground, with important side slopes (15-20%).
- driving on a slope, the cage side of the platform must be up-hill positioned
- when the platform is stabilized on a garage slope, it is advisable to place wooden boards under the lower legs, avoiding any sliding possibility; make sure that the machine does not slip and operate oblique or upward.



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# **CHAP. 5 EMERGENCY CONDITIONS**

## **5.1 DEFINITION**

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Intervention under emergency conditions is the recovery of the personnel blocked on the cage in aerial position, for a sudden illness, or for a breakdown.

The reasons for a recovery can be of two kinds:

- illness of the people driving the cage
- machine damage, due to a lack of the engine power, settling of the pumps, battery or flexible pipes damage, electric failures.

In this last case, the persons on the platform may have become unable to move but can use the emergency devices placed near them.

Any other emergency situation (fire, earthquake, etc.) is not considered, as the machine is not designed for fire-fighting and for rescue service.

Time of the recovery operations is not necessarily short

#### 5.2 INTERVENTIONS UNDER EMERGENCY CONDITIONS

The platform is provided with safety devices protectiong the personnel during the normal work and also allowing the recovery in case of a possible breakdown Main emergency devices consist of :

dual power source, dual control stations, emergency stop push buttons, interphonic communication system, supplementary hand pump, direct control of electro-distributor valves.

#### <u>1 Procedures to follow in emergency</u>

Platform is provided with several devices for aerial cage recovery. Therefore, it is recommended to follow these directions, avoiding operators descent by cables, along the boom, etc.

#### THAT IS VERY DANGEROUS!!!

In case the operator on the aerial cage is seized by a sudden illness, before touching the platform, be sure that boom or cage are not in contact with live electric lines.

# DON'T TOUCH THE PLATFORM, ALSO FOR PERSONS AT GROUND THERE IS A SERIOUS ELECTROCUTION HAZARD

When the emergency caused by a breakdown is finished, platform must be submitted to a check-up by a specialist.

#### 2 Hydraulic power

In case of a breakdown of diesel engine, it is recommended to connect the electric



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motor to a feeding line, so operators have an alternative power source at their disposal also in emergency; on the contrary, in absence of electric energy, the power source can be replaced with the starting of the diesel engine

In both cases the work can continue and all safety devices are regularly working

# 3 Controls

Turning the selecting key on turntable symbol, assistant can operate any movement for normal aerial work, or for re-entry in emergency, from the ground control panel. In this case, all safety devices are regularly working

## 4 Emergency stop

Emergency red push button is mounted on all control stations and, when pressed, it allows to stop the energy source activated at that moment.

Push-button is of self-retaining type and permanently cuts re-starting system from any control station if it has not been re-set by rotation

If you do not succeed in starting the diesel or the electric engine, check whether one of these "stop" buttons has been left stuck down or not.

6 Electropump for emergency (optional)

In case of failure or impossibility to use the service pumps, it is possible to intervent, in order to recover people, onto the emergency elecric pump connected to the equipment batteries.

Push the STOP button on the panel and act on the control levers

Is fed by the batteries of the diesel engine and, for overheating problems, can be activated for cycles of 3' with a pause of 15'

WARNING this electropump is to be used exclusively for recovery in emergency

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# 5.3 RECOVERY OF THE PERSONNEL ON THE AERIAL CAGE

#### Machine working in order.

It is possible to recovery personnel on the aerial cage acting on the ground controls: turn key (Fig. 3.2 pos. 1) on turntable symbol and operate by the remote control; in this case you can working because all the safety devices work regularly

#### Anomaly to the electric plant

In case of motor and pump doesn't run, it is impossible to act on ground control panels, or there is an anomaly to the electric plant.

To lower the aerial cage on ground, act as follow:

- Inside to the turntable, uncover in lead and unscrew the blue cap of the valve marked with EV09 (fig. 5.1 part.1) and EV23 (Fig.5.2), push the cursor and rotate in clockwise and lock in that position.
- Open the cover of Fig. 5.3

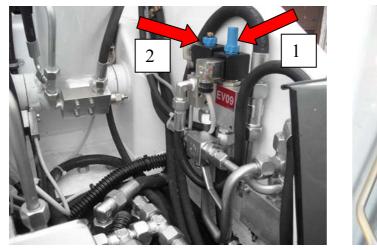


Fig. 5.1

Fig. 5.2

- *Telescopic boom in*. By means the lever 1 of Fig. 5.4 activate the boom in (see the label).
- *Lowering main boom.* Once the telescopic boom is total in, with the lever 2 of Fi. 5.4 activate the lowering boom (see the label) until the cage is on the ground.
- *Attention!* During the lowering boom, the cage not levelling automatically but it's necessary to do this manually as follow: push the button of the valve in the turntable marked with EV10(Fig. 5.1 part. 2) and at same time, the person on the cage has to push the centre of the valve of Fig. 5.5 from one side or other until the cage floor is horizontal. Execute alternatively the cage levelling and boom lowering.



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Fig. 5.3

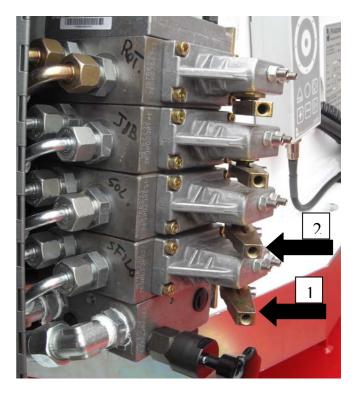


Fig. 5.4



Fig. 5.5

Safety devices are excluded when you act on the hand pump – therefore, recovery interventions must be executed exclusively by specialized personnel, authorized by the employer



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In any case, telescopic extension and rotation of the boom must be avoided

Warning! Once the operation has been completed, inform the responsible personnel so that they control the machine, also informing about how the machine has been used and in which conditions the failure has occured.

Warning! The uncovering in lead of the valves (fig 5.1 and fig 5.2) is to be justified on the register in the Manual that comes with the machine and the valves are to be unclamped and re-covered in lead before restarting the machine.

Any tampering that is not justified makes the discharges the producer's responsibility.

#### **Recovery by hand pump**

In case of a total breakdown including engine and el.motors, it is necessary to generate the hydraulic power by means of the hand pump



# Fig. 5.6

The use of the pump is only possible when first closing the "piloting exclusion" wheel (fig 5.6), and by using its proper lever of the pump (Fig. 5.7).

The manual pump is an alternative pump, though it is small and hard to use.

Once the wheel has been closed, in order to recover the cage you only need to follow all the instructions in the previous paragraph

(Anomaly in the electric plant), with the difference that now you use the manual pump Fig. 5.7 as source of energy.

Fig. 5.7



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# 5.4 STABILIZER LIFTING

When the boom is completely leaned and retracted, it is possible to hoist the stabilizing legs acting a.f. :

This operation is not included in the emergency procedures because the arm has to be laid down already and the people kept back from the cage; anyway, it may be necessary to close the stabilizers for loading onto a lorry.

Recovery has to be executed following this path

- 1. start the diesel engine
- 2. open the cover of Fig. 5.8
- 3. screw the knob of the valve marked with EV03 and EV06 of Fig. 5.9
- 4. activate the lever of Fig. 5.10 of the hydraulic distributor side "stabilizer" and at the same time push the centre of the valve of the stabilizers in the cover of the left side of the machine (from EV11 to EV14 of Fig. 5.11) one by one.



Fig. 5.8



Fig. 5.9



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Fig. 5.10



Fig. 5.11



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# 5.5 SELFPROPELLING

This operation is not part of the emergency operations. Anyway it may be necessary to move the machine in order not to obstruct a passage. Act as follow:

- execute the preview operations until the point 2
- screw the only knob of the valve marked with EV03 of Fig. 5.9 (the knob of the valve EV06 has to be unscrew).
- act on the two control levers (Fig. 5.10) forward and backward

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# 5.6 FIRST BREAKDOWN SHOOTING FOR OPERATORS

# IN CASE OF ANY IRREGULARITY IN WORKING, IMMEDIATELY RECOVER THE PLATFORM AND ASK FOR A TECHNICAL INTERVENTION

If diesel engine, or A.C.el. motor does not start, check that:

• electric line is live

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- switch on electric case cover is rotated on pos. 1
- the level of the fuel
- the charge of the batteries
- general key on main control desk is turned on pos. 1
- emergency stop push-buttons are re-set
- an additive is needed in the diesel oil in case of low temperatures
- all the el. switches are on ON position

If selfpropelling does not work, verify that:

- selecting key on ground control panel is rotated on "turntable" symbol
- all legs are not in pressure on the ground
- there is no oil leakage or damaged component

Cosa controllare se le manovre si effettuano con sobbalzi e non con moto uniforme; verificare che:

- nel caso delle prolunghe che queste siano ingrassate
- che a macchina tutta chiusa il livello olio nel serbatoio sia regolare
- se è stato aperto il circuito per una qualunque riparazione è necessario spurgare l'aria effettuando tutte le manovre fino a fine corsa per un paio di volte cominciando dagli stabilizzatori.

If aerial work movements do not work, verify that:

- control panel has been selected to the ground
- red lamp on control panel is off
- hydraulic oil level is regular
- turntable locking pin has been taken away
- one pin of the legs suppors is not insert

In case of vibrations or irregular movements, verify that:



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- telescopic boom sections are greased
- the chains of the booms are regularly tensed and hydraulic oil level is regular
- after a repair intervention, the presence of air is possible in the hydraulic system - in this case, it is recommended to make two complete movements sequences, to end stroke, starting from stabilizing legs

# 5.7 TRAILING

Platform trailing is not admitted, and so it is forbidden.

The machine has to move at low speed, not only because of its low levels of power, but also because of its high centre of gravity, its narrow support area and the lack of elastic suspensions.



# CHAP. 6° MAINTENANCE AND CHECK-UP

#### Foreword

It is recommended that the maintenance is carried out by personnel, which:

- is specifically prepared,
- knows the manual
- is authorized by the boss
- intervents only following the producer's guidelines

Any intervention has to be carried out by:

- a producer authorized workshop
- experienced personnel instructed by the producer.

Always ask the producer when complex interventions are needed.

# 6.1. ORDINARY MAINTENANCE - GENERAL INFORMATION

Advise for a correct maintenance, which guarantees long life performance:

- place the machine on plain ground.
- take the key off or attach a sign saying "do not start the engine"
- always clean the working area before opening the engine or the hydraulic system.
- do not open a circuit or an engine in presence of contaminating fluids
- never leave the engine or parts open longer than necessary for reparation and keep them safe from powder and rain
- only use lubrificants specificated by the producer
- keep track of any recommendation by the operators, in order to check any disorder, also to avoid more serious damage.
- Do not use the equipment in case it has not been repaired completely or all the safeties are not operational
- The personnel assigned to maintenance must know this manual and must wear protection clothes and devices



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- Do not allow reparations by personnel which has not been authorized by the producer.
- Do not use spare parts different from the original, in this way producer's responsibility decays.
- Do not use this equipment for different purposes, as who does it, becomes its producer.
- Do not apply mods to the machine (bigger cage, longer hand extension, more powerful engine, highest speed of work, etc.) because also in this case, who does it, becomes its producer with all the responsibility that follow.
- Respect the programmed repair terms and keep track of them on the register
- Keep track of any failure on the register and any reparation intervention

#### 6.2. HYDRAULIC OILS FEATURES

The oils used in this equipment are:

Hydraulic system	BP ENERGOL HLP – HM 46
Reducers/Bridges	FZG 85 W/90
Turntable/Frame Fat	AUTOGREASE MP
Arms fat	NILS NILEX EP2

Topping up using different oils is allows but not recommended.

It is suggested that you completely replace the oil with the one you are using for other machines because of saving matters, provided it has similar features. We do not give names of alternative products because of the constant name changing by other producers.

The features requested for an oil to be suitable are the following:Hydraulic systemISO - VG 46Reducers and bridgesISO - VG 11,0 ÷ 13,5



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# 6.3. DAILY CHECK

Before starting any intervention, set close the machine, engine off, disconnected from the power source and possibly clean.

# A DIRTY MACHINE DOES NOT ALLOW A CORRECT INSPECTION.

#### Check:

- 1. Absence of damage to the equipment due to transport; parts missing or damaged, oil leaks, damaged tyres, disconnected cables
- 2. The hydraulic oil level, which has to reach the middle of the optic signal when the machine is in transport position The engine oil level through the engine stick (see the engine manufacturer manual attached) and the fuel level through the indicator Fig. 6.1





 The hydraulic oil level in the tank must be half in the optical signal Fig 6.2 when the machine is completely closed (in transport conditions)



Fig. 6.2

- 4. The integrity of the arms extension chains, and their junction (cup spring, nuts and banking pins)
- 5. The interlock between stabilizers and arms. When the stabilizers are lifted from the ground, try to commute the key pos. 15 Fig. 3.5 to the turntable symbol and cage symbol and check that in both positions no manoeuvre of the arm can be executed. When the stabilizers are set to the ground, the machine has been levelled and the arms are not in transport position, try to commute the key pos. 15 Fig. 3.5 onto the stabilizer symbol and check that the stabilizers do not move



- 6. The area limiter works this way:
  - Set the stabilizers into the narrowest hole
  - Using the horizontal arm, on the engine side, unthread the extensions and check the extension is blocked when the area limiter activates; one or both the lights on the stabilizers will turn on. Check now that it is impossible to lower the arm, rotate and unthread.
  - Repeat the previous operation when the arm is taken off opposite to the engine and, when the lights on the stabilizers are on, check that the extension, the lowering and the rotation of the arm are blocked.
- 7. The emergency arrest buttons are positioned in every command position. By arming the emergency button, every machine movement has becomes disabled.

It is recommended not to start the machine before checking that the command devices are functioning.

If the machine is used rarely, the check must be done before the machine is started.



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# 6.4. WEEKLY CHECK

The cleaning must be done weekly also to better find liquids leakings or loosened tightening.

- The cleaning must be done at least weekly. When the diesel engine is running, check the hydraulic pressure level, by completely retiring one of the stabilizers and checking if this corresponds to the value shown in chapter 1
- Check the tracks tension. If they're inflected, it is recommended to put them under tension by using a greasing pump (6bar), as shown in Fig. 6.3



Fig. 6.4

- Check the level of the endothermal engine fumes and its noise level.
- Check the batteries and grease their positive pole. The poles must not present encrustations.
- Check the correct manual pump functioning (after having closed the piloting "exclusion wheel", as described in the chapter about emergency operations it is sufficient to use the pump some seconds without making any movement to check if the pressure increases during the operation.
- Check the instruction plates are legible and not damaged, in contrary case substitute them
- Check that the ground and cage commands are functioning. Using the controls the movement must be correct.
- Grease all the articulations arms, cylinders, stabilizers and the cage. Before applying the greasing pump, clean the greasers and then keep on greasing until the old grease comes out
- Execute all the checks as shown in the previous paragraph

Inform the responsible personnel about any failure encountered.

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# 6.5. QUARTERLY CHECK

The quarterly check must be done when the machine is clean and has to be registered. The operator is recommended to wear gloves, glasses, proper clothes and to have his hair protected.

Pay attention when using compressed air or water under high pressure and check no other people are in that area; it is better that only one person make the ordinary check. If the work has not been completed, leave a sign on the machine in order not to allow its usage.

When opening the hoods from the engine, the batteries and the hydraulic main circuit, be aware of this:

- The noise levels are changed and it is recommended to wear acoustic protections
- The batteries are not covered and so it is recommended not to allow flames or fires near them. It is also recommended to wear glasses
- The temperature in some parts may overcome the ordinary level, thus it is recommended not to touch any part without gloves

It is recommended to execute these operations:

- Check the inspection register to verify the completeness of the previous maintenance operations
- Daily execute all the maintenance operations.
- Grease the telescopic extensions of the arms using a brush
- lubricate chain for the boom extension with a brush (see paragraph 6.12 "maintenance"
- Check the state of the oil in the tank: it must be coloured in light yellow; it must not present foam or look milky because of the presence of water
- Verify the absence of oil leaks or damage to flexible pipes in the articulations of the arms or inside the frame (lift the machine on the stabilizers and look beneath the frame
- Check the oil levels and the amount of hours the thermal engine has been running; therefore execute all the maintenance operations or the needed replacements. Clean the edge of the caps in order not to let powder in
- Check the level of the electrolyte in the batteries
- Inspect the arms next to the pivots or the sliding pads, in order to verify the absence of damages in the joins, maybe caused by crashes or by unusual vibrations
- Put the tracks under tension using the greasing pump (see previous chapter)

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Check the output voltage from the generator on board. While the thermal engine is running, activate the generator using the selector on the control panel in the cage. Open the main command panel (fig 3.2) and measure the voltage between the binding clamps G1 and G2 (fig 6.5). The voltage must be 200V ±10%. If the voltage is higher or lower, set the number of rounds of the thermal engine

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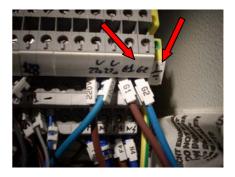


Fig. 6.5

• Using a dynamometrical wrench, check the bolts of the slewing (see the following table)

	SCREWING TORQUE TABLE (kgm)										
Screv	v type	Screw diameter									
ISO	DIN	M 10	M 12	M 14	M 16	<b>M 18</b>	M 20	M 22	M 24	M 27	<b>M 30</b>
8,8	8G	4	7	12	18	26	33	44	57	80	105
10,9	10K	6	8,5	15	22	32	41	53	69	100	127
12,9	12K	8	10	18	26	38	49	63	82	115	150

- Check the oil level in the reducer gear for the cage levelling by means of the special display Fig. 6.6. When the display is in horizontal position, the oil level has to be at the middle. If not refill by means of the dedicate cap (Fig. 6.6).
- Check the play between the reducer and the slewing; set the equipment in work position and execute the boom rotation manoeuvre. Check that when you leave the command, the rotation stops and does not produce strange plays. If you notice any play, it is necessary to set the reducer closer to the slewing. Check the oil level from the visor as shown in fig 6.7; the oil must be visible, if not, top up from the proper cap.

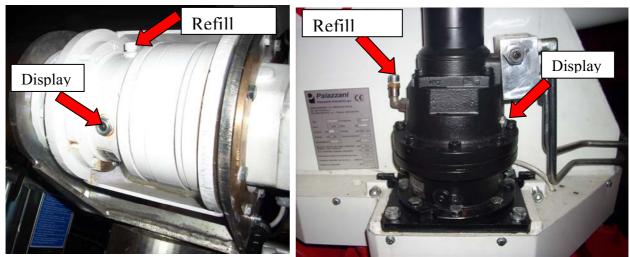


Fig. 6.6

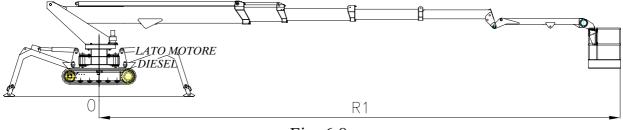
Fig. 6.7



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- Check the absence of leaks in the turntable reducer, otherwise top up.
- Execute a functioning test, paying attention to the safety devices and their working conditions.
- Check the microswitch is functioning correctly (stabilizer pivots, chains, turntable centering, resting arm)
- Check the correct functioning of the outreach limiting device in this way:
  - ▶ put stabilizers at the first hole (see Fig. 1.2) and, if provided, open the last boom of the stabilizer at max angle, pos. A Fig. 1.2. Note: not all the Palazzani machine has the possibility to set the extreme boom of the stabilizer.
  - level the equipment using the stabilizers on a plain ground by lifting the tracks 15/20cm from the ground. Take care the stabilizers are well pressed onto the ground, in order to reach the maximum machine performance.
  - $\succ$  load 200 kg into the cage
  - > open the jib and lower the arm in horizontal position
  - while the arm is in horizontal position, unthread the extensions on the engine side until you reach the locking of extension, rotation and arm lowering.
  - now check the distance from the slewing rotation centre to the edge of the cage (R1 of Fig. 6.8) is like the comparative value showed in the following table "max outreach for Ragni" with a max tolerance of 300 mm
  - retire the telescopic booms; rotate the arm to the other side opposite to the engine.
  - while the arm is in horizontal position, unthread the extensions on the engine side until you reach the locking of extension, rotation and arm lowering.
  - now check the distance from the slewing rotation centre to the edge of the cage (R2 of Fig. 6.9) is like the comparative value showed in the following table "max outreach for Ragni" with a max tolerance of 300 mm

# WARNING! If you noticed an excessive value regarding the extensions outreach, do not use the machine and ask Palazzani or an authorized workshop.



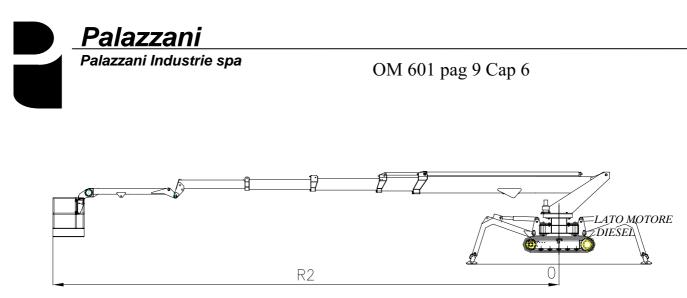


Fig. 6.9

#### Max outreach for Ragni Palazzani

Model	Outreach engine side R1	Outreach opposite engine side R2
	[m]	[m]
TSJ 23	10	9
TSJ 27	13.5	12.5
TSJ 34	11.3	12.6
TSJ 39	15	15.5
XTJ 32	15	15
XTJ 42	18	18
XTJ 48	18	18

#### Assembly advice:

The screws have to be lubricated with oil for engines.

In case of assembling with two or more screws, the screwing will have to be progressive and alternated until the proper torque is reached.

If you need to use plain washers, these are to be made of steel and have to be a minimum strenght of 80kg/mmq.

Inform the responsible personnel about any anomalies encountered.

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#### 6.6. SIX-MONTH MAINTENANCE

Besides the checks described previously, it is recommended to evaluate the situations and the environment in which the machine has been operating, above all if near the sea, in aggressive environments or if the equipment has been left outside all the time and thus subject to the weather.

- Check if the fluid in the hydraulic system has foam or is dark coloured
- Check the conditions of the extension chain and its usury (see paragraph 6.12) and grease it
- Check the tracks conditions (even if some steel wires are uncovered or damaged, the endurance of the machine is not committed)
- Check the solderings are not rusty
- Check the conditions of the protection paint and, if necessary, fix it, in order to prevent rust formation.
- Check the possible presence of paint blisters on the cylinders and on the arms and make sure it is not because of any structural subsidence
- Set the engine following the proper manual
- check the usury of the chromium plated stems of the cylinders, especially if near the sea
- Once the machine is parked and the engine is not running, check the stabilizers in search of any subsidence; subsidences are not accepted for these cylinders and the replacement must be instantaneous
- Check the signs on the command panels, the instruction plates and the emergency signs and replace the ones damaged
- refill the slewring reducer and the tracks engines
- Clean the arm and stabilizers microswitches
- grease the stabilizers articulation springs.

Inform the responsible personnel of any problem encountered.



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# 6.7. ANNUAL MAINTENANCE

Besides the checks described in the previous section, check the following: - the chains tension and if necessary set them by acting on the bolts. Fig. 6.10 and 6.11 (for any further detail see paragraph 6.12). Setting the arm in horizontal position, pull out 10 cm and make it go back in. Loosen the upper bolts until the chain is loose and then screw until the chain becomes a little tight.

- Grease the chains and check there is no rust
- Check the plays in the manoeuvres: the arm in the turntable, the cage at the end of the arm, stabilizers over the support plan and between them, turntable.
- Check that the slewing screws are well tightened.
- Check the cage support and the levelling system bearings usury
- Replace the engine oil filters if not done previously following the producer's recommendations.
- Replace the flexible damaged pipes.



Fig. 6.10



Inform the responsible personnel of any problem encountered.



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#### 6.8. FOUR-YEAR MAINTENANCE

Besides the recommendations in the previous paragraph, check the extension chains and if damaged, prepare them for replacement.

- hydraulic oil replacement
- cylinders resistance and valves check. Put the cylinders under pressure and, after at least 1 hour, check that no subsidence has taken place
- check the cylinders stems surface
- flexible pipes and articulations replacement
- check the command levers on the manoeuvres panel
- check the articulations pivots iron rings
- replace the turntable rotation reducer oil
- Filters replacement (cartridge)
- Dismount and check the chains, particularly the booms connections and the not accessible areas. Substitute the defeated parts if any.

We remind you that these checks are just recommendations.

The operator must inform and the maintenance operator must provide for lubrication, refillments, replacements etc.

Inform the responsible personnel of any problem encountered

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#### 6.9. EXTRAORDINARY MAINTENANCE

As described above, in hostile work conditions it may be necessary to anticipate the programmed maintenance operations. For example, the saltiness damages paint, chains, cylinders stems; the wind, when carrying sand, may damage the hydraulic oil or the command panels. It is also recommended not to leave the machine outside for a long time: water may penetrate and damage electric equipment and cause rust formation.

In other situations too the agent must intervent immediately: pump replacement, perforated tyres, damage of flexible pipes, damage of batteries, solderings...

In case of battery damage we recommend the maximum care because the electrolyte is dangerous for people and for the environment.

Wear glasses to avoid squirts into the eyes and wear glasses to avoid skin damage.

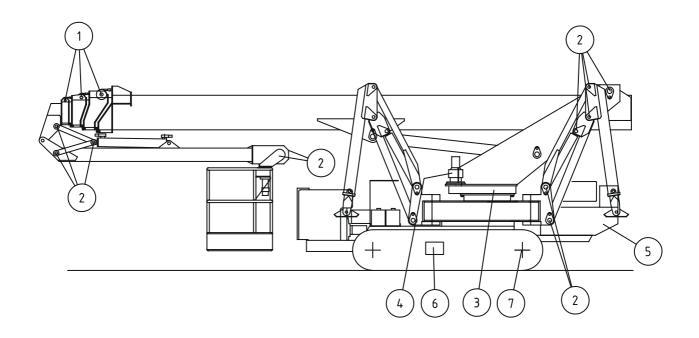
Use these protections also when treating oil. The oil acts as human fat solvent and a constant exposition to it may cause dermatitis or serious irritation. In case of any contact with the eyes rinse copiously with water and if the irritation persists, contact a doctor.

Moreover, before manipulating these products, read carefully the producer's recommendations about its usage.

Before soldering, disconnect both the battery poles. Connect the mass onto the element where you have to execute the soldering and <u>never</u> onto a hydraulic circuit element.



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# LUBRICATION SCHEME

1)	SLIDING PADS GREASING				
	Lubricant	NILS NILEX EP2			
2)	VARIOUS PIVOTS	S GREASING AUTO GREASE MP			
3)	SLEWRING GREA				
	Lubricant	AUTO GREASE MP			
4)	ROTATION REDU	JCER PONTIAX FZG 85W/90			
5)	HYDRAULIC OIL Lubricant	TANK BP ENERGOL HLP – HM 46			
6)		TING TRACKS UNDER TENSION AUTO GREASE MP			
7)	TRACKS ENGINE Lubricant	S Pontiax FZG 85W/90			



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# 6.10. HYDRAULIC CIRCUIT CHECK

These are the recommended checks for the hydraulic circuit.

- Oil in the tank: through the level visually
- Diesel engine pumps efficiency: when the engine is running, commute the command key to "stabilizers", activate a stabilizer until it is completely retired and check that the pressure is within the maximum value shown in chapter 1. When the stabilizers are under pressure, start the generator and check the voltage is 220V + 10%.
- Electric engine pump efficiency. When the engine is running, turn the key onto "stabilizers" and move a stabilizer until it's completely retired; then check the pressure value is within the maximum shown in chapter 1.
- Filters efficiency. Open the engine hood and after a few minutes (10 minutes during the cold season) check the indicators are not on the red.
- Maximum pressure valves. Using the thermal engine and moving the arms until they're completely retired, the manometer should show the maximum value as shown in chap 1.
- Flexible pipes: check if they're not damaged or blistered near the hose fitting, damages in the metalic/textil stranded wire or permanent foldings. The black surface film spealing is not dangerous for the pipe
- Cylinders locking valves. Put the stabilizer cylinders under pressure, after lifting the lifting cylinder, jib open (and then closed): mark the stems with a plaster and measure the distance from a point (as the flange thread) to the plaster. The subsidence allowed is none within 15 minutes, 1mm after an hour.
- Oil leaks: Maximum allowed is few on the stems and on the spiral pipes.



#### 6.11. GENERAL ELECTRIC SYSTEM AND BATTERY RECHARGER CHECK

The machine mounts a rectifier for the battery charge, set in the general electric frame (box1).

This rectifier is automatically fed by the plug (both 220 V or 380 V) for the equipment starting.

Also the diesel engine contributes to the battery charge, when it is running.

Thus, it is necessary to keep the electrolyte level in the batteries checked and keep the positive poles greased.

We've seen that it is fundamental to check the safety devices correct functioning, many of which are electric and may simulate manoeuvre mistakes.

Often, the electric plant check corresponds to the searching for a failure, given that these parts are the most exposed to injuries due to rain, powder, vibrations etc.

The maintenance employee has to be specifically instructed, but above all precise and respectful of the electric parts and their connections.

We remind you some important things.

- The microswitches, the relays, the diode valves and the condensers may be similar but connected each other in different ways. We recommend to replace them with parts that has the same brand and the same code; try to remember the colour of the cables or the terminal numbers not to make connections mistakes
- Do not take off more than one relay at a time, check it and if necessary replace it with an equal one
- The microswitches have a symbol representing a little arrow inside a circle or this **P**. They're just in case of emergency and cannot be replaced with other similar parts which do not have this symbol
- Be careful with NA or NC connections
- Always re-connect the grounding cables and the equipotentiality cables
- The emergency stop buttons must be repaired immediately when a failure is encountered.
- Follow carefully the scheme and do not operate any modification that may damage or commit the entire machine functioning.
- After any intervention check all the machine emergency functions.

# **N.B.** The access to the inside of the electric plant wrappings is recommended to be executed by instructed personnel only.

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# 6.12. CHAIN CHECK

The chain for the boom extension are Fleyer type and for safety factor are fitted in couple with separate link and a device that assure the approximately equal tension on the chains.

The chains need of periodical maintenance.

#### Maintenance

For proper operation of the chains and moving parts must always be maintain appropriate lubrication conditions.

To lubricate chains, develop your arm horizontally, making sure to support end with a crane with adequate capacity (see Fig. 6.12). In this way the chains Extension are available for maintenance and inspections.



Fig. 6.12

The lubricant has two main tasks: Action anti-friction, protective action.

The lubricant is usually applied brushstrokes on the surface of the plates, it must penetrate inside the plates to reach the area of wear between the pin and hole plates.

If on the chain there are abrasive particles (e.g. sand), before oiling must be carefully cleaned by washing with appropriate solvent. Oiling the chains with dirty indeed push the abrasive material in the joints, triggering phenomena of abrasive wear.

The type of lubricant to use is a normal mineral oil with viscosity about ISO VG 46 - 460. Keep in mind that more viscous oils are suitable for ambient temperatures lower.

An oil very fluid, penetrates in the joints better, but resists less, compared with more viscous lubricants. A compound very viscous contrast, has difficulties to penetrate the joints and thus may not allow the lubricant effect desired.

Perform lubrication every 200 hours or every 12 weeks

#### **Check**

For each intervention lubrication must be recorded, if necessary, the chain tensioning system and check for abnormalities of alignment between the chain and pulley system attack. The misalignments are very dangerous because they can induce high Overstressing the chains.



#### Check for wear elongation

To control the elongation due to wear is necessary to establish a registration form. Since probably will not wear the uniform along the entire length, the measure must be made for features that are appropriately identified. (Break the chain length in 5 sections) Should be recognized that the original measure serves as a reference for subsequent ones and should be kept in mind that all subsequent measurements must be made on the same traits.

After a few measures you can identify which traits are more subject to the phenomenon of wear, and then subsequent measurements can be restricted only to these traits. The measurement can be made or slide gauge long enough or line graph. The reference may be either the head of the pins or the profile of the plate. The maximum elongation is conservatively set at 2%.

#### Check wear plates Profile

After identifying the length of chain where this phenomenon is more evident, with a gauge should be recognized the actual height of the plate eyelet and compared with the initial one.

They set the limit on the maximum acceptable wear (see Fig. 6.13):

Wear on one side $[(H - H1) / H] \ge 100 < 2\%$ Wear on two side $[(H - H2) / H2] \ge 100 < 3.5\%$ 

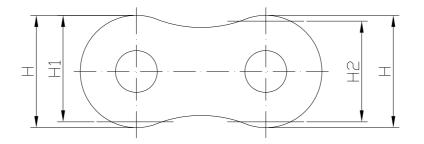


Fig. 6.213

The high specific pressures between the plate and pulleys can cause plates, as well as wear, even consummation of the material on the edge of the plate that can lead to blocked joints. If you encounter locked joints, the chain must be replaced.



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Wear on the side chain

This wear is caused by improper interaction with the chain pulleys or guide elements side.

If it is found that consumption over the heads of pins over 25% of the projection of rewriting or on the outside of the plate more than 20% of the thickness (see Fig. 6.14), and the chain must be replaced before applying the new , must be sought the cause of this malfunction.

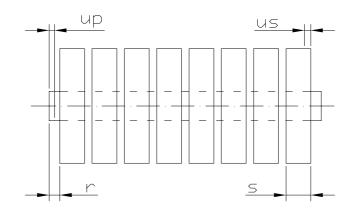


Fig. 6.14

Consumption rate head pin up / r x 100 < 25%Consumption percentage edge plate us / s x 100 < 20%

These checks should be performed every 3 months.

After four years of the chains must be dismantled and inspected in the attacks on the arm and in areas not normally accessible and, if damaged, replace.



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# 6.13. TRACKS CHECK

If a track is loose or tends to come off, it is necessary to tighten it.

In order to do this it is necessary to take off the two plates which are set on the external side of the base (fig.6.15) using a greasing pump, pump the grease in until the tanks are full.

This operation is even easier if executed when the tracks are lifted from the ground.



Fig. 6.15



# 6.14 TERMS FOR THE PRODUCER'S CHECKS

In order to guarantee a better performance to the user, it is recommended to have the equipment checked at Palazzani Industrie spa or at one of the authorized workshops within thirty months from the purchase or the last check.

During this check the machine functioning, its safety, its booms, chains and the rest of its parts are tested. A test certificate will be released.

Whether the check shows the necessity of a part to be replaced or fixed, the estimated cost of the operation will be communicated to the user.

If the machine has not been tested in 4 years from its purchase or from the last check, the guarantee will be no more valuable.



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# CAP. 7° SETTINGS

Some settings are necessary both to keep track of some relevant temperature gaps in comparison to the first calibration and because of the different work conditions in matter of usable space.

CAGE ROTATION: if the cage rotates too slowly or it does not rotate at all, set the two valves opening as shown in fig 7.1.

Mount it all again and check the correct cage rotation speed.

Rimontare il tutto e verificare la corretta velocità di rotazione della navicella.



Fig. 7.1

EXTENSION CHAINS: if the extension chains are loose, you must screw the auto-locking bolt (6.9) without using further extensions, until they're tight. Straighten the chains (6.10).



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JIB ARM: if maneuver is not available, specially after a long period of inactivity, it is necessary to set the locking valves by acting as shown in fig 7.2 and 7.3; Take off the valves cap and then rotate the grub screw by using a key. By rotating counter-clockwise, the valve opens and the maneuver is speeded up; if rotating clockwise the maneuver is slowed down.

**Warning:** if the jib cannot be lifted, it is necessary to loosen the valve set on the chromed stem side; if the jib cannot be lowered down, use the other valve.

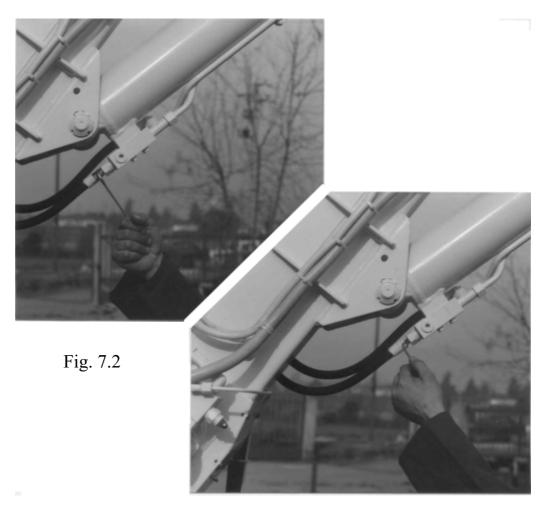


Fig. 7.3

LIFTING ARM: in case of hard vibrations when the oil is already hot, while moving the boom, it is recommended to intervent on the overcenter valve mounted on the lifting cylinder bottom.

- screw by a 1/8 round (fig. 7.4)



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Fig. 7.4

TURNTABLE ROTATION: If the turntable rotates vibrating or jumping, act on the locking valve (fig 7.5) as shown in the lifting boom paragraph.



Fig. 7.5

STABILIZERS: the stabilizer setting can be chosen in function of the work area. Their regulation concerns their position in respect to the frame.

Fig. 7.6 shows three work holes.

The rest position does not allow using the arm and it is thus to be used only for



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transporting in narrow spaces.

The other four possibilities are all usable (the most external hole in the frame limits consistently the work area and thus it is to be used when the work area is narrow). It is obvious that if the positions chose are symmetrical the machine will operate at the same distance in both sides.

Forgetting to insert a locking pivot does not allow to use the boom



Fig. 7.6



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# **CHAP 8 PLATFORM ASSIGNEMNT**

It is remembered that in case of a next sale, the seller has the responsability of the manufacturer, towards the new owner, if he has modified the platform.

Therefore, the platform must be delivered in its original execution and in a perfect efficiency, as regards: safety devices, control systems and structures integrity.

All warning and directions paltes must be readables perfectly and CE Mark must be evidenced.

Being an integral part of the machine, this Operation and Maintenance Manual and the Conformity Declaration must follow the platform.

The seller must also make a training to the personnel of the new owner, about use and maintenance of the platform.



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# **CHAP. 9 PLATFORM DEMOLITION**

Platform is essentially steel made and, therefore, it can be almost totally breaked into iron scraps.

Nevertheless, some components are classified toxic-noxious waste and special waste and they must be treated by specialized companies.

Toxic-noxious waste:	batteries
Special waste:	hose, fiberglass, el. wires and oil of: hydraulic system, engine, reducer-gears, and differential gear group



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# **CHAP. 10 TRAINING COURSES**

Use and maintenance of Ragno, platforms require personnel specifically informed about the machine functions, its safety devices and the manoeuvres in emergency.

For this reason, users are invited to partecipate to the one-day training courses organized by Palazzani Industrie S.p.A. and its Distributors and explaining: basic rules for use, periodical maintenance, selfpropelling and stabilizing manoeuvres in critical conditions, interventions in emergency, etc.



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### CHAP. 11 MAINTENANCE REGISTER

The register is issued by Palazzani Industrie S.p.A. to the owner of Ragno, in accordance with encl. I of the Directive 98/37/CEE and following modifications.

#### DIRECTIONS FOR PRESERVATION

This register is an integral part of the Operation Manual and it must follow the platform during its life, till to its final demolition.

#### DIRECTIONS FOR FILLING IN

Following directions are given in accordance with the Directive ruling at the moment of the sale of the platform. New rules can modify the user's obligations.

Following the schemes of the register, all the events concerning the life of the platform must be annotated:

- \* change of property
- \* replacement of engine, gear groups, structural elemets, safety devices and their components

important breakdowns and repairs



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#### DELIVERY OF RAGNO ...... TO THE FIRST OWNER

#### FOLLOWING CHANGE OF PROPERTY

On ..... the property of Ragno ..... is transferred to: .... It is certified that, under this date, technical, dimensional and working characteristics of the platform are exactly corresponding to ones described by the operational manual and that eventual modifications have been annotated on this register.

For the Seller

# FOLLOWING CHANGE OF PROPERTY

On the property of Rag	no is transferred to:
	imensional and working characteristics of the escribed by the operational manual and that

For the Seller



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#### **REPLACEMENT OF DIESEL ENGINE / ELECTRIC MOTOR**

••••
••••

responsabile fo the replacement

.....

#### **REPLACEMENT OF DIESEL ENGINE / ELECTRIC MOTOR**

Date
Manufacturer
kW
replaced with the engine / motor
Serial Nr.
Manufacturer
kW
cause of replacement:
responsabile fo the replacement

.....



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# **REPLACEMENT OF GEAR GROUPS**

Date			
Description of the gear group			
Manufacturer			
Delivered by			
Cause of the replacement			
• • • • • • • • • • • • • • • • • • • •	•••••	• • • • • • • • • • • • • • • • • • • •	• • • • • • • • • • • • • • • • • • • •

#### **REPLACEMENT OF GEAR GROUPS**

Date			
Description of the gear grou	1		
Manufacturer			
Delivered by			
Cause of the replacement			
•••••••••••••••••••••••••••••••••••••••	••••••••••••••••••••••	•••••	•••••



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#### **REPLACEMENT OF STRUCTURAL ELEMENTS**

Date			
Description of the material			
Delivered by			
Cause of the replacement			
	•••••	• • • • • • • • • • • • • • • • • • • •	•••••

# **REPLACEMENT OF STRUCTURAL ELEMENTS**

Date		
Description of the material		
Manufacturer		
Delivered by	 	 
Cause of the replacement		
	 •••••	 • • • • • • • • • • • • • • • • • • •



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# **REPLACEMENT OF SAFETY SYSTEM AND ITS COMPONENTS**

Date			
Description of the material			
Manufacturer			
Delivered by	 	 	
Cause of the replacement			

#### **REPLACEMENT OF SAFETY SYSTEM AND ITS COMPONENTS**

Date			
Description of the material			
Manufacturer			
Delivered by		 	
Cause of the replacement			
	••••••••••••••••	 ••••••	



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# PERIODICAL CHECK-UP

User is obligated to follow the check-up and maintenance program described by the operational manual of the platform.

<u>ITEM</u>	DATE	DESCRIPTION OF THE INTERVENTION	<u>SIGNATURE</u>
RAGNO	MOD	SERIAL NR. P	Γ



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# **Palift** - DIVISION

# RAGNO XTJ 32/C

VERSIONE CINGOLATA-CRAWLER VERSION EXECUTION SUR CHENILLE

> CATALOGO PARTI DI RICAMBIO

CATALOGUE RECHANGES

SPARE PARTS LIST

NR 081 A 10



**OPERATION MANUAL OM 801** 

RAGNO MOD.

SERIAL NR. PT .....

# MEMORANDUM FOR THE MAINTENANCE SERVICE

When you ask for spare parts, always specify to the manufacturer the platform model and serial number

<u>Required spare must be located in this book and corresponding table and code</u> <u>numbers must be communicated</u>

Use original spares exclusively and not similar products. It is remembered that the manufacturer responsability can be reduced, or cancelled when the user does not follow the instructions given by the operational manual, or use spare parts not originals or without warranty

Be sure to execute the intervention in a correct way, otherwise apply to Palazzani after sale service

During your intervention, follow all safety rules and use individual protections

No servicing intervention is allowed with persons in aerial cage and with platform in action: firstly, lower the booms, place the platform in a safe position, stop the engine and detach the el.plug

<u>Never modify the original setting values of the platform: engine r.p.m., hydraulic pressures, speeds, valves regulations and throttlers, to increase the performances</u>

Do not change the use for which the platform has been designed



#### WARNING FOR THE RESPONSIBLE TO EXTRAORDINARY REPARATION AND/OR MAINTENANCE

- The complex interventions of reparation must be carried out by Palazzani Industrie or authorised workshops technical personnel
- After 30 months and after no more than 4 years, the machine must be checked by Palazzani personnel at customer's site, or at Manufacturer's site in case of a most general control, with the appropriate procedure and with registration on the intervention report
- Not important interventions can be carried out by the personnel, authorised by the customer, who have the capacities, instruments and knowledge of the Manufacturers instructions and schemes

In this personal occasion we remind to:

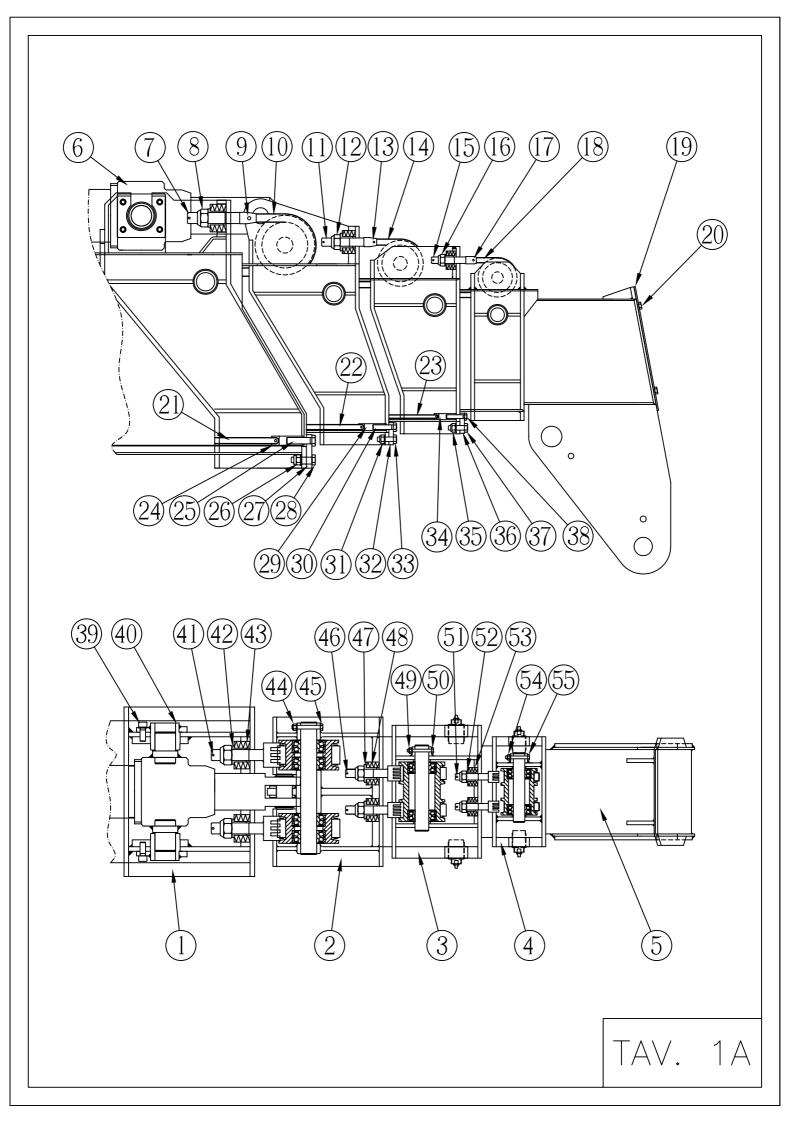
- Verify that the component which must be substituted is conforming to the original one (in case it has been bought from Palazzani or on site)
- Detach the components one by one and substitute it before proceeding with any further detaching (this regards most of all relay, diodes, breakers, end of stroke, electrovalves connectors, flex pipes).
- Memorise the connections before detach the faulty components, in order to reconnect them to the new piece correctly (the diodes have an horizontal line on the cover to indicate the correct position), put insulating sticker on the electrovalves connectors as not to invert their position during the re-connection
- <u>Never forget to make a complete functioning test</u> with particular regards to the safety devices and to the circuit where the components substitution have taken place, <u>before</u> <u>start working with the machine</u>

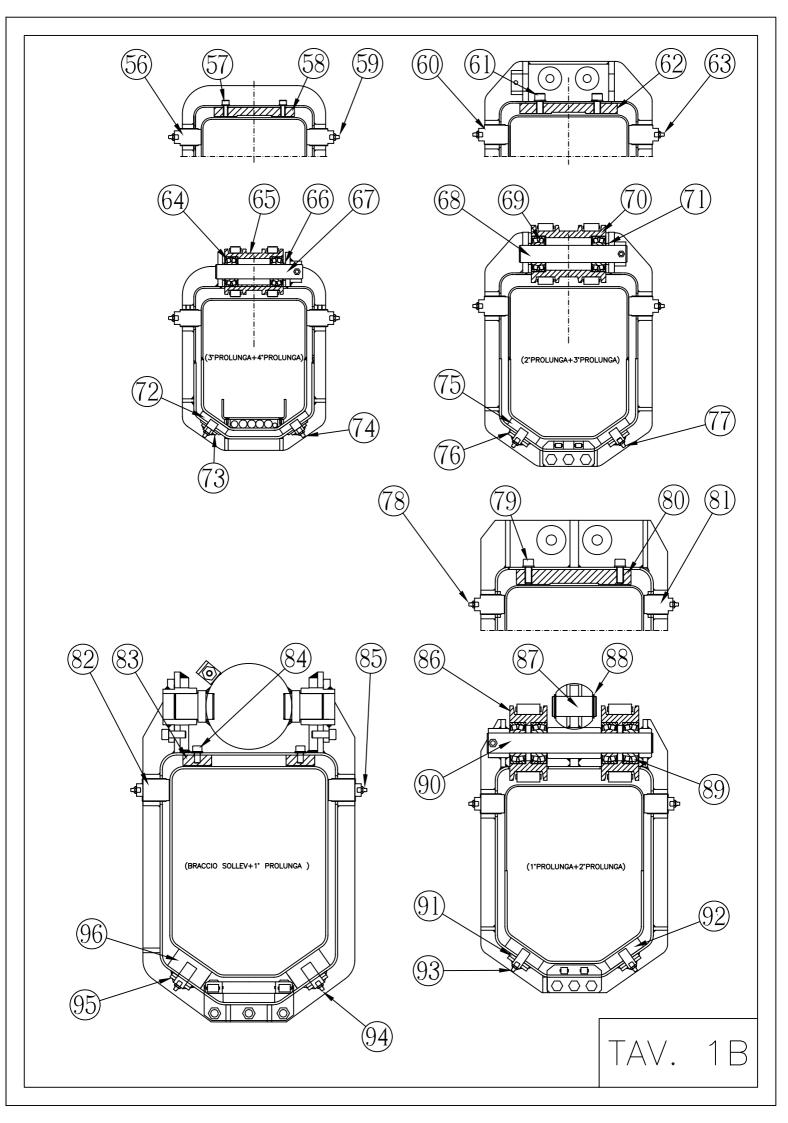
GRUPPO BRACCI			CCI	BOOM SET		GROU	GROUP DE BRAS	
PART.	CODICE	QUANT.	DENOMINAZ	ZIONE	DESCRIPTION	I D	ESIGNATION	
1	05.14.1762	1	BRACCIO SOLLEV	SOLLEVAMENTO LIFTING BOOM		BRAS	S LEVAGE	
2	05.14.1761	1	PRIMO BRACCIO		1° BOOM	1° BR	RAS	
3	05.14.1760	1	SECONDO BRACC	CIO	2° BOOM	2° BR	RAS	
4	05.14.1759	1	TERZO BRACCIO		3° BOOM	3° BR	RAS	
5	05.14.1758	1	QUARTO BRACCIO	C	4° BOOM	4° BR	RAS	
6	01.01.0609	1	CILINDRO DI SFILO	0	EXTENSION RAM	/ VERI TELE	N DE SCOPAGE	
7	08.14.3072	2	TIRANTE CATENA		ROD	TIRA	NT	
8	19.02.0021	2	DADO		NUT	ECRO	JU	
9	07.14.1062	2	PERNO		PIN	AXE		
10	55.28.0545		CATENA LH 1266	i	CHAIN	CHAI	NE	
11	08.14.1902	2	TIRANTE CATENA		ROD	TIRA	NT	
12	19.02.0018	2	DADO		NUT	ECRO	ECROU	
13	55.28.0098	2	PERNO		PIN	AXE		
14	55.28.0046		CATENA UF 1588	3	CHAIN	CHAI	NE	
15	08.14.2504	2	TIRANTE CATENA		ROD	TIRA	NT	
16	19.02.0016	2	DADO		NUT	ECRO	JU	
17	55.28.0571	2	PERNO		PIN	AXE		
18	55.28.0563		CATENA UF 1266	5	CHAIN	CHAI	NE	
19	08.14.3076	1	COPERCHIO		LID	COU	VERCLE	
20	19.01.0003	4	VITE		BOLT	VIS		
21	55.28.0056		CATENA UF1566		CHAIN	CHAI	NE	
22	55.28.0564		CATENA UF1244		CHAIN	CHAI	NE	
23	55.28.0050		CATENA UF 944	4 CHAIN CHAIN		NE		
24	08.14.3037	1	TIRANTE CATENA		ROD	TIRA	NT	
	, Pala	ZZá	ani		PaLIFT		TAV N° 1	
			ustrie spa	•	DIVISION		XTJ 32	

GRUPPO BRACCI			BOOM	BOOM SET		Rouf	P DE BRAS		
PART.	CODICE	QUANT.	DENON	MINAZIONE	DESCRIPTION		DE	SIGNATION	
25	19.01.0073	2	VITE		BOLT		VIS		
26	19.02.0025	3	DADO		NUT		ECRC	U	
27	08.14.3056	1	PIATTO TIRA	NTE CATENA	SUPPORT		SUPP	ORT	
28	19.01.0053	3	VITE		BOLT		VIS		
29	08.14.3089	1	TIRANTE CA	TENA	ROD		TIRAN	ΙT	
30	19.01.0037	2	VITE		BOLT		VIS		
31	19.02.0024	3	DADO		NUT		ECRC	U	
32	08.14.1916	1	PIATTO TIRA	NTE CATENA	SUPPORT		SUPP	ORT	
33	19.01.0035	3	VITE		BOLT		VIS		
34	08.14.2335	1	TIRANTE CA	TENA	ROD		TIRAN	ΙT	
35	19.02.0024	3	DADO		NUT		ECROU		
36	08.14.3035	1	PIATTO TIRA	PIATTO TIRANTE CATENA		SUPPORT		SUPPORT	
37	19.01.0035	3	VITE	VITE		BOLT			
38	19.01.0266	2	VITE		BOLT		VIS		
39	08.14.3073	4	VITE		BOLT		VIS		
40	08.14.3073	2	FLANGIA		FLANGE		BRIDE	Ξ	
41	55.10.0021	2	COPIGLIA		SPLIT PIN		GOUF	PILLE	
42	08.14.3082	2	BOCCOLA		BUSH		DOUII	_LE	
43	55.13.0029	14	MOLLA A TAZ	ZZA	SPRING		RESS	ORT	
44	19.02.0022	1	DADO		NUT		ECRC	U	
45	19.01.0012	1	VITE		BOLT		VIS		
46	55.10.0032	2	COPIGLIA		SPLIT PIN		GOUF	PILLE	
47	08.14.1906	2	BOCCOLA	CCOLA			DOUII	_LE	
48	55.13.0014	14	MOLLA A TAZ	ZZA	SPRING		RESS	ORT	
	Pala	ZZa	ani		PaLIF			TAV N° 1	
			ustrie spa		DIVISION			XTJ 32	

	GRUPPC	BRAG		BOOM	SET	GROU	P DE BRAS
PART.	CODICE	QUANT.	DENOMI	NAZIONE	DESCRIPTIO	N DI	ESIGNATION
49	19.02.0022	1	DADO		NUT	ECRO	JU
50	19.01.0010	1	VITE		BOLT	VIS	
51	55.10.0032	2	COPIGLIA		SPLIT PIN	GOU	PILLE
52	08.14.2503	2	BOCCOLA		BUSH	DOUI	LLE
53	55.13.0030	14	MOLLA A TAZZ	A	SPRING	RESS	SORT
54	19.02.0022	1	DADO		NUT	ECRO	JU
55	19.010009	1	VITE		BOLT	VIS	
56	08.14.3030	2	PATTINO		LINING	GOU	JON
57	19.01.0239	2	VITE		BOLT	VIS	
58	08.14.2566	1	PATTINO		LINING	GOU	JON
59	55.14.0002	2	INGRASSATOR	E	GREASE NIPPLE	E GRAI	SSEUR
60	08.14.3034	2	PATTINO		LINING	GOU	JON
61	19.01.0264	2	VITE		BOLT	VIS	
62	08.14.3077	1	PATTINO		LINING	GOU	JON
63	55.14.0002	2	INGRASSATOR	E	GREASE NIPPLE	E GRAI	SSEUR
64	49.02.0072	2	CUSCINETTO		BALL BEARING	ROUI	LEMENT
65	08.14.3121	1	RULLO		ROLLER	ROUI	LEAU
66	08.14.1911	2	DISTANZIALE		SPACER	ENTF	RETOISE
67	07.14.0933	1	PERNO		PIN	AXE	
68	07.14.0932	1	PERNO		PIN	AXE	
69	49.02.0070	2	CUSCINETTO		BALL BEARING	ROUI	LEMENT
70	08.14.3122	1	RULLO		ROLLER	ROUI	LEAU
71	08.14.1910	2	DISTANZIALE		SPACER	ENTF	RETOISE
72	08.14.3119	2	PATTINO		LINING	GOU	JON
	. Pala	ZZa	ani		PaLIFT		TAV N° 1
		-	ustrie spa		DIVISION		XTJ 32

	GRUPPO	BRAC	CI	BOOM	I SET	C	GROUP DE BRAS		
PART.	CODICE	OUANT.	DEN	OMINAZIONE	DESCRIPT	TION	DE	SIGNATION	
73	08.14.2577	2	PIATTO FE	RMAPATTINO	SUPPORT		SUPP	ORT	
74	55.14.0005	2	INGRASSA	TORE	GREASE NIP	GREASE NIPPLE		SSEUR	
75	08.14.2333	2	PATTINO		LINING		GOUJ	ON	
76	08.14.1972	2	PIATTO FE	RMAPATTINO	SUPPORT		SUPP	ORT	
77	55.14.0005	2	INGRASSA	TORE	GREASE NIP	PLE	GRAIS	SSEUR	
78	55.14.0002	2	INGRASSA	TORE	GREASE NIP	PLE	GRAIS	SSEUR	
79	19.01.0264	2	VITE		BOLT		VIS		
80	08.14.3078	1	PATTINO		LINING		GOUJ	ON	
81	08.14.3034	2	PATTINO		LINING		GOUJ	ON	
82	08.14.3051	2	PATTINO		LINING		GOUJ	ON	
83	08.14.3080	2	PATTINO		LINING		GOUJ	ON	
84	19.01.0252	4	VITE		BOLT		VIS		
85	55.01.0002	2	INGRASSA	TORE	GREASE NIP	PLE	GRAI	SSEUR	
86	08.14.3079	2	RULLO		ROLLER		ROUL	EAU	
87	07.14.1134	1	PERNO		PIN		AXE		
88	55.07.0071	2	SEEGER		CIRCLIP		ANNE RETE	AU DE NUE	
89	49.02.0071	4	CUSCINET	ТО	BALL BEARIN	١G	ROUL	EMENT	
90	07.14.1131	1	PERNO		PIN		AXE		
91	08.14.3025	2	PIATTO FE	RMAPATTINO	SUPPORT		SUPP	ORT	
92	08.14.3020	2	PATTINO		LINING		GOUJ	ON	
93	55.14.0005	2	INGRASSA	TORE	GREASE NIP	PLE	GRAIS	SSEUR	
94	55.14.0005	2	INGRASSA	TORE	GREASE NIP	PLE	GRAIS	SSEUR	
95	08.141921	2	PIATTO FE	RMAPATTINO	SUPPORT		SUPP	ORT	
96	08.14.3081	2	PATTINO		LINING		GOUJ	ON	
	. Pala	772	ani		PaLIF	T		TAV Nº 1	
			a III ustrie spa				·	XTJ 32	



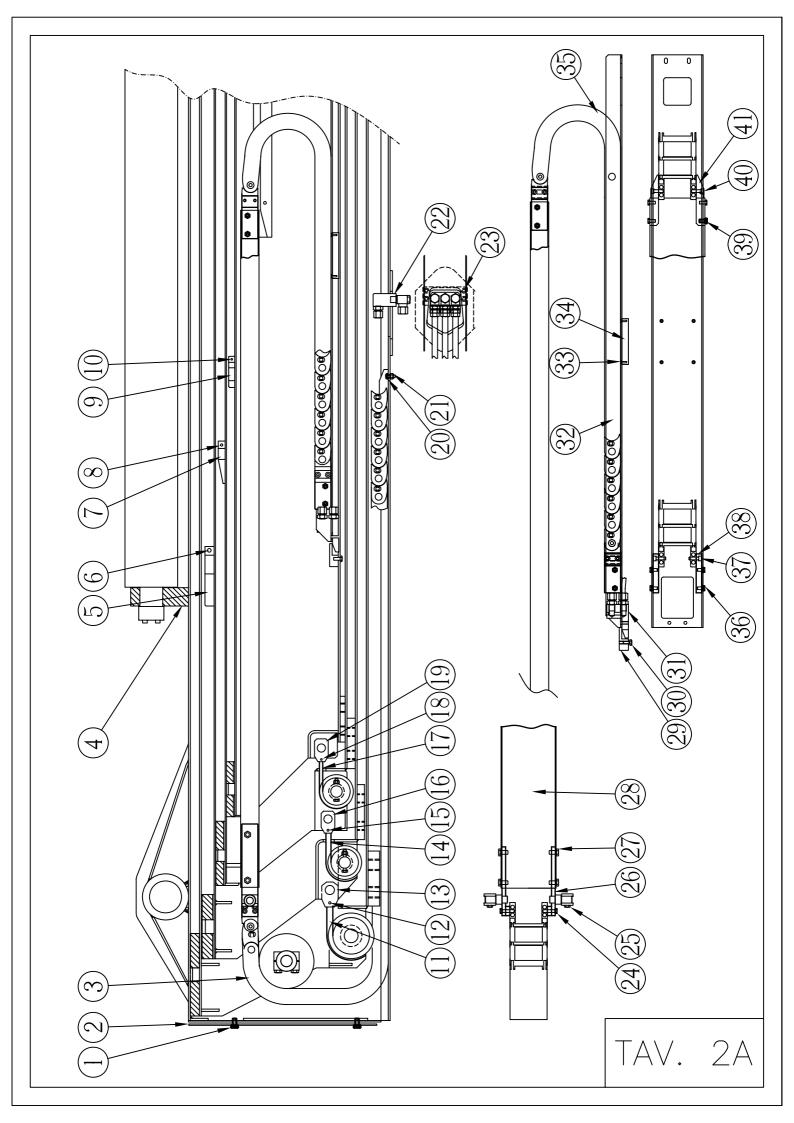


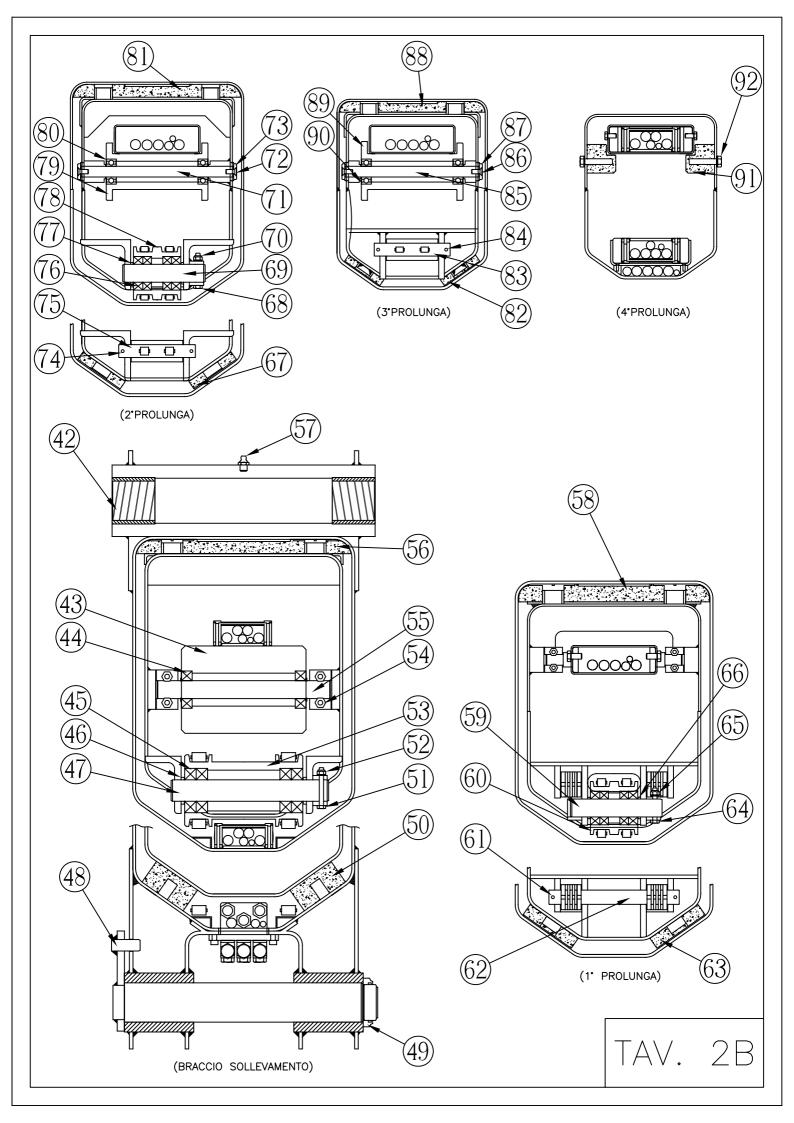
	GRUPPO	BRAG		BOOM	SET	G	<b>GROUP DE BRAS</b>		
PART.	CODICE	QUANT.	DENO	MINAZIONE	DESCRIPT	ION	DE	SIGNATION	
1	19.01.0003	6	VITE		BOLT		VIS		
2	08.14.3085	1	COPERCHIC	C	COVER		COUVI	ERCLE	
3	55.28.0694		CATENARIA	POSTERIORE	CHAIN		CHAIN	E	
4	08.14.3096	1	SUPPORTO	FONDELLO	SUPPORT		SUPPO	ORT	
5	08.14.3091	1	TIRANTE CA	ATENA	ROD		TIRAN	Т	
6	07.14.1062	2	PERNO		PIN		AXE		
7	08.14.3083	1	TIRANTE CA	ATENA	ROD		TIRAN	Т	
8	55.28.0098	2	PERNO		PIN		AXE		
9	08.14.3123	1	TIRANTE CA	ATENA	ROD		TIRAN	Т	
10	55.28.0571	2	PERNO		PIN		AXE		
11	55.28.0056		CATENA U	F1288	CHAIN		CHAIN	E	
12	55.28.0102	2	PERNO		PIN		AXE		
13	08.14.3022	2	TIRANTE CA	ATENA	ROD		TIRAN	Т	
14	55.28.0564		CATENA U	F1288	CHAIN		CHAIN	E	
15	55.28.0572	2	PERNO		PIN		AXE		
16	08.14.3018	1	TIRANTE CA	ATENA	ROD		TIRAN	Т	
17	55.28.0050	2	CATENA U	F1288	CHAIN		CHAIN	E	
18	55.28.0100	2	PERNO		PIN		AXE		
19	08.14.2321	1	TIRANTE CA	ATENA	ROD		TIRAN	Т	
20	19.01.0003	2	VITE		BOLT		VIS		
21	19.02.0022	2	DADO		NUT		ECRO	J	
22	08.14.3055	1	MASSELLO	TUBI IDRAULICI	CONNECTION	1	RACCO	ORD	
23	19.01.0004	4	VITE		BOLT		VIS		
24	19.01.0005	4	VITE		BOLT		VIS		
	Pala	ZZa	ani		PaLIF <sup>-</sup>	Г		TAV N° 2	
			ustrie spa		DIVISION			XTJ 32	

	GRUPPC	BRAG	CCI	BOOMS	SET	(	GROU	P DE BRAS
PART.	CODICE	QUANT.	DEN	OMINAZIONE	DESCRIPTI	ON	Di	ESIGNATION
25	19.01.0004	4	VITE		BOLT		VIS	
26	08.14.3146	2	SUPPORTO	) TUBOLARE	SUPPORT		SUPP	ORT
27	19.01.0017	4	VITE		BOLT		VIS	
28	08.14.3095	1	TUBOLARE		TUBULAR		TUBC	LAIRE
29	08.14.3017	1	TASSELLO	FERMA CANALINA	LINING		GOU	ION
30	19.01.0003	2	VITE		BOLT		VIS	
31	08.14.3047	1	MASSELLC	) TUBI IDRAULICI	CONNECTION	J	RACC	ORD
32	08.14.3094	1	STAFFA CA	ATENARIA	BRACKET		BRAC	KET
33	19.01.0300	12	VITE		BOLT		VIS	
34	08.14.3046	6	TASSELLO	FERMA CANALINA	LINING		GOU	ION
35	55.28.0693		CATENARI	A ANTERIORE	CHAIN		CHAII	NE
36	19.01.0002	4	VITE		BOLT		VIS	
37	19.01.0231	4	VITE		BOLT		VIS	
38	08.14.3045	2	PIATTO CA	TENARIA	SUPPORT		SUPP	ORT
39	19.01.0231	4	VITE		BOLT		VIS	
40	19.01.0231	4	VITE		BOLT		VIS	
41	08.14.3045	2	PIATTO CA	TENARIA	SUPPORT		SUPP	ORT
42	08.14.2891	2	BOCCOLA		BUSH		DOUI	LLE
43	08.14.3043	1	RULLO CA	TENARIA	ROLLER		ROUL	.EAU
44	49.02.0008	2	CUSCINET	ТО	BALL BEARIN	G	ROUL	EMENT
45	49.02.0001	4	CUSCINET	ТО	BALL BEARIN	G	ROUL	EMENT
46	08.14.1901	2	DISTANZIA	LE	SPACER		ENTR	ETOISE
47	07.14.1120	1	PERNO		PIN		AXE	
48	07.14.1133	1	PERNO		PIN		AXE	
	Pala	ZZa	ani			Г		TAV N° 2
			ustrie spa		DIVISION	_		XTJ 32

	GRUPPC	BRAG	CCI	BOOM S	ET	GROUF	DE BRAS
PART.	CODICE	QUANT.	DENOMINAZ	ZIONE	DESCRIPTION	DE	SIGNATION
49	50.09.0084	1	GHIERA		WHEEL	GNIE	RA
50	08.14.3088	2	PATTINO		LINING		JON
51	19.01.0010	1	VITE		BOLT	VIS	
52	19.02.0022	1	DADO		NUT	ECRO	DU
53	08.14.3023	1	RULLO CATENARI	A	ROLLER	ROUL	EAU
54	19.01.0021	4	VITE		BOLT	VIS	
55	07.14.1123	1	PERNO		PIN	AXE	
56	08.14.3087	1	PATTINO		LINING	GOU	JON
57	55.14.0002	1	INGRASSATORE		GREASE NIPPLE	GRAI	SSEUR
58	08.14.3092	2	PATTINO		LINING	GOU	JON
59	07.14.1021	1	PERNO		PIN	AXE	
60	08.14.1183	1	RULLO CATENARI	A	ROLLER	ROUL	EAU
61	55.10.0021	2	COPIGLIA		SPLIT PIN	GOUI	PILLE
62	07.14.1116	1	PERNO		PIN	AXE	
63	08.14.3093	2	PATTINO		LINING	GOU	JON
64	19.01.0008	1	VITE		BOLT	VIS	
65	19.02.0022	1	DADO		NUT	ECRO	DU
66	08.14.1911	2	DISTANZIALE		SPACER	ENTR	ETOISE
67	08.14.3019	2	PATTINO		LINING	GOU	JON
68	19.01.0008	1	VITE		BOLT	VIS	
69	07.14.1118	1	PERNO		PIN	AXE	
70	19.02.0022	1	DADO		NUT	ECRO	DU
71	07.14.1115	1	PERNO		PIN	AXE	
72	19.01.0314	2	VITE		BOLT	VIS	
	Pala	ZZa	ani	F	PaLIFT		TAV N° 2
	Palazza	ni Indi	ustrie spa		DIVISION		XTJ 32

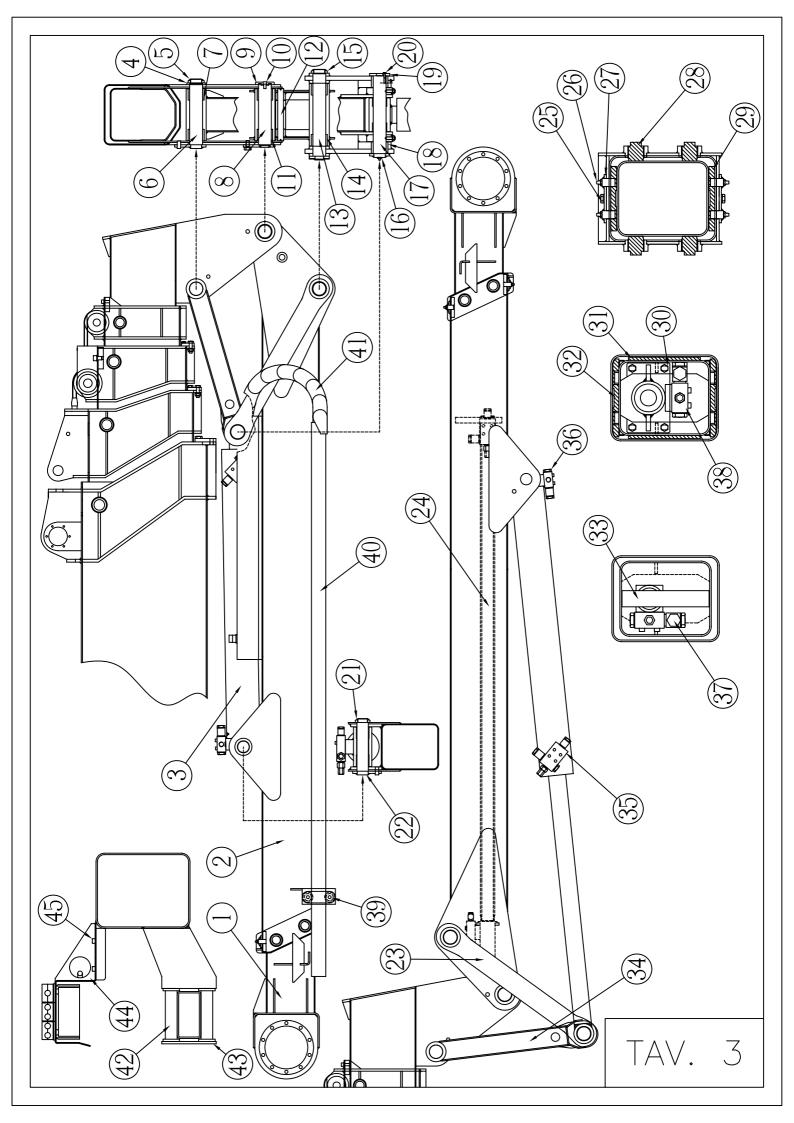
	GRUPPC	BRAG		BOOM	I SET		GROUP	DE BRAS
PART.	CODICE	QUANT.	DENOMI	VAZIONE	DESCRIPT	ΓΙΟΝ	DE	SIGNATION
73	08.14.3013	2	RONDELLA		WASHER		RONE	DELLE
74	55.10.0021	2	COPIGLIA		SPLIT PIN		GOUF	PILLE
75	07.14.1117	1	PERNO		PIN		AXE	
76	49.02.0042	4	CUSCINETTO		BALL BEARIN	١G	ROUL	EMENT
77	08.14.1911	2	DISTANZIALE		SPACER		ENTR	ETOISE
78	08.14.1183	1	RULLO CATENA	ARIA	ROLLER		ROUL	EAU
79	08.14.3012	1	RULLO CATENA	ARIA	ROLLER		ROUL	EAU
80	49.02.0068	2	CUSCINETTO		BALL BEARIN	١G	ROUL	EMENT
81	08.14.3084	1	PATTINO		LINING		GOU	ON
82	08.14.3120	2	PATTINO		LINING		GOU	ON
83	07.14.1117	1	PERNO		PIN		AXE	
84	55.10.0021	2	COPIGLIA		SPLIT PIN		GOUF	PILLE
85	07.14.1151	1	PERNO		PIN		AXE	
86	19.01.0314	2	VITE		BOLT		VIS	
87	08.14.3013	2	RONDELLA		WASHER		RONE	DELLE
88	08.14.3147	1	PATTINO		LINING		GOU	ON
89	08.14.3012	1	RULLO CATENA	ARIA	ROLLER		ROUL	.EAU
90	49.02.0068	2	CUSCINETTO		BALL BEARIN	١G	ROUL	EMENT
91	08.14.3118	2	PATTINO		LINING		GOU	ION
92	19.01.0021	18	VITE		BOLT		VIS	
	. Pala	ZZa	ani		PaLIF	T		TAV N° 2
			ustrie spa		DIVISION			XTJ 32





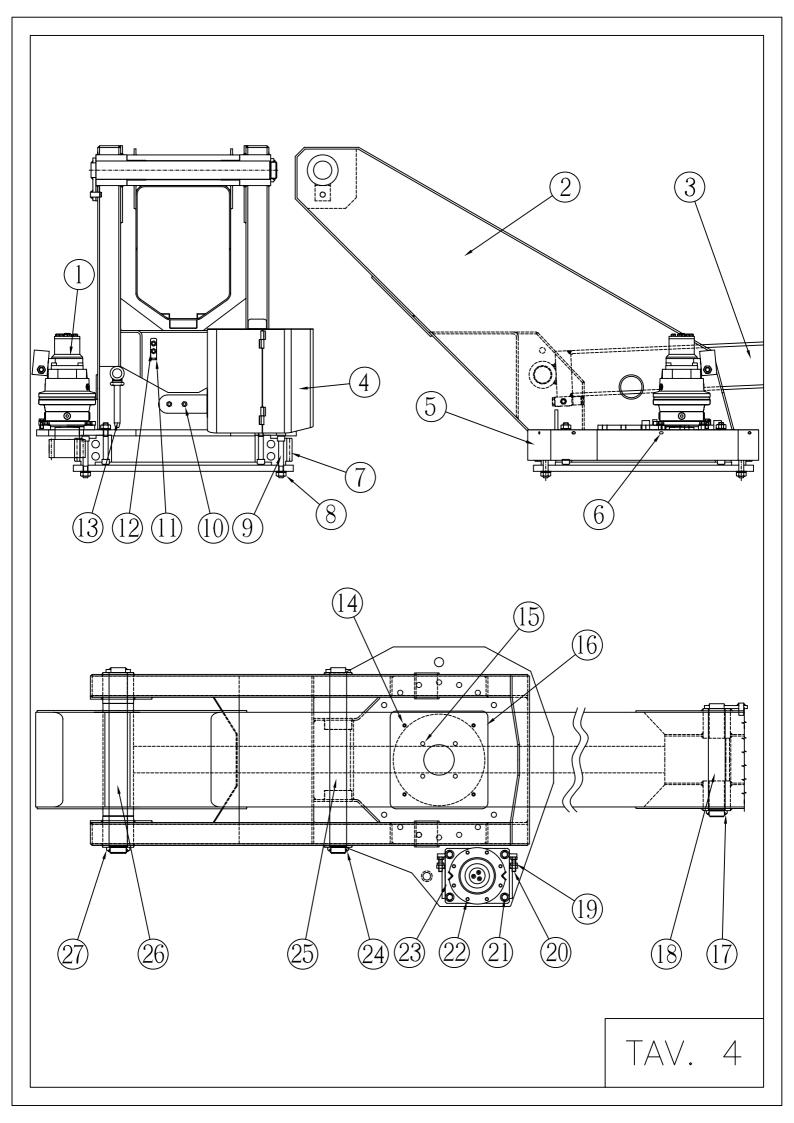
GR	UPPO ORIE	NTAME	ENTO JIB	JIB S	ET	GRC	DUPE D	E PENDULAIRE
PART.	CODICE	QUANT.	DENO	OMINAZIONE	DESCRIPT	ION	DI	ESIGNATION
1	05.14.1754	1	PROLUNG	A JIB	JIB EXTENSIO	ON	JIB R	ALLONGE
2	05.14.1755	1	BRACCIO J	IIB	JIB BOOM		BRAS	PENDULAIRE
3	01.01.0614	1	CILINDRO	ORIENT. JIB	JIB CYLINDEF	र	VERIN	PENDULAIRE
4	55.11.0026	1	RONDELLA	N.	WASHER		RONE	DELLE
5	50.09.0060	1	GHIERA		WHEEL		GNIE	RA
6	07.14.1148	1	PERNO		PIN		AXE	
7	08.14.2988	2	BOCCOLA		BUSH		DOUI	LLE
8	07.14.1145	2	BOCCOLA		BUSH		DOUI	LLE
9	08.14.3112	1	RONDELLA	N.	WASHER		RONE	DELLE
10	19.01.0238		VITE		BOLT		VIS	
11	08.14.2988	2	BOCCOLA		BUSH		DOUI	LLE
12	07.14.1146	1	PERNO		PIN		AXE	
13	07.141147	1	PERNO		PIN		AXE	
14	08.14.2988	2	BOCCOLA		BUSH		DOUI	LLE
15	50.09.0060	1	GHIERA		WHEEL		GNIE	RA
16	55.14.0002	2	INGRASSA	TORE	GREASE NIP	PLE	GRAI	SSEUR
17	07.14.1150	1	PERNO		PIN		AXE	
18	08.14.2988	2	BOCCOLA		BUSH		DOUI	LLE
19	08.14.3113	1	RONDELLA	N.	WASHER		RONE	DELLE
20	19.01.0231		VITE		BOLT		VIS	
21	50.09.0059	1	GHIERA		WHEEL		GNIE	RA
22	07.14.1149	1	PERNO		PIN		AXE	
23	05.14.1756	1	TIRANTE		CONNECTING	ROD	TIRAN	ΝT
24	01.01.0615	1	CILINDRO	SFILO JIB	RAM		VERI	N
	. Pala	77	ani		PaLIF	Г		TAV N° 3
		-	ustrie spa		DIVISION	-		XTJ 32

	GRUPPC	BRAG	CCI	BOO	M SET	C	GROUF	P DE BRAS
PART.	CODICE	QUANT.	DEN	OMINAZIONE	DESCRIPT	ION	DI	ESIGNATION
25	19.01.0016	2	VITE		BOLT		VIS	
26	55.14.0005	4	INGRASSA	TORE	GREASE NIPP	PLE	GRAI	SSEUR
27	08.14.3110	2	SUPPORT	O PATTINO	SUPPORT		SUPP	ORT
28	08.14.3115	4	PATTINO		LINING		GOUJ	ION
29	08.14.3114	2	PATTINO		LINING		GOUJ	ION
30	19.01.0017	4	VITE		BOLT		VIS	
31	13.92.0003	2	PATTINO		LINING		GOUJ	ION
32	08.14.3111	2	PATTINO		LINING		GOUJ	ION
33	08.14.3116	1	PATTINO		LINING		GOUJ	ION
34	05.14.1757	1	TIRANTE		CONNECTING	ROD	TIRAN	NT
35	50.12.0166	1	VALVOLA		VALVE		VALV	E
36	50.12.0166	1	VALVOLA		VALVE		VALV	E
37	50.12.0166	1	VALVOLA		VALVE		VALV	E
38	50.12.0166	1	VALVOLA		VALVE		VALV	E
39	08.14.1158	2	PERNO		PIN		AXE	
40	08.14.2143	1	TUBOLARE	E	TUBULAR		TUBC	LAIRE
41	55.28.0388		CATENARI	A	CHAIN		CHAII	NE
42	08.14.1159	2	RULLO		ROLLER		ROUL	.EAU
43	08.14.1157	1	PIATTO TE	NUTA RULLI	SUPPORT		SUPP	ORT
44	08.14.2996	1	SUPPORT	O CATENARIA	SUPPORT		SUPP	ORT
45	19.01.0231	4	VITE		BOLT		VIS	
	Pala	ZZa	ani		PaLIF	Г		TAV Nº 3
			ustrie spa	,	DIVISION	-		XTJ 32

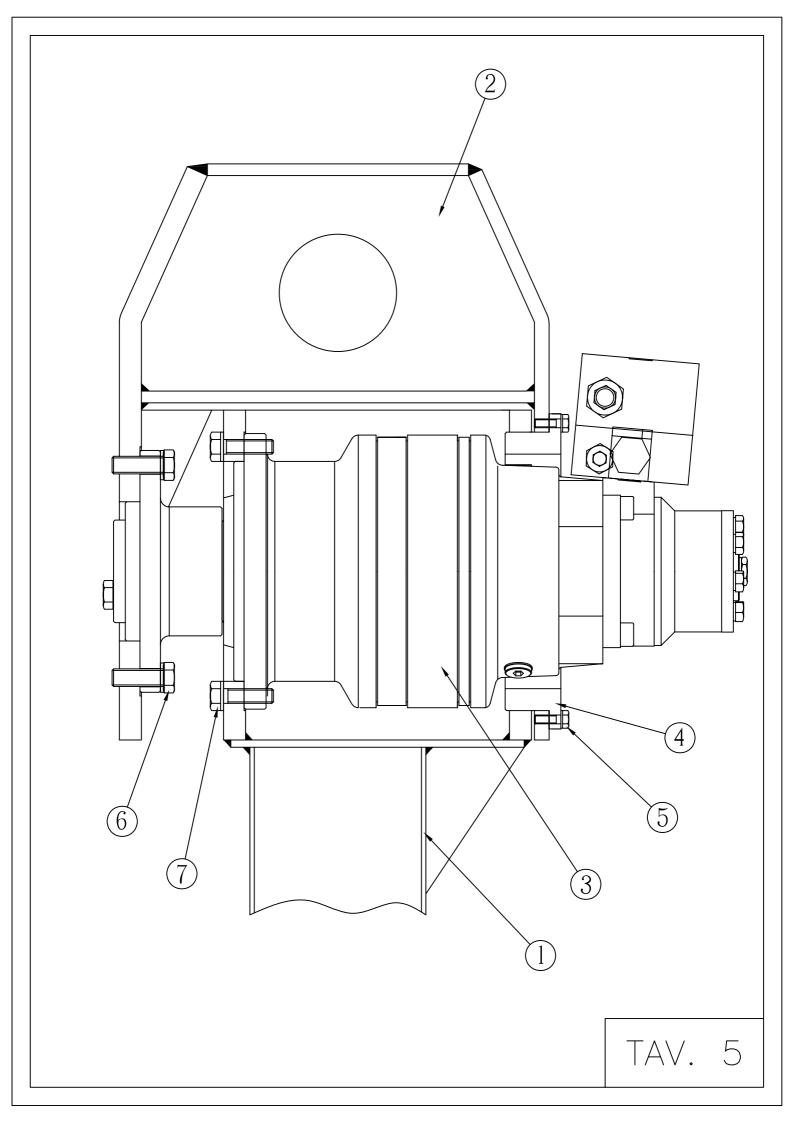


	GRUPPO	TORRI	ETTA TURNTAB	LE SET	GROUP TOURELLE
PART.	CODICE	QUANT.	DENOMINAZIONE	DESCRIPTION	DESIGNATION
1	55.28.0316	1	RIDUTTORE	SLEWING OIL	ENGRANAGE ROTATION
2	05.14.1763	1	TORRETTA	TURNTABLE	TOURELLE
3	01.01.0616	1	CILINDRO DI SOLLEVAMENTO	CYLINDER	CYLINDRE
4	05.92.0003	1	CARTER DANFOSS	COVER	CARTER
5	05.14.1863	1	CARTER RALLA	COVER	CARTER
6	19.01.0003	4	VITE	BOLT	VIS
7	55.28.0352	1	RALLA	SLEWING REAR RING	COURONNE DE ROTATION
8	19.02.0086	38	DADO	NUT	ECROU
9	19.01.0231	48	VITE	BOLT	VIS
10	19.01.0327	2	VITE	BOLT	VIS
11	08.14.2997	1	SUPPORTO FINECORSA	SUPPORT	SUPPORT
12	19.01.0004	2	VITE	BOLT	VIS
13	07.14.0407	1	PERNO	PIN	AXE
14	19.01.0034	4	VITE	BOLT	VIS
15	19.01.0054	4	VITE	BOLT	VIS
16	08.14.2987	1	PIASTRA COLLETTORE	BRACKET	PATTE
17	50.09.0084	1	GHIERA	WHEEL	GNIERA
18	07.14.1133	1	PERNO	PIN	AXE
19	19.02.0006	2	DADO	NUT	ECROU
20	19.01.0052	2	VITE	BOLT	VIS
21	19.01.0051	4	VITE	BOLT	VIS
22	19.01.0035	8	VITE	BOLT	VIS
23	08.14.3059	1	PIASTRA RIDUTTORE	BRACKET	PATTE
24	50.09.0084	1	GHIERA	WHEEL	GNIERA
	, Pala	77	ani	PaLIFT	TAV N° 4
			ustrie spa	DIVISION	XTJ 32

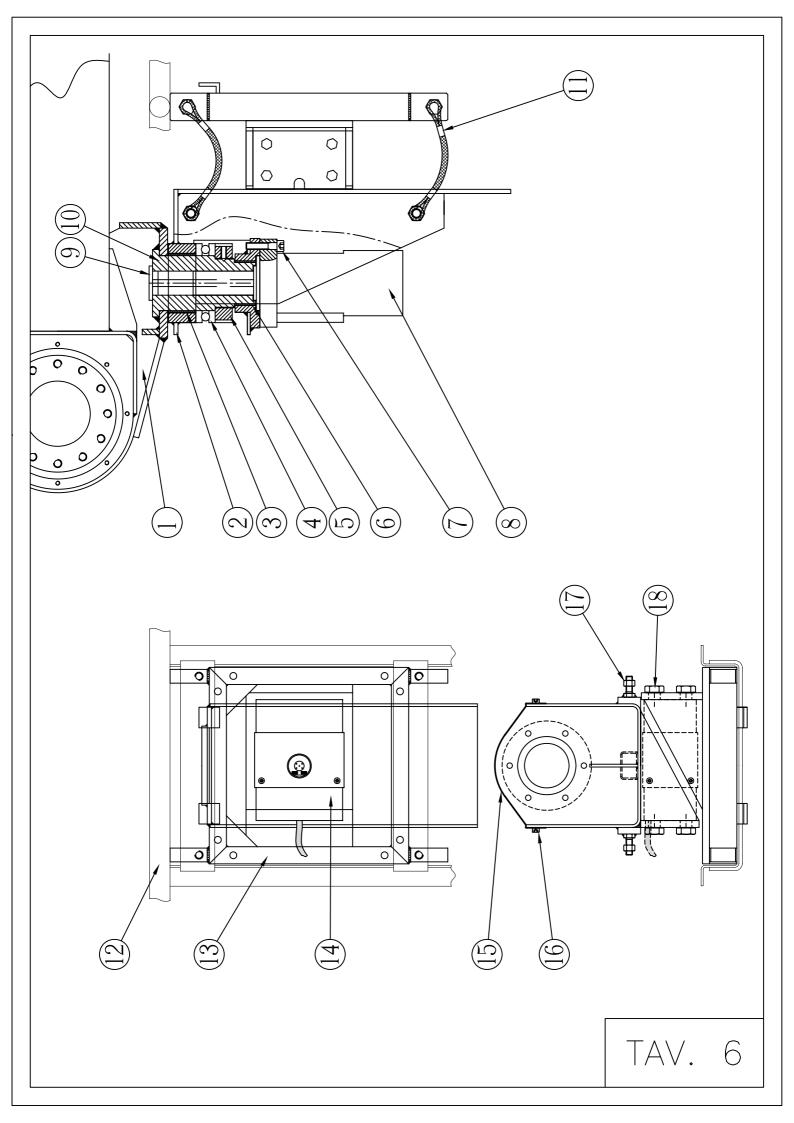
	GRUPPO	TORR	ETTA	٦	URNTABI	E SET	GF	GROUP TOURELLE		
PART.	CODICE	QUANT	DENO	OMINAZ	IONE	DESCRIPT	ON	DI	ESIGNATION	
25	07.14.1135	1	PERNO			PIN		AXE		
26	07.14.1136	1	PERNO			PIN		AXE		
27	50.09.0062	1	GHIERA			WHEEL		GNIEI	RA	
	Pala		ani		PaLIFT				TAV N° 4	
	Palazzani Industrie spa				DIVISION			XTJ 32		



OR		ТО СЕ	STO ORIEN	ITATION B	ASKET	ORIE	NTAT	ON NACELLE
PART.	CODICE	QUANT.	DENOMINAZ	IONE	DESCRIPT	ION	DE	SIGNATION
1	05.14.1754	1	BRACCIO JIB		воом		BRAS	
2	05.14.1626	1	SUPPORTO GIREV	OLE (JIB)	SUPPORT		SUPP	ORT
3	55.28.0457	1	RIDUTTORE ROTA	ZIONE	SLEWING OIL	_	ENGR ROTA	ANAGE TION
4	08.14.2357	1	BOCCOLA		BUSH		DOUII	.LE
5	19.01.0003	8	VITE		BOLT		VIS	
6	19.01.0051	12	VITE		BOLT		VIS	
7	19.01.0035	10	VITE		BOLT		VIS	
								TAV N° 5
				PaLIFT			·	
	Palazza	ni indi	ustrie spa		DIVISION			XTJ 32



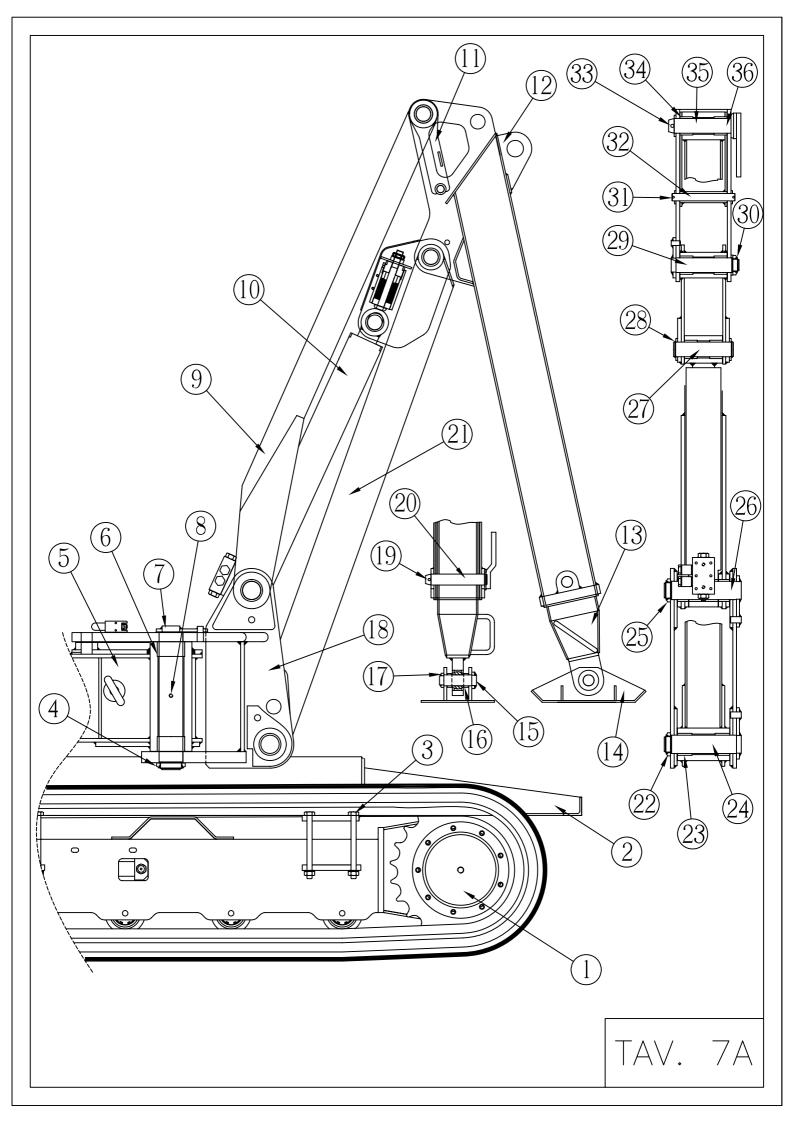
AMEN	то се	STO ORIENTATION	BASKET	ORIE	NTATION NACELLE
DDICE	QUANT.	DENOMINAZIONE	DESCRIPT	ION	DESIGNATION
4.1626	1	SUPP. GIREVOLE (JIB)	SUPPORT		SUPPORT
4.1848	1	SUPP. GIREVOLE (CESTO)	SUPPORT		SUPPORT
8.0485	1	BRONZINA	BUSH		DOUILLE
49.04.0015 1 CUS		CUSCINETTO	BEARING		ROULEMENT
4.2315	1	GHIERA	RING		ECROU
8.0486	1	BRONZINA	BUSH		DOUILLE
1.0257	5	VITE	BOLT		VIS
8.0392	1	ATTUATORE ROTATIVO	ACTUATOR		MOTEUR
4.2610	1	COPERCHIO	COVER		COVER
4.2314	1	ALBERO CENTRALE	GEAR		PIVOT
4.2967	4	CAVO ACCIAIO	CABLE		CABLE
4.2921	1	SUPPORTO SNODO CESTO	SUPPORT		SUPPORT
2.1007	1	CELLA DI CARICO	LOAD CELL		CELLULE DE CHARGE
2.0026	4	DADO	NUT		ECROU
4.2717	1	CARTER	COVER		COUVERCLE
1.0233	2	VITE	BOLT		VIS
1.0068	8	VITE	BOLT		VIS
4.1524	1	CESTO	CAGE		NACELLE
	-	-	PaLIF	 T	TAV N° 6 <b>XTJ 32</b>
_	-		<b>azzani</b> vani Industrie spa		

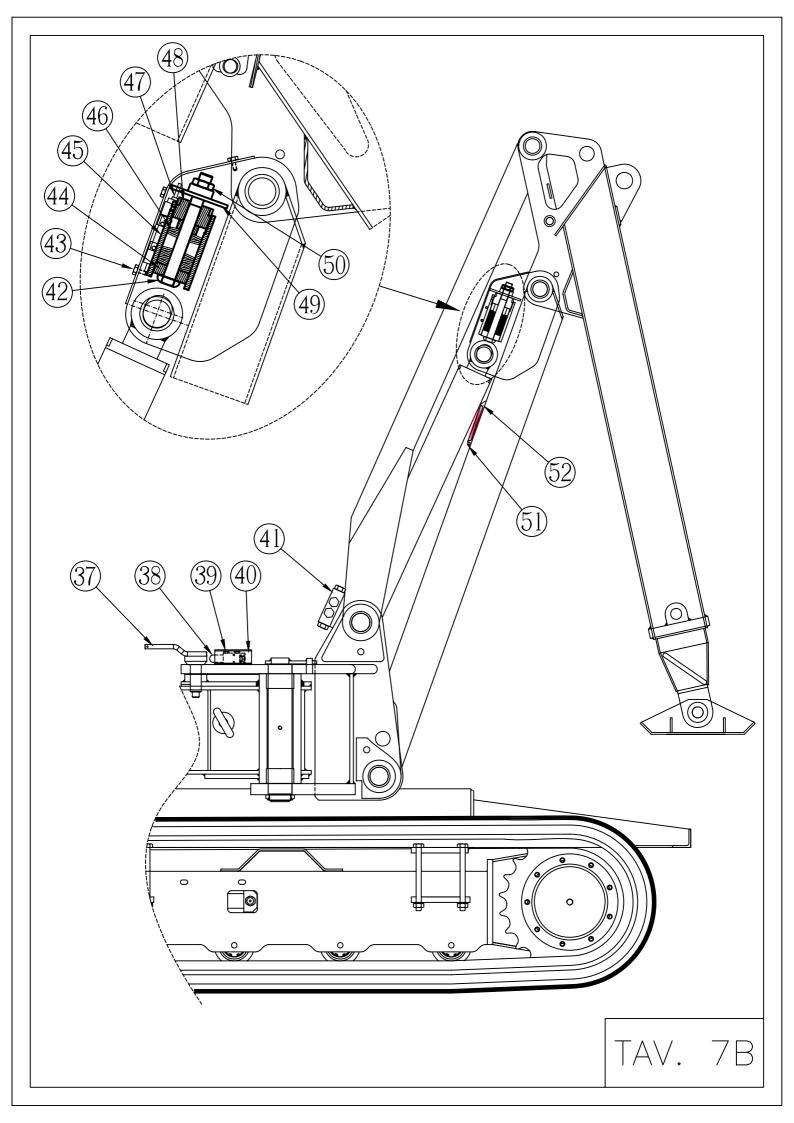


CARRO BASE U							CHAR DE BASE	
PART.	CODICE	QUANT.	DENOMINAZIONE		DESCRIPTION		DESIGNATION	
1	55.28.0705	1	CARRO		CARRIGE		CHAR	
2	05.14.1171	1	TELAIO		FRAME		CHASSIS	
3	19.01.0401	8	VITE		BOLT		VIS	
4	50.09.0083	4	GHIERA		RING		ECROU	
5	05.14.1767	1	BASAMENTO		FRAME		CADRE DE VEHIEVRE	
6	08.14.3108	8	BOCCOLA		BUSH		DOUILLE	
7	07.14.1140	4	PERNO		PIN		AXE	
8	55.14.0002	4	INGRASSATORE		GREASE NIPPLE		GRAISSEUR	
9	05.14.1749	4	PUNTONE SUPERIORE		SUPERIOR BOOM		BRAS SUPERIEUR	
10	01.01.0618	4	CILINDRO STABILIZZATORI		STABILIZER RAM		VERIN DE STABILIS.	
11	05.14.1769	4	LEVA STABILIZZATORI		LEVER		LEVIER	
12	05.14.1768	4	SECONDO BRACCIO STABILIZZATORE		SECOND BOOM		DEUXIEME BRAS	
13	05.14.1770	4	PROLUNGA STABILIZZATORI		THIRD BOOM		DERNIER BRAS	
14	05.14.1000	4	PIATTELLO		JOINT FOOT		PIED ARTICULE	
15	07.14.2261	4	PERNO		PIN		AXE	
16	08.14.2261	8	DISTANZIALE		SPACER		ENTRETOISE	
17	50.09.0058	4	GHIERA		RING		ECROU	
18	05.14.1766	4	SUPPORTO STABI	LIZZATORI	DRI STAB. SUPPORT		SUPPORT DE STAB.	
19	14.01.0016	4	FERMO A MOLLA	ERMO A MOLLA SPLIT PIN			COUPILLE FENDUE	
20	07.14.1155	4	PERNO		PIN		AXE	
21	05.14.1750	4	PRIMO BRACCIO STABILIZZATORE		FIRST BOOM		PREMIER BRAS	
22	50.09.0061	4	GHIERA		RING		ECROU	
23	08.14.2849	8	BOCCOLA		BUSH		DOUILLE	
24	07.14.1139	4	PERNO		PIN		AXE	
	Pala	77	ani		PaLIF	Г		TAV N° 7
			ustrie spa	DIVISION			XTJ 32	

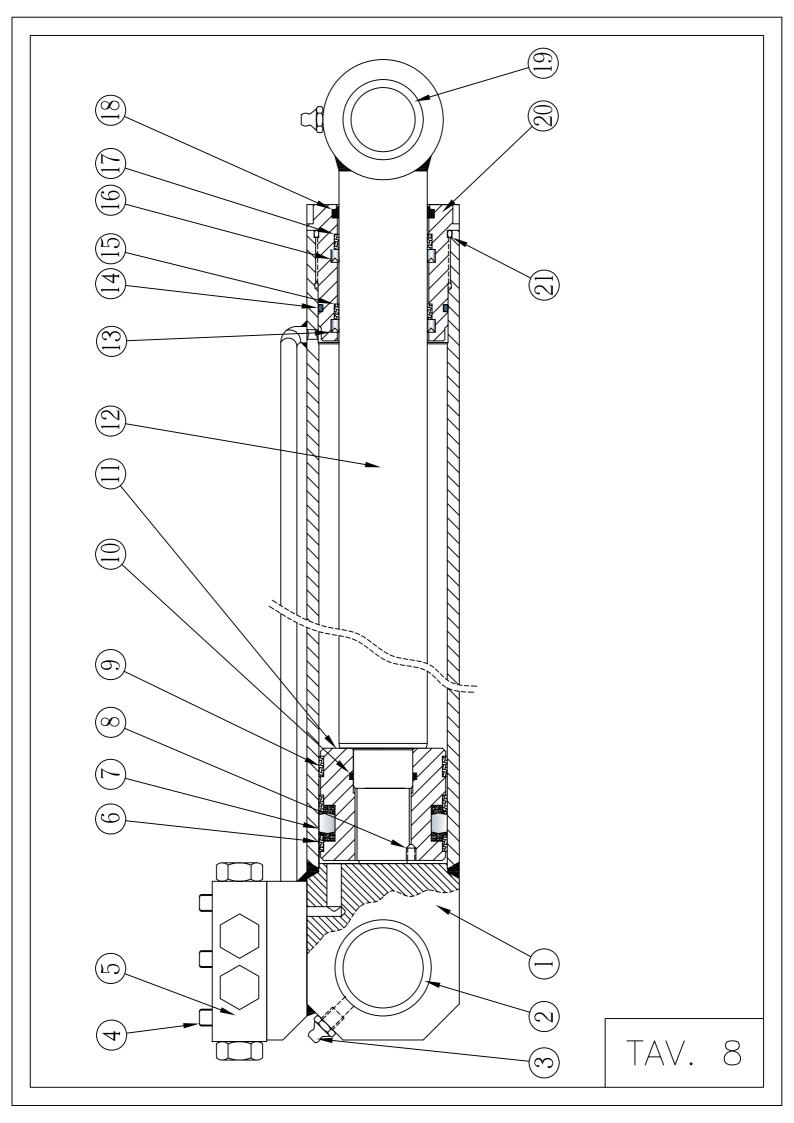
CARRO BASE U							CHAR DE BASE	
PART.	CODICE	QUANT.	DENOMINAZ	ZIONE	DESCRIPTION		DESIGNATION	
25	50.09.0061	4	GHIERA		RING		ECROU	
26	07.14.1138	4	PERNO		PIN		AXE	
27	07.11.1159	4	PERNO		PIN		AXE	
28	55.07.0025	8	SEEGER		CIRCLIP		ANNEAU DE RETENUE	
29	07.14.1157	4	PERNO		PIN		AXE	
30	50.09.0059	4	GHIERA		RING		ECROU	
31	55.10.0014	2	COPIGLIA		RING		ECROU	
32	07.14.1156	4	PERNO		PIN		AXE	
33	14.01.0082	4	FERMO A MOLLA		SPLIT PIN		COUPILLE FENDUE	
34	55.11.0086	4	RONDELLA		WASHER		RONDELLE	
35	08.14.2418	8	BOCCOLA		BUSH		DOUILLE	
36	07.14.1158	4	PERNO		PIN		AXE	
37	07.92.0001	4	PERNO		PIN		AXE	
38	08.14.3502	4	SUPPORTO MICRO		SUPPORT		SUPPORT	
39	19.01.0008	8	VITE		BOLT		VIS	
40	13.92.0001	4	CARTER		COVER		COUVERCLE	
41	50.12.0310	4	VALVOLA		VALVE		VALVE	
42	08.14.3141	4	PERNO PREMIMO	LLE	PIN		AXE	
43	19.01.0003	16	VITE		BOLT		VIS	
44	08.14.3144	4	STANTUFFO PREMIMOLLE		PRESS-SPRINGS		PRESSE-RESSORTS	
45	08.14.3139	4	CILINDRO CUSTODIA MOLLE		SPRINGS CARE		CILINDRE ETUI RESSORTS	
46	55.13.0032		MOLLE A TAZZA		SPRINGS		RESSORTS	
47	14.12.1153	4	DISTANZIALE		SPACER		ENTRETOISE	
48	08.14.3140	4	GHIERA DI REGIS	TRO	RING	NG ECRO		U
	Pala	ZZ	ani		PaLIF <sup>-</sup>	Γ		TAV Nº 7
	Palazza	ni Indi	ustrie spa		DIVISION			XTJ 32

	CARRO	) BAS	E	UNDER C	ARRIAGE		CHAR I	DE BASE
PART.	CODICE	QUANT.	DENO	MINAZIONE	DESCRIPTI	ON	DE	SIGNATION
49	08.14.3143	4	PIATTO PER	FINECORSA	SUPPORT		SUPP	ORT
50	19.02.0018	4	DADO		NUT		ECRO	U
51	19.01.0461	8	VITE		BOLT		VIS	
52	14.12.1190	4	LUCCIOLA		FIREFLY		LUCIC	DLE
							T	
	Pala	ZZa	ani		PaLIF <sup>-</sup>	Г	F	TAV N° 7
	Palazza	ni Indi	ustrie spa		DIVISION			XTJ 32

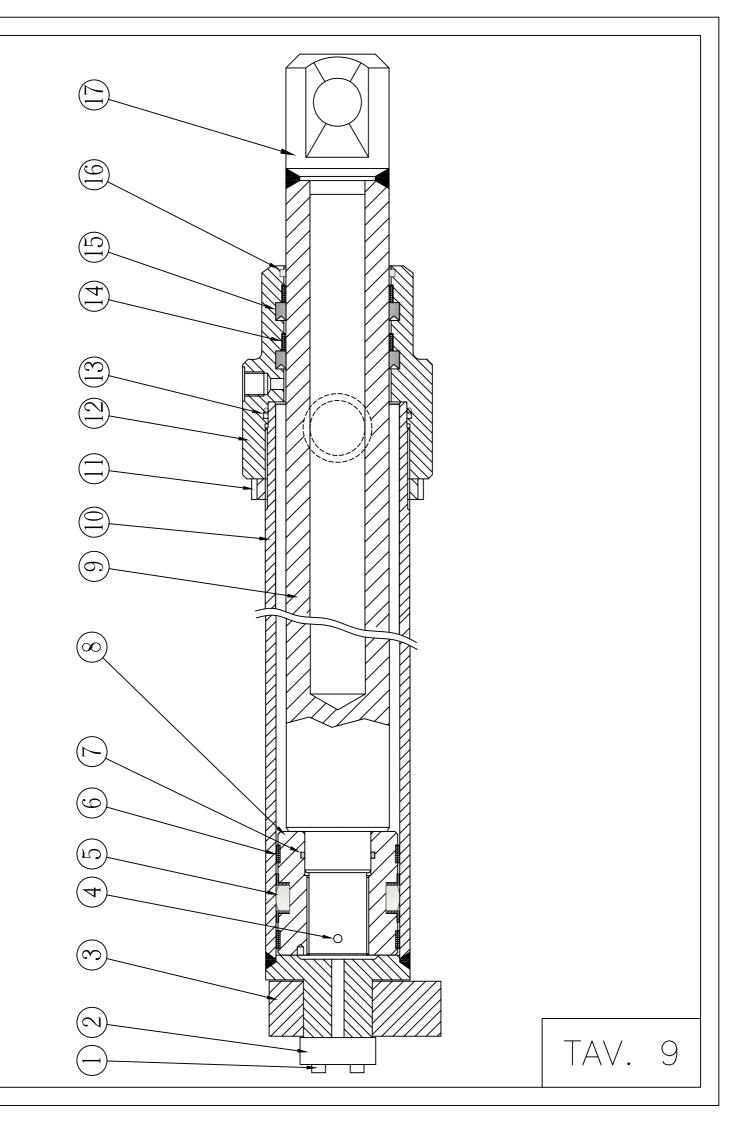




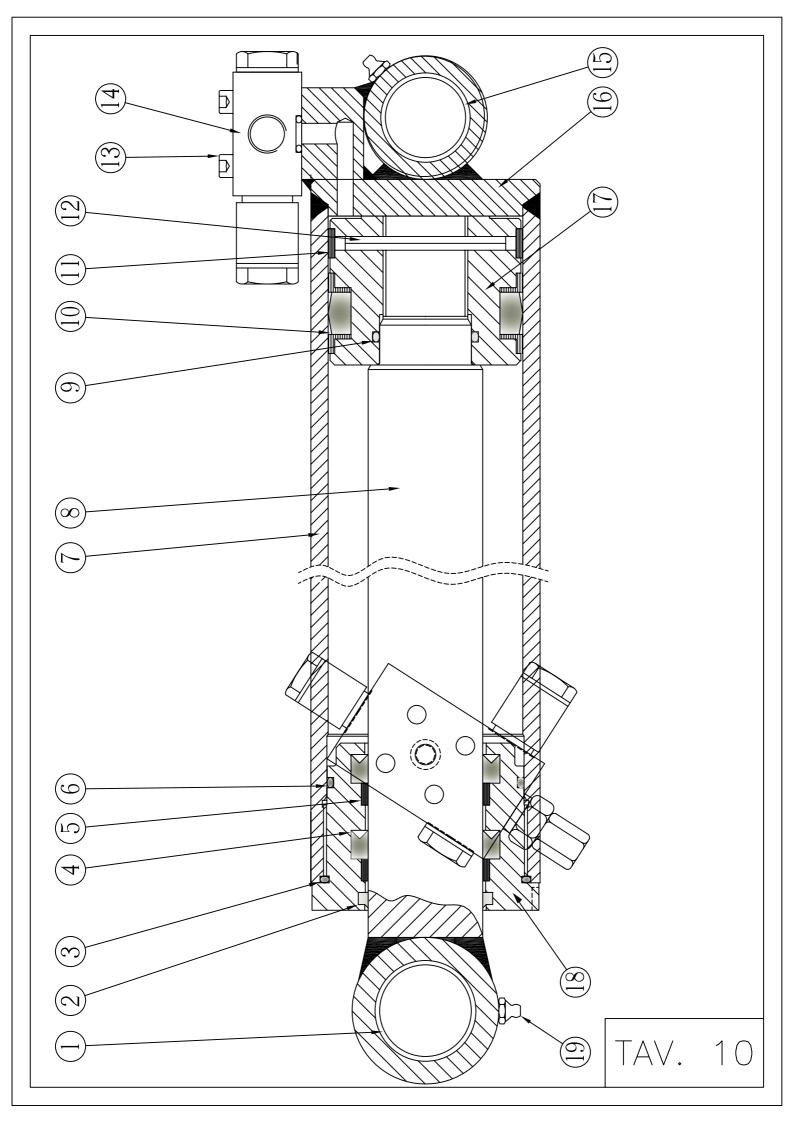
CII	INDRO ST	ABILIZ	ZATORI STAB	ILIZER RAM	ST	VERIN DE ABILISATEUR	
PART.	CODICE	QUANT.	DENOMINAZIONE	DESCRIPTI	ON	DESIGNATION	
1	01.01.0618	4	CILINDRO COMPLETO	LIFTING RAM	١	/ERIN DE LEVAGE	
2	08.14.3104	2	BOCCOLA	BUSH	[	DOUILLE	
3	55.14.0002	2	INGRASSATORE	GREASE NIPP	LE	GRAISSEUR	
4	19.01.0236	6	VITE	BOLT	١	/IS	
5	50.12.0310	1	VALVOLA	VALVE	S	SOUPAPE	
6	18.05.0051	3	ANELLO DI GUIDA	GUIDE RING	E	BAGUE DE GUIDAGE	
7	18.04.0033	1	GUARNIZIONE	GASKET	,	JOINT	
8	19.01.0351	1	GRANO	SCREW	١	/IS	
9	01.09.0613	1	CAMICIA	CYLINDER TU	BE 7	TUYAU DE CILINDRE	
10	18.01.0115	1	GUARNIZIONE OR	GASKET	,	JOINT	
11	01.15.1104	1	STANTUFFO	PISTON	F	PISTON	
12	01.10.0802	1	STELO	PISTON ROD	٦	TIGE DE PISTON	
13	18.02.0047	1	GUARNIZIONE EU	GASKET		JOINT	
14	18.01.0160	1	GUARNIZIONE OR	GASKET		JOINT	
15	18.05.0043	1	ANELLO DI GUIDA	GUIDE RING	E	BAGUE DE GUIDAGE	
16	18.02.0047	1	GUARNIZIONE EU	GASKET		JOINT	
17	18.05.0043	1	ANELLO DI GUIDA	GUIDE RING	E	BAGUE DE GUIDAGE	
18	18.06.0004	1	RASCHIATORE	WIPER SCAL	S	SEGMENT RACLEUF	
19	08.14.2418	2	BOCCOLA	BUSH	[	DOUILLE	
20	01.15.1110	1	FLANGIA ANTERIORE	FRONT FLANC	E E	BRIDE	
21	18.01.0160	1	GUARNIZIONE OR	GASKET		JOINT	
	Pala		oni	PaLIF		TAV N° 8	
			<b>XIII</b> Istrie spa			XTJ 32	



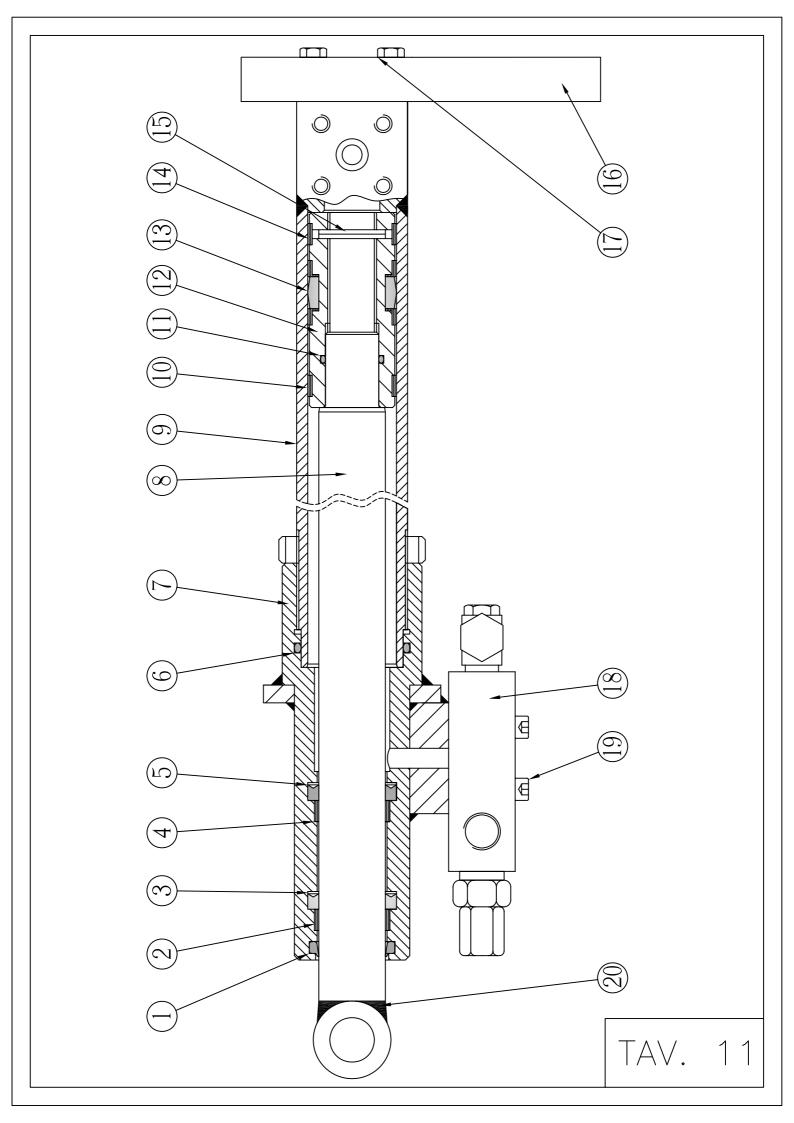
	CILINDRO	D DI SF	FILO	EXTENS	ENSION RAM		VERIN DE TELESCOPAGE		
PART.	CODICE	QUANT.	DENG	OMINAZIONE	DESCRIPT	ION	D	ESIGNATION	
1	19.01.0236	4	VITE		BOLT	BOLT			
2	50.12.0166	1	VALVOLA		VALVE		SOUF	PAPE	
3	08.14.3096	1	SUPPORTO	) FONDELLO	SUPPORT		SUPF	ORT	
4	55.09.0001	1	SPINA ELA	STICA	SPLIT SPIN		GOUF	PILLE FENDUE	
5	18.04.0054	1	GUARNIZIC	DNE	GASKET		JOINT	Г	
6	18.05.0041	2	ANELLO DI	GUIDA	GUIDE RING		BAGL	IE DE GUIDAGE	
7	18.01.0051	1	GUARNIZIC	ONE OR	GASKET		JOINT	Г	
8	01.15.1106	1	STANTUFF	0	PISTON		PISTO	N	
9	01.10.0884	1	STELO		PISTON ROD		TIGE	DE PISTON	
10	01.151106	1	CAMICIA	CAMICIA CYLINDER TUBE		TUYAU DE CYLIND			
11	01.15.1021	1	GHIERA DI	BLOCCAGGIO	NUT	NUT		ECROU	
12	01.15.1105	1	BUSSOLA I	DI GUIDA	GUIDE BUSH	GUIDE BUSH		LLE DE AGE	
13	18.01.0170	1	GUARNIZIC	ONE OR	GASKET		JOINT	Γ	
14	18.05.0056	2	ANELLO DI	GUIDA	GUIDE RING		BAGL	IE DE GUIDAGE	
15	18.05.0145	2	GUARNIZIC	DNE	GASKET		JOINT	Γ	
16	18.06.0037	1	RASCHIAT	ORE	NIPER SCAL		SEGN	IENT RACLUER	
17	01.01.0609	1	CILINDRO	COMPLETO	LIFTING RAM		VERI	N DE LEVAGE	
	Pala				PaLIF	Г		TAV N° 9	
	Palazza	ni Indi	ustrie spa		DIVISION			XTJ 32	



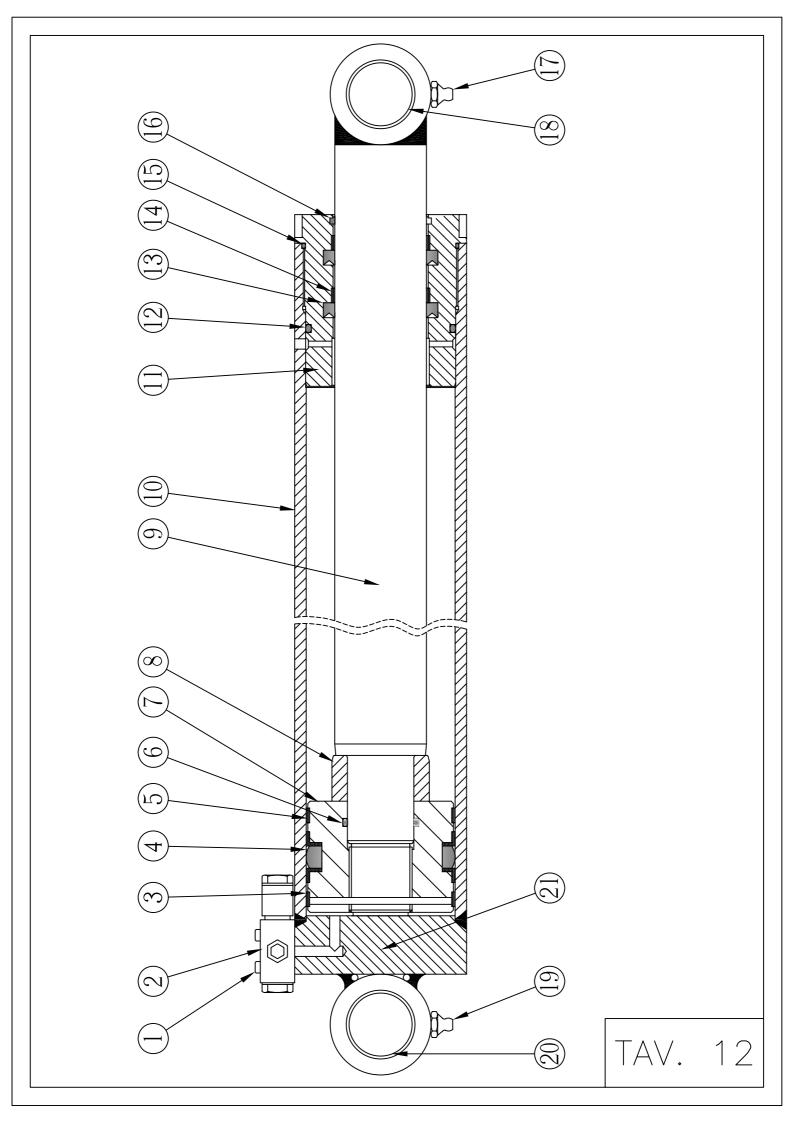
CILINDRO ORINTAMENTO JIB			ENTO JIB	JIB	RAM		VEF	RIN JIB
PART.	CODICE	QUANT.	DENO	MINAZIONE	DESCRIPT	ION	DN DESIGNA	
1	08.14.3511	2	BOCCOLA		BUSH		DOUII	LE
2	18.06.0005	1	RASCHIATC	RE	WIPER SCAL		SEGM	IENT RACLEUR
3	18.01.0166	1	GUARNIZIO	NE OR	GASKET		JOINT	-
4	18.05.0061	2	GUARNIZIO	NE	GASKET		JOINT	-
5	18.05.0044	2	ANELLO DI	GUIDA	RING		BAGU	IE
6	18.01.0167	1	GUARNIZIO	NE OR	GASKET		JOINT	-
7	01.09.0609	1	CAMICIA		CYLINDER TU	JBE	TUYA	U DE CILINDRE
8	01.10.0888	1	STELO		PISTON ROD		TIGE	DE PISTON
9	18.01.0210	1	GUARNIZIO	NE OR	GASKET		JOINT	-
10	18.04.0054	1	GUARNIZIO	NE	GASKET		JOINT	
11	18.05.0041	1	ANELLO DI	GUIDA	RING		BAGUE	
12	55.09.0001	1	SPINA ELAS	STICA	SPLIT PIN		GOUPILLE FENDUE	
13	19.01.0236	8	VITE		BOLT	VIS		
14	50.12.0166	2	VALVOLA		VALVE		SOUF	PAPE
15	08.98.0002	2	BOCCOLA		BUSH		DOUILLE	
16	01.01.0614	1	CILINDRO C	OMPLETO	JIB RAM		VERIN JIB	
17	01.15.1113	1	STANTUFFC	)	PISTON		PISTON	
18	01.15.1112	1	BUSSOLA D	I GUIDA	GUIDE BUSH		DOUII GUID	LE DE AGE
19	55.14.0002	2	INGRASSAT	ORE	GREASE NIP	PLE	GRAI	SSEUR
	Pala		oni		PaLIF	┲		TAV N° 10
			<b>di II</b> ustrie spa					XTJ 32



CILINDRO SFILO JIB EX					ON JIB RAM	VERI	N DE TE	LESCOPAGE JIB	
PART.	CODICE	QUANT.	DENG	OMINAZIONE	DESCRIP	ΓΙΟΝ	D	ESIGNATION	
1	18.06.0036	1	RASCHIAT	ORE	WIPER SCAI	_	SEGN	IENT RACLEUR	
2	18.05.0048	1	ANELLO DI	GUIDA	RING		BAGL	JE	
3	18.05.0146	1	GUARNIZIC	DNE	GASKET		JOIN	Г	
4	18.05.0048	1	ANELLO DI	GUIDA	RING		BAGL	JE	
5	18.05.0146	1	GUARNIZIC	DNE	GASKET		JOIN	Г	
6	18.01.0044	1	GUARNIZIC	DNE	GASKET		JOIN	Г	
7	01.15.1114	1	TESTATA		GUIDE BUSH	ł	DOUI GUID	LLE DE AGE	
8	01.10.0889	1	STELO		PISTON ROL	)	TIGE	DE PISTON	
9	01.09.0610	1	CAMICIA		CYLINDER T	CYLINDER TUBE		U DE CILINDRE	
10	18.05.0055	1	ANELLO DI	GUIDA	RING	RING		BAGUE	
11	18.01.0026	1	GUARNIZIC	DNE	GASKET	GASKET		JOINT	
12	01.15.0909	1	STANTUFF	0	PISTON	PISTON		PISTON	
13	18.04.0073	1	GUARNIZIC	DNE	GASKET	GASKET		Г	
14	18.05.0055	1	ANELLO DI	GUIDA	RING	RING		JE	
15	55.09.0022	1	SPINA ELA	STICA	SPLIT PIN	SPLIT PIN		PILLE FENDUE	
16	08.14.3116	1	PATTINO		LINING	LINING		ION	
17	19.01.0005	4	VITE		BOLT	BOLT VIS			
18	50.12.0166	2	VALVOLA		VALVE	SOUF		PAPE	
19	19.01.0235	8	VITE		BOLT		VIS		
20	01.01.0615	1	CILINDRO	COMPLETO	JIB RAM		VERI	N JIB	
	Pala	ZZa	ani		PaLIF	Т		TAV Nº 11	
	Palazzai	ni Indi	ustrie spa		DIVISION	l		XTJ 32	



CILINDRO DI SOLLEVAMENTO			LIFTIN	LIFTING RAM V		ERIN DE LEVAGE			
PART.	CODICE	QUANT.	DENO	MINAZIONE	DESCRIPT	ION	Di	ESIGNATION	
1	19.01.0235	4	VITE	VITE BOLT		VIS			
2	50.12.0166	1	VALVOLA		VALVE		SOUF	PAPE	
3	18.05.0078	1	ANELLO DI O	GUIDA	RING		BAGL	JE	
4	18.04.0059	1	GUARNIZIO	NE	GASKET		JOINT	Г	
5	18.05.0078	1	ANELLO DI O	GUIDA	RING		BAGL	JE	
6	18.01.0264	1	GUARNIZIO	NE OR	GASKET		JOINT	Γ	
7	01.15.1116	1	STANTUFFC	)	PISTON		PISTO	ON	
8	01.15.1109	1	BUSSOLA D	I FRENATURA	GUIDE BUSH		DOUI GUID	LLE DE AGE	
9	01.10.0890	1	STELO		PISTON ROD		TIGE	DE PISTON	
10	01.09.0611	1	CAMICIA		CYLINDER TU	IBE TUYAL		U DE CILINDRE	
11	01.15.1115	1	BUSSOLA D	I GUIDA	GUIDE BUSH		DOUI GUID	LLE DE AGE	
12	18.01.0093	1	GUARNIZIO	NE OR	GASKET	GASKET		JOINT	
13	18.55.0082	1	GUARNIZIO	NE	GASKET	GASKET		Г	
14	18.05.0056	1	ANELLO DI O	GUIDA	RING	RING		JE	
15	18.01.0176	1	GUARNIZIO	NE	GASKET		JOINT	Г	
16	18.06.0037	1	RASCHIATO	RE	WIPER SCAL		SEGMENT RACLE		
17	55.14.0002	1	INGRASSAT	ORE	GREASE NIP	PLE	GRAISSEUR		
18	08.14.3512	2	BOCCOLA		BUSH		DOUILLE		
19	55.14.0002	1	INGRASSAT	ORE	GREASE NIPF	PLE	GRAI	SSEUR	
20	08.14.3512	2	BOCCOLA		BUSH		DOUI	LLE	
21	01.01.0616	1	CILINDRO C	OMPLETO	JIB RAM		VERI	N JIB	
	Pala		oni					TAV N° 12	
			<b>d      </b> ustrie spa					XTJ 32	



## VARIANTE CON STABILIZZATORI A BRACCIO FISSO

**OPZIONALE** 

## ELENCO TUBI FLESSIBILI XTJ 32 Cod. 02.24.0111

LE LUNGHEZZE SI RIFERISCONO AL TAGLIO DEL TUBO AGGIORNATO AL : 31/12/2009

(a) -N°1 TUBO FLEX. SAE100 R2AT 1/2"gas TR16x250AK DA FILTRO A 1630

(b) -N°1 TUBO FLEX. SAE100 R2AT 1/2"gas TR16x1400AK MANDATA GENERATORE

(c) -N°1 TUBO FLEX. SAE100 R2AT 1/2"gas TR16x1000AK 2° POMPA HATZ A FILTRO

(d) -N°1 TUBO FLEX. SAE100 R2AT 1/2"gas TR16x1000AK SCARICO BASE STABILIZZATORE

(e) -N°1 TUBO FLEX. SAE100 R2AT 1/2"gas TR16x800AA SCARICO VEI GENERATORE

(f) -N°1 TUBO FLEX. SAE100 R2AT 1/2"gas TR16x1250AK MANDATA BASE STABILIZZATORE

(g) -N°1 TUBO FLEX. SAE100 R2AT 3/4"gas TR20x900AK DA 1630 A 1630

(h) -N°1 TUBO FLEX. SAE100 R2AT 1/2"gas TR16x350AA 1° FILTRO A 1630

(i) -N°1 TUBO FLEX. SAE100 R2AT 1/2"gas TR16x1200AK 1° POMPA HATZ A FILTRO

(j) -N°1 TUBO FLEX. SAE100 R2AT 1/2"gas TR16x1000AK MANDATA COLLETTORE

(k) -N°1 TUBO FLEX. SAE100 R2AT 1/2"gas TR16x700AK SCARICO COLLETTORE

(l) -N°1 TUBO FLEX. SAE100 R2AT 1/2"gas TR16x1300AK SCARICO DANFOSS

(m)-N°1 TUBI FLEX. SAE100 R2AT 3/4"gas TR20x1400AK 1630 A DANFOSS

(n) -N°1 TUBO FLEX. SAE100 R2AT 5/16"gas TR12x1000AK MANDATA MOTORE 220

(o) -N°1 TUBO FLEX. SAE100 R2AT 5/16"gas TR12x1400AK POMPA A MANO

(p) -N°1 TUBO FLEX. SAE100 R2AT 1/2"gas TR16x1300AK 630 A CINGOLO (q) -N°1 TUBO FLEX. SAE100 R2AT 1/2"gas TR16x900AA SCARICO 630

(r) -N°3 TUBI FLEX. SAE100 R2AT 1/2"gas TR16x2600AK CINGOLI

(s) -N°2 TUBI FLEX. SAE100 R2AT 5/16"gas TR10x1500AK FRENO

(t) -N°2 TUBI FLEX. SAE100 R2AT 5/16"gas TR10x900AK DRENAGGIO

(u) -N°1 TUBO FLEX. SAE100 R2AT 5/16"gas TR12x900AA SCARICO 220

(v) -N°1 TUBO FLEX. SAE100 R2AT 5/16"gas TR10x300AK SCARICO VALVOLA DOPPIA VELOCITA'

(w)-N°4 TUBI FLEX. SAE100 R2AT 1/4"gas TR10x2700AA STAB. N 1-2 – ANTIABRASIONE

(x) -N°4 TUBI FLEX. SAE100 R2AT 1/4"gas TR10x2000AA STAB. N 3-4 – ANTIABRASIONE

(y) -N°1 TUBO FLEX. SAE100 R2AT 1/6"gas TR16x2000AK DA 630 A DANFOSS

(z) -N°1 TUBO FLEX. SAE100 R2AT 5/16"gas TR12x600AK SFILO VALVOLA DI MASSIMA

(aa) -N°1 TUBO FLEX. SAE100 R2AT 5/16"gas TR12x900AK SOLL. A VALVOLA DI NON RITORNO

(bb) -N°1 TUBO FLEX. SAE100 R2AT 5/16"gas TR12x1500AK DANFOSS A PISTONE SOLL.

(cc) -N°1 TUBO FLEX. SAE100 R2AT 1/2"gas TR16x500AK DA VALVOLA RIPARATRICE A DANFOSS

(dd) -N°1 TUBI FLEX. SAE100 R2AT 5/16"gas TR12x1000AK DA VEI A PISTONE

(ee) -N°1 TUBO FLEX. SAE100 R2AT 1/2"gas TR16x700AK VEI A COLLETTORE

(ff) -N°1 TUBO FLEX. SAE100 R2AT 5/16"gas TR12x600AA VALVOLA RIPARATRICE A VEI

(gg) -N°4 TUBI FLEX. SAE100 R2AT 1/2"gas TR16x500AA SCARICO VEI TORRETTA

(hh) -N°1 TUBO FLEX. SAE100 R2AT 5/16"gas TR12x300AK SCARICO VALVOLA DI MASSIMA (ii) -N°1 TUBO FLEX. SAE100 R2AT 1/2"gas TR16x1000AK SCARICO DANFOSS TORRETTA

(jj) -N°2 TUBI FLEX. SAE100 R2AT 5/16"gas TR12x1000AK ROTAZIONE TORRETTA

(kk) –N°2 TUBI FLEX. SAE100 R2AT 5/16"gas TR12x2000AK DANFOSS JIB TORRETTA

(ll) -N°1 TUBO FLEX. SAE100 R2AT 5/16"gas TR12x2500AK SFILO

(mm) -N°1 TUBO FLEX. SAE100 R2AT 5/16"gas TR12x2900AK DANFOSS SFILO

(nn) -N°3 TUBI FLEX. SAE100 R2AT 5/16"gas TR10x1200AK JIB

(oo) -N°2 TUBI FLEX. SAE100 R2AT 5/16"gas TR10x1200AK PISTONE JIB

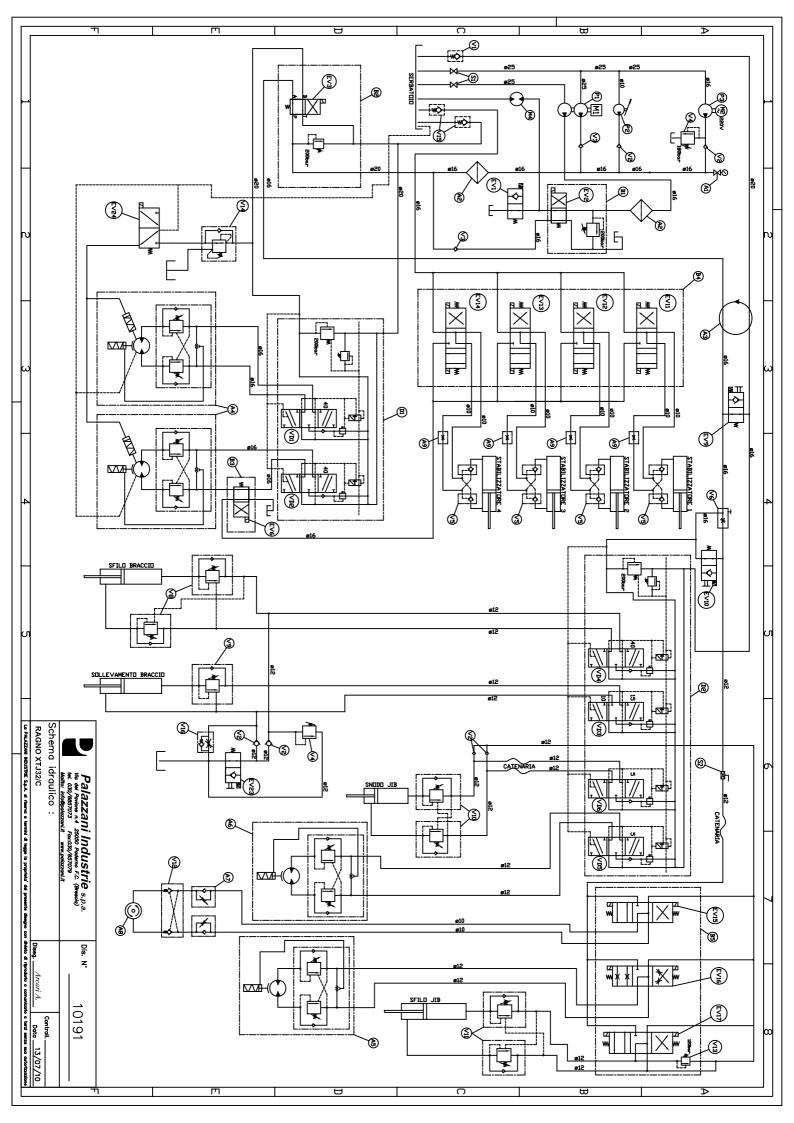
(pp) -N°1 TUBO FLEX. SAE100 R2AT 5/16"gas TR12x4800AA R7

(qq) -N°1 TUBO FLEX. SAE100 R2AT 5/16"gas TR10x4800AA R7

(rr) -N°1 TUBO FLEX. SAE100 R2AT 1/4"gas TR10x800AA

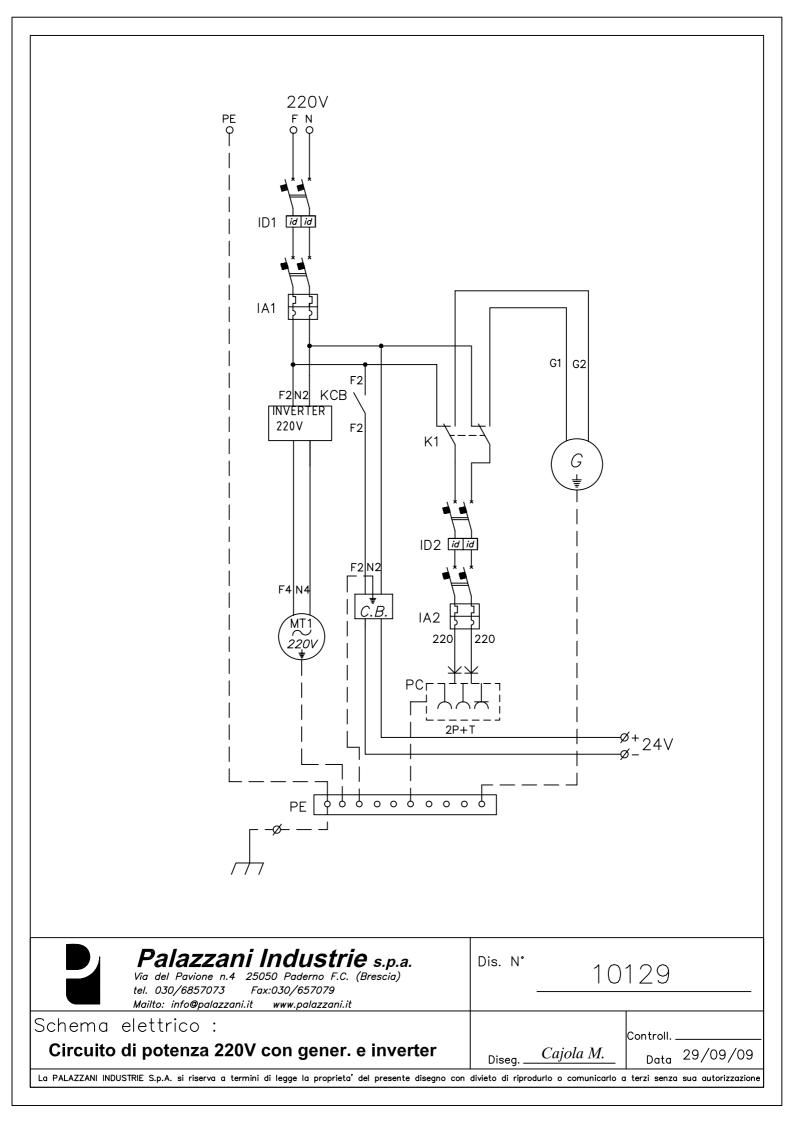
RAGNO XTJ 32	CON CINGOLI	DIS. 10191

A1 A2	1		
A2		MANOMETRO 0 - 250 bar ø 80 con rubinetto 1/4" gas	50120227
		FILTRO IN MANDATA 25 micron 40 lt/min. 1/2" gas	50120261
A3	1	COLLETTORE A 2 VIE da 1/2" gas	55280531
A4		MOTORE IDRAULICO TRASMITAL 704 C2K + valvola blocco + freno	Orig. Cing.
A5		MOTORE IDRAULICO MGLR 300 AS + freno xf30 ei 6b + valvola controllo	55280543
A6	1	MOTORID.MD211TS7,2+MLG400 VBO35MD + FRENO	55280148
A7		REGOLATORE DI FLUSSO DA 1/4" gas	50120146
A8		ATTUATORE ROTANTE ARM30/168/F cod.H.807/168F1A1F	55280548
A9		RACCORDO 337/F/006 FORO Ø 1	50110307
B1		BASE 3/4" gas (IDM 323 con sovrappressione incorporata)	50120252
B2		BASE 3/4" gas IDM 323 con sovrapressione incorporata	50120252
B3		BASE BA 302 1/2" gas	55280291
B4		PANNELLO A 4 PER DHU senza sovrappressione	55280313
B5		PANNELLO A 3 PER ELETTROVALVOLE	55280290
D1		DISTRIBUTORE PROPORZIONALE PVG 32/2 - 40 l/min.	55280354
D2		DISTRIBUTORE PROPORZIONALE PVG 32/4 (40 - 15 - 5 - 51/min.) Cod.157F3094	55280537
EV1		ELETTROVALVOLA VEI - A2 - 09 con massello 1/2" gas	55280360
EV10		ELETTROVALVOLA VEI - 8A- 2A- 06 - NA - D1 con massello 3/8" gas	55280363
EV11		ELETTROVALVOLA DHU 0713 WP 24V	55280289
EV12		ELETTROVALVOLA DHU 0713 WP 24V	55280289
EV12		ELETTROVALVOLA DHU 0713 WP 24V	55280289
EV14		ELETTROVALVOLA DHU 0713 WP 24V	55280289
EV15		ELETTROVALVOLA DHU 0713 WP 24V	55280289
EV15		ELETTROVALVOLA DHZO-A-073-L1/18 20	55280315
EV10		ELETTROVALVOLA DHU 0713 WP 24V	55280289
EV2		ELETTROVALVOLA DKU 1630 WP - 24V	55280282
EV23		VEIC S128A COD. OS150617190302 +S8H12.7 24VDC 17W	55280428
EV23		VALVOLA OS131051300900 + OD021601300C00	55280599
EV24 EV3		ELETTROVALVOLA DKU 1630 - WP - 24V	55280282
EV3		ELETTROVALVOLA DHU 0630 - WP - 24V	55280282
EV8		ELETTROVALVOLA DIO 0030 - WF - 24V ELETTROVALVOLA 1/4 gas Cod. 5012262 24V	
EV0 EV9		VEIC S128A COD. OS150617190302 +S8H12.7 24VDC 17W	55280599
EV9 M1		MOTORE TERMICO HATZ 2L 41 C insonorizzato 24V	55280428 55280303
M2	1		
			55280284
M4	1	MOTORE IDRAULICO PLM 20.6,3 SO - 82E2 - LEA	14170065
P1		POMPA DOPPIA PLP 20.14 / 20.14D / FS EL POMPA DI EMERGENZA EP25 - W - B - TXA	14170063
P2			55280013
P3		POMPA PLP 20.4 DO - 82E2 - LEA / EA N - EL	14170061
S1		SARACINESCA DA 3/4" gas	55030113
S2			50120225
V1		VALVOLA DI FONDO EUROPA 1" gas	50120325
V10		VALVOLA DI BLOCCO VBSO - SEC - 30 - 4,2 : 1 - 20 - D	50120166B
V11		VALVOLA DI BLOCCO A - VBSO - SE 30 FC1 38 - 35 A	50120166
V12		VALVOLA DI BLOCCO VSO DEL 14	50120202
V13		VALVOLA HMP - 012/210 22	55280568
V14		VALVOLA RIDUZIONE PRESSIONE	50120333
V15		VALVOLA DI FONDO EUROPA 1" gas	50120241
V16		VALVOLA REGOLATRICE DI FLUSSO VRF 1/4"	50120289
V2		VALVOLA UNIDIREZIONALE CD 3/8" gas	50120120
V4		VALVOLA SOVRAPRESSIONE VSC 30 N da 3/8" gas	50120204
V5		VALVOLA DI BLOCCO VSO-DE-FC2 055344000201000	50120310
V6		VALVOLA RIPARTITRICE VRFC3 -C da 1/2" gas	50120250
V7		VALVOLA SOVRAPPRESSIONE VSC 80N da 1/2" gas	50120213
V8		VALVOLA DI BLOCCO A - VBSO - SE 30 FC1 38 - 35 A	50120166
V9	1	VALVOLA DI BLOCCO A - VBSO - SE 30 - PL - 38 - 35	50120196



## CIRCUITO DI POTENZA 220V CON GENERATORE E INVERTER DIS. 10129

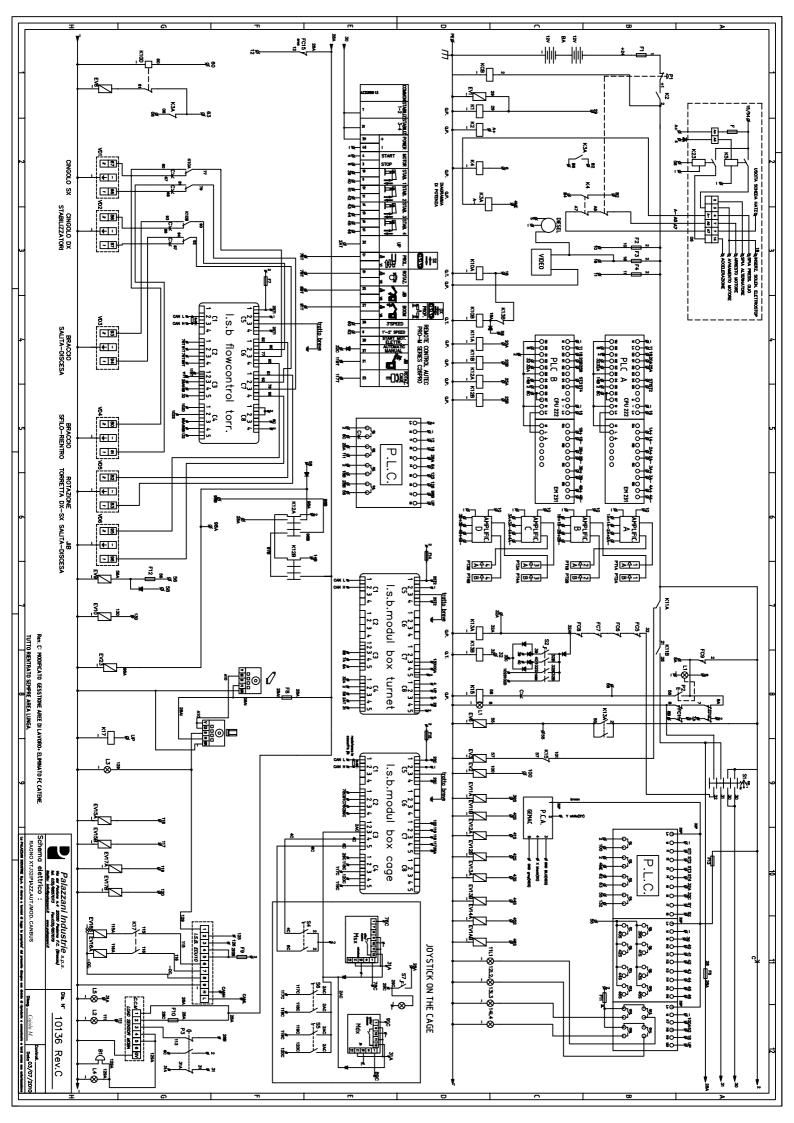
SIGLA	DESCRIZIONE	POSIZIONE
CB	CARICA BATTERIE 10A 24V	
KCB	RELE' PROTEZIONE CARICA BATTERIE	
G	GENERATORE	
IA1	INTERRUTTORE AUTOMATICO LINEA 220V – 16A	
IA2	INTERRUTTORE LINEA GENERATORE 6A	
ID1	INTERRUTTORE DIFFERENZIALE AUTOMATICO LINEA 220V – 25A – 0,03A	
ID2	INTERRUTTORE DIFFERENZIALE AUTOMATICO LINEA GENERATORE 25A –	
	0,03A	
K1	RELE' GENERATORE	
MT1	MOTORE ELETTRICO 220V 2,2Kw	
INVERT	INVERTER	
ER		
PC	PRESA SUL CESTO 220V 2P+T	
PE	BARRETTA DI RAME PER PROTEZIONE EQUIPOTENZIALE	



## RAGNO XTJ32 WITH TRACK ELECTRICAL DIAGRAM DRAW 10136 REV.C

SIGLA	DESCRIZIONE
BA	BATTERY 12V
С	INTERCOMM. SYSTEM I.S.B.
B1	BUZZER LOAD SENSOR
EV1	ELETTROVALVE GENERATOR
EV2	ELETTROVALVE 2 PUMP
EV3	ELETTROVALVE OIL GROUND – BOOM
EV6	ELETTROVALVE OIL OUTRIGGERS
EV8	ELETTROVALVE 3 SPEED
EV9	ELETTROVALVE OIL BOOM
EV10	ELETTROVALVE OIL CAGE
EV11A	ELETTROVALVE OUTRIGGERS N°1(HOISTING)
EV11B	ELETTROVALVE OUTRIGGERS N°1(LOWERING)
EV12A	ELETTROVALVE OUTRIGGERS N°2(HOISTING)
EV12B	ELETTROVALVE OUTRIGGERS N°2(LOWERING)
EV13A	ELETTROVALVE OUTRIGGERS N°3(HOISTING)
EV13B	ELETTROVALVE OUTRIGGERS N°3(LOWERING)
EV14A	ELETTROVALVE OUTRIGGERS N°4(HOISTING)
EV14B	ELETTROVALVE OUTRIGGERS N°4(LOWERING)
EV15A	ELETTROVALVE ROTATION CAGE RIGHT
EV15B	ELETTROVALVE ROTATION CAGE LEFT
EV16A	ELETTROVALVE LEVELLING CAGE
EV16B	ELETTROVALVE LEVELLING CAGE
EV17A	ELETTROVALVE EXTENSION JIB
EV17B	ELETTROVALVE RE-ENTRY JIB
EV23	ELETTROVALVE LIMITATOR OIL
F	FUSE HATZ BOARD 10A
F1	MAIN FUSE 8A
F2	POWER AMPLIFICATOR FUSE 2A
F3	FUSE OF POWER PLC A – PLC B 2A
F4	FUSE FOR OUTPUT PLC A – PLC B 1A
F6	FUSE FOR THE CAGE LINE 4A
F7	FUSE FOR THE FLOWCONTROL 2A
F8	FUSE FOR THE EASY TALK 4A
F9	FUSE FOR THE ISB LEVELLING CAGE 4A
F10	FUSE FOR THE MOBA 2A
F11	FUSE FOR THE OUTRIGGERS LUMP 2A
F12	FUSE FOR THE OIL BOOM 2A
F13	FUSE FOR THE PLC FOR THE AUTOMATIC LEVELLING 2A
F14	FUSE FOR THE MODULBOX ISB 2A
F15	FUSIBILE MODULBOX ON THE CAGE 2A
FC5	MICROSWITCH FOR THE OUTRIGGERS
FC6	MICROSWITCH FOR THE OUTRIGGERS
FC7	MICROSWITCH FOR THE OUTRIGGERS
FC8	MICROSWITCH FOR THE OUTRIGGERS
FC9	MICROSWITCH BOOM RE-ENTRY
FC10	MICROSWITCH LOWERING BOOM
FC11	MICROSWITCH CENTER BOOM
FC15	MICROSWITCH AREA WORKING
I.S.B.	ELETTRONIC LEVELLING SYSTEM ECU10
MOBA	LOAD SENSOR
KCB	RELAY TO CHARGE BATTERY
K1	RELAY GENERATOR
K2	MAIN RELAY
K3A	RELAY TO CHANGE ELECTRICAL MOTOR AND HATZ
K4	RELAY STOP MOTOR
K5	RELAY START MOTOR
K10A	RELAY CHANGE TRAVELLING
K10B	RELAY CHANGE TRAVELLING
K10D	RELAY 3SPEED
K11A	RELAY BOOM MOVEMENTS INTERLOCK
K11B	RELAY BOOM MOVMENTS INTERLOCK
K12A	RELAY LIMIT AREA PLC A

IZ 10D	
-	RELAY LIMIT AREA PLC B
K13A	RELAY CHANGE OUTRIGGERS
-	RELAY CHANGE OUTRIGGERS
-	RELAY EMERGENCY BOOM
	RELAY FOR THE LEVELLING ELECTROVALVE
_	RELAY ACCELERATOR
L1	GREEN LUMP
	LUMP FOR THE LIMIT AREA WORKING
	LUMP FOR THE ALARM TO LEVELLING CAGE
	LUMP FOR THE LOAD ALARM
L5	GREEN LUMP FOR THE CONTROL PANEL IN THE CAGE
	LUMP OUTRIGGER 1
	LUMP OUTRIGGER 2
	LUMP OUTRIGGER 3
	LUMP OUTRIGGER 4
	EMERGENCY STOP IN THE MAIN BOX
	PUSH BUTTON TO HOISTING THE BOOM (WITH GREEN LUMP)
P3	EMERGENCY STOP IN THE CAGE
	PROGRAMMABLE LOGIC CONTROLLER
PLC B	PROGRAMMABLE LOGIC CONTROLLER
PT1A	POTENTIOMETER GEFRAN
PT1B	POTENTIOMETER GEFRAN
PT2A	POTENTIOMETER GEFRAN
PT2B	POTENTIOMETER GEFRAN
PT3A	POTENTIOMETER GEFRAN
PT3B	POTENTIOMETER GEFRAN
PT4A	POTENTIOMETER GEFRAN
	POTENTIOMETER GEFRAN
	SWITCH OUTRIGGER/TRASLATION/CAGE
	SWITCH TO AUTOMATIC LEVELING
	SWITCH START/STOP ON THE CAGE
S5	SWITCH EXTENSION/RE-ENTRY JIB ON THE CAGE
	SWITCH ROTATION CAGE ON THE CAGE
<b>S</b> 7	SWITCH GENERATOR ON THE CAGE
MA1	JOYSTICH ROTATION/EXTENSION
MA2	JOYSTICH BOOM/JIB
	DANFOSS – TRACK LEFT
VD2	DANFOSS –TRACK RIGHT– OUTRIGGERS
VD3	DANFOSS – BOOM
VD4	DANFOSS – EXTENSION/RE-ENTRY BOOM
VD5	DANFOSS – ROTATION
VD6	DANFOSS –JIB
P.L.C.	P.L.C. AUTOMATIC LEVELLING
P.A.C.	AUTOMATIC LEVELLING SENSOR
ISB	MODULO FLOWCONTROL CANBUS
FLOW	
ISB TOR	MODULO CANBUS
ISB	MODULO TASTIERA CANBUS
TAST.	



	KIT ADESIVI XTJ32 FILO 14070558	
CODICE	DESCRIZIONE	Qta
14070077	ADESIVO GANCIO DI SOLLEVAMENTO	4
14070078	ADESIVO RIFORNIMENTO GASOLIO	1
14070070		
14070079	ADESIVO RIFORNIMENTO OLIO IDRAULICO	1
14070080	ADESIVO DIVIETO LAVORO CON STAB. SFILATI	4
14070082	ADESIVO TENSIONE 220VOLT	1
14070084	ADESIVO PERICOLO SCHIACCIAMENTO MANI	1
14070085	TARGA ALLUM. IDENTIFIC. PALIFT ITALIA	1
		-
14070086	TARGA ALLUM.IDENTIFICAZIONE NAVICELLA	1













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Palazzani In	dustrie spa
Туре	
Serial number	
Max. allowable manual force	N
Max. allowable wind speed Force 6 Beaufort	scale 14.07.0006

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14070087	TARGHETTA ALLUM. IDENTIFIC. STABILIZ.	4	
14070087	TARGHETTA ALLOW. IDENTIFIC. STADILIZ.	4	
14070088	ADESIVO USO ATTREZZATURA	1	
14070089	ADESIVO ISTRUZ.OPERATIVE	1	
14070090	ADESIVO MANUTENZIONE ORDINARIA	1	
14070095	ADESIVO PORTATA MAX. CESTO	2	
14070178	ADESIVO LOGO PALAZZANI h10cm	2	
14070556	ADESIVO CARICO SUGLI STABILIZZ. 35 KN	4	
14070244	ADESIVO PALAZZANI.IT TRICOLORE BASE 130	1	
14070286	ADESIVO POTENZA SONORA LWAd/B CE 2000/14	1	



	[	r –	l
14070303	ADESIVO RECUPERO STABILIZZATORI	1	OUTRIGGERS RECOVERY IN EMERGENCY Insert manually Ev ground-boom and Ev Outriggers Act on the lever (right side) of the electrodistributor on the chassis. Push the rubber caps of the outriggers electrovalves. Orive the hand pump.
			FONDO VERDE SCRITTE BIANCHE TO USE THE HAND PUMP, FIRSTLY CLOSE THE LITTLE WHEEL ON
14070304	ADESIVO USO DELLA POMPA A MANO	1	THE ELECTROVALVE GROUP
			OFFERENTIAL MAGNETO DIFFERENTIAL MAGNETO Relay Thermic Relay Thermic Contactor Breaker Out let Electric Motor
14070305	ADESIVO APPARECC. ELETTRICA RAGNI	1	
14070352	ADESIVO ACCESSO AI DISTRIBUTORI (PALIFT)	1	COMPARTMENT OF ACCESS AND NANODIVIC.     ADVANCESS AND NANODIVIC.     COMPACT ACCESS AND NANODIVIC.
14070353	ADESIVO TRASLAZIONE	1	DRIVE THE PLATFORM FROM A REMOTE, SAFE POSITION AND HOLD THE CONTROL PANEL
14070555	ADESIVO AREA DI LAVORO RAGNI XTJ32	1	
14070393	ADESIVO PER RAGNI	1	DISCONNECT THE ELECTRIC PLUG AND SWITCH-OFF THE GENERATOR BEFORE ANY INTERVENTION IN THIS AREA
14070413	SERIE ADESIVI "1 2 3 4" STAB. PIATTAFORME	2	4
14070414	ADESIVO OBBLIGO DI INDOSSARE L'ELMETTO	1	ALWAYS WEAR HARD HAT

14070415	ADESIVO OBBLIGO DI INDOSSARE LE CINTURE DI SICUREZ	1
14070416	OBBLIGO DI UTILIZZARE UTENSILI CLASSE 2	1
14070418	ADESIVO PRESP. PALAZZANI TSJ CON OMBRA	2
14070420	ADESIVO PERICOLO ATTREZ. NON ISOLATA	1
14070421	ADESIVO POMPA MANUALE	1
14070422	ADESIVO PRESA 220V 35X20mm	1
14070429	ADESIVO PROIBITO SOSTARE RAGGIO AZIONE MACCHINA	1
14070430	ADESIVO GANCIO SOLLEVAMENTO RAGNO	4
14070431	ADESIVO SALITA STABILIZZATORI	1



















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14070432	TARGA ADESIVA ALLUM. 'ARRESTO D'EMERGENZA'	1	ENERGENCL
14070436	ADESIVO VERDE MANOVRE EMERGENZA ELETTROVAL.	1	中 二 二 二 二 二 二 二 二 二 二 二 二 二
	ADESIVO BLU "STACCABATTERIE"		BATTERY DISCONNECTOR
		1	UPPER MOVEMENTS EXCLUSION
14070446	ADESIVO ESCLUSIONE MOVIMENTI SUPERIORI	1	RELATS, AS WELL AS DIODES, ARE DIFFERENT ONE ANOTHER. THES WIDON SOSTITUTION CAN BERIOUSLY ENDANGER THE MACHINE SAFETY. THIS INTERVENTION IS ALLOWED ONLY BY GUALIFIED PERSONNEL.
14070457	ADESIVO GIALLO PERICOLO SOSTITUZIONE RELE',	1	PUSH-BUTTON FOR MANUAL CAGE LEVELLING
14070458	ADESIVO: PULSANTE PER LIVELLAMENTO CESTA	1	A to be a set of the s
14070557	RECUPERO CESTO (VERDE)	1	(
14070479	ADESIVO DA APPLICARE SU LEVA PER MOVIMENTO CINGOLI	2	
14070480	ADESIVO DA APPL. SU LEVA (SELEZIONA CESTO O STAB)	1	

14070485	ADESIVO GIALLO: FAR CONTROLLARE L'IMPIANTO SE	1
4.4070.400		
14070488	ADESIVO VERDE ESCLUSIONE PILOTAGGI	2
14070437	ADESIVO SFILO - RIENTRO JIB	1
14070552	ADESIVI TARGHETTE EV	1

